

MAHENDRA ENGINEERING COLLEGE

Autonomous | Accredited by NAAC with 'A++' Grade (Cycle-2)
Accredited by NBA Tier-I (WA) UG: CSE, ECE, EEE
Mahendhirapuri, Mallasamudram (W), Namakkal (Dt) - 637 503, Tamil Nadu



04288-288 500 / 521 / 522 | www.mahendra.info



DEPARTMENT OF MECHANICAL ENGINEERING

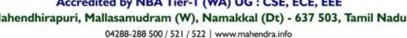
B.E. Mechanical Engineering

Choice Based Credit System (CBCS)

R 2024 Curriculum and Syllabi



Accredited by NBA Tier-I (WA) UG : CSE, ECE, EEE





Institute - Vision, Mission

Vision

To be an internationally recognized institute for engineering education and research with ethical values

Mission

- > To ensure the effective use of resources to mould the students as professionals and entrepreneurs
- ➤ To enhance the industry institute interaction for innovative technology practice
- > To encourage the faculty members and students for advanced research
- > To inculcate ethical values among the faculty members and students.

Department - Vision, Mission

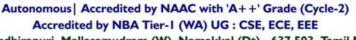
Vision

• To enable Mechanical Engineering Graduates excel in engineering education, research and innovation with ethical values as global practitioners.

Mission

- To impart quality education, enhance student's skills and make them to compete globally
- To provide State-of-the-Art technologies and enhance students problem solving skills in Mechanical Engineering
- To prepare graduates to pursue lifelong learning, intellectually with ethical values in Mechanical Engineering as professionals and entrepreneurs
- To expand students' knowledge in the Mechanical Engineering domain to conduct research and innovate for a sustainable development.





ahendhirapuri, Mallasamudram (W), Namakkal (Dt) - 637 503, Tamil Nadu



Department of Mechanical Engineering

Program Educational Objectives (PEOs)

The graduates of Mechanical Engineering will be able to

PEO1: Apply the mathematical and scientific concepts necessary to formulate, solve and analyze engineering problems.

PEO2: Conceptualize and synthesize data, carry out product design and development.

PEO3: Work in teams on multidisciplinary projects.

PEO4: Observe professional ethics and develop successful careers globally

Program Outcomes (POs)

Engineering Graduates will be able to:

- **1. Engineering knowledge:** Apply the knowledge of mathematics, science, engineering fundamentals, and an engineering specialization to the solution of complex engineering problems.
- **2. Problem analysis:** Identify, formulate, review research literature, and analyze complex engineering problems reaching substantiated conclusions using first principles of mathematics, natural sciences, and engineering sciences.
- **3. Design/development of solutions:** Design solutions for complex engineering problems and design system components or processes that meet the specified needs with appropriate consideration for the public health and safety, and the cultural, societal, and environmental considerations.
- **4. Conduct investigations of complex problems**: Use research-based knowledge and research methods including design of experiments, analysis and interpretation of data, and synthesis of the information to provide valid conclusions.
- **5. Modern tool usage:** Create, select, and apply appropriate techniques, resources, and modern engineering and IT tools including prediction and modeling to complex engineering activities with an understanding of the limitations.
- **6.** The engineer and society: Apply reasoning informed by the contextual knowledge to assess societal, health, safety, legal and cultural issues and the consequent responsibilities relevant to the professional engineering practice.

- **7. Environment and sustainability**: Understand the impact of the professional engineering solutions in societal and environmental contexts, and demonstrate the knowledge of, and need for sustainable development.
- **8. Ethics:** Apply ethical principles and commit to professional ethics and responsibilities and norms of the engineering practice.
- **9. Individual and team work:** Function effectively as an individual, and as a member or leader in diverse teams, and in multidisciplinary settings.
- **10. Communication:** Communicate effectively on complex engineering activities with the engineering community and with society at large, such as, being able to comprehend and write effective reports and design documentation, make effective presentations, and give and receive clear instructions.
- **11. Project management and finance:** Demonstrate knowledge and understanding of the engineering and management principles and apply these to one's own work, as a member and leader in a team, to manage projects and in multidisciplinary environments.
- **12. Life-long learning:** Recognize the need for, and have the preparation and ability to engage in independent and life-long learning in the broadest context of technological change.

Programme Specific Outcomes (PSOs)

PSO1: Identify, understand, apply and solve problems in Mechanical Engineering Design.

PSO2: Identify, understand, apply and find solutions for problems in Manufacturing Engineering.

PSO3: Identify, understand, apply and provide solutions for problems in Thermofluid Industrial Applications.





		CBCS - Regulation 2024									
		I Semester									
Sl. No.	Course code	CourseTitle	L	T	P	C	Cate- gory				
THE	ORY										
1	24MA12101	Engineering Mathematics-I	3	1	0	4	BS				
2	24HS11001	Communicative English	nmunicative English 3 0								
3	24CY12001	Engineering Chemistry	3	0	0	3	BS				
4	24GE13101	Engineering Drawing	2	0	2	3	ES				
5	24HS11002	Heritage of Tamils	1	0	0	1	SH				
6	24SH61101	Induction Program	-	-	-	-	MC				
PRA	CTICAL										
7	24HS21001	Personality Development Practice	0	0	2	1	SH				
8	24CY22001	Chemistry Laboratory	0	0	3	1.5	BS				
9	24GE23101	Computer Aided Drafting and Modeling Laboratory	0	0	3	1.5	ES				
		TOTAL	12	1	10	18					





	CBCS - Regulation 2024											
		II Semester										
Sl. No.	Course code	CourseTitle	L	T	P	C	Cate- gory					
THE	ORY		ı		ı	ı						
1	24MA12201	Engineering Mathematics-II	3	1	0	4	BS					
2	24PY12001	Engineering Physics	ngineering Physics 3 0 0 3									
3	24CS13001	Problem Solving Techniques using C	3	0	0	3	ES					
4	24EE13001	Basics of Electrical and Electronics Engineering	3	0	0	3	ES					
5	24GE13201	Engineering Mechanics	3	0	0	3	ES					
6	24HS11003	Tamils and Technology	1	0	0	1	SH					
PRA	CTICAL											
7	24PY22001	Engineering Physics Laboratory	0	0	3	1.5	BS					
8	24CS23001	Problem Solving Techniques Laboratory	0	0	3	1.5	ES					
9	24GE23001	Engineering Practices Laboratory	0	0	3	1.5	ES					
		TOTAL	16	1	9	21.5						





	grives										
		CBCS - Regulation 2024									
III Semester											
Sl. No.	Course code	CourseTitle	L	T	P	C	Cate- gory				
THE	ORY						I				
1	24MA12301	Transforms and Partial Differential Equations	3	1	0	4	BS				
2	24ME14301	0	3	PC							
3	24ME14302	02 Manufacturing Processes 3 0 0					PC				
4	24ME14303	Strength of Materials	3	0	0	3	PC				
5	24ME14304	Engineering Thermodynamics	3	0	0	3	PC				
6		Open Elective-I	3	0	0	3	OE				
7	24CY11001	Environmental Science And Sustainability	2	0	0	0	MC				
PRA	CTICAL										
8	24ME24301	Strength of Materials Laboratory	0	0	3	1.5	PC				
9	24ME24302	Computer Aided Machine Drawing Laboratory	1	0	2	2.0	PC				
		TOTAL	21	1	5	22.5					





	CBCS - Regulation 2024										
Sl. No.	Course code	CourseTitle	L	T	P	C	Cate- gory				
THE	ORY										
1	24MA12405	Statistics And Numerical Methods	3	1	0	4	BS				
2	24ME14401	Fluid Mechanics and Machinery	3	0	0	3	PC				
3	24ME14402	Metrology and Measurements	3	0	0	3	PC				
4		Professional Elective-I*	3	0	0	3	PE				
5		Professional Elective-II	3	0	0	3	PE				
6		Open Elective-II	3	0	0	3	OE				
7	24HS11006	Universal Human Values	3	0	0	3	SH				
PRA	CTICAL										
7	24HS21002	Professional Communication Skills	0	1	2	2.0	SH				
8	24ME24401	Fluid Mechanics and Machinery Laboratory	0	0	3	1.5	PC				
9	24ME24402	Metrology and Measurements Laboratory	0	0	3	1.5	PC				
		TOTAL	21	2	8	27					





		V Semester					
Sl. No.	Course code	CourseTitle	L	T	P	C	Cate- gory
THE	ORY						I
1	24ME14501	0	3	PC			
2	24ME14502	0	3	PC			
3	24ME14503	3	0	0	3	PC	
4		Professional Elective- III**	0	0	3	PE	
5		Professional Elective-IV	3	0	0	3	PE
6		Open Elective-III	3	0	0	3	OE
7	24HS11004	Constitution of India	2	0	0	0	MC
PRA	CTICAL						
8	24HS21003	Interview Skills and Soft Skills	0	0	4	2.0	SH
9	24ME24501	Thermal Engineering Laboratory	0	0	3	1.5	PC
10	24ME24502	Manufacturing Laboratory	0	0	3	1.5	PC
11	24ME25501	Internship	0	0	2	1.0	PC
		TOTAL	20	0	12	24	





		CBCS - Regulation 2024										
	VI Semester											
Sl. No.	Course code	crse code CourseTitle L T		P	C	Cate- gory						
THE	ORY						I					
1	24ME14601	Theory of Machines	3	0	0	3	PC					
2	24ME14602	Heat and Mass Transfer	3	0	0	3	PC					
3	24ME14603	Design of Transmission Systems	3	0	0	3	PC					
4	24ME16601	Principles of Management	3	0	0	3	EEC					
5		Professional Elective-V	3	0	0	3	PE					
6		Professional Elective-VI	3	0	0	3	PE					
PRA	CTICAL											
7	24ME24601	Theory of Machines Laboratory	0	0	3	1.5	PC					
8	24ME24602	Heat and Mass Transfer Laboratory	0	0	3	1.5	PC					
9	24ME36601	Design and Fabrication Project	0	0	4	2.0	EEC					
		TOTAL	18	0	10	23						





		CBCS - Regulation 2024									
	VII Semester										
Sl. No.	Course code	CourseTitle	L	T	P	C	Cate- gory				
THE	ORY				1		I				
1	24ME14701	Industrial Automation	3	0	0	3	PC				
2	24ME14702	Finite Element Analysis	0	3	PC						
3	24ME14703	Operations Research	3	0	0	3	PC				
4		Professional Elective-VII	3	0	0	3	PE				
5		Professional Elective-VIII	3	0	0	3	PE				
6		Professional Elective-IX	3	0	0	3	PE				
PRA	CTICAL										
7	24ME24701	Industrial Automation Laboratory	0	0	3	1.5	PC				
8	24ME24702	Analysis and Simulation Laboratory	0	0	3	1.5	PC				
9	24ME36701	Project Work(Phase-I)	0	0	6	3.0	EEC				
		TOTAL	18	0	12	24					





DEPARTMENT OF MECHANICAL ENGINEERING

		CBCS - Regulation 2024											
		VIII Semester											
Sl. No.	Course code	CourseTitle	L	T	P	C	Cate- gory						
PRA	CTICAL												
1	24ME36801	Project Work(Phase-II)	0	0	12	6	EEC						
		TOTAL	0	0	12	6							

Total Credit: 166

Subject Category	Credits p	er semes	er semester			Credit total	% of Credits (Actual Credits / Total Credits)			
	I	II	III	IV	V	VI	VII	VIII		
SH	5	1	-	5	2	-	-	-	13.0	7.8
BS	8.5	8.5	4	4	-	-	-	-	25.0	15.1
ES	4.5	12	-	-	-	-	-	-	16.5	10.0
PC	-	-	15.5	9	13	12	12		61.5	37.0
PE	-	-	-	6	6	6	9	-	27.0	16.3
OE	-	-	3	3	3	-	-	-	9.0	5.4
EEC	-	-	-	-	-	5	3	6	14.0	8.4
MC	0	-	0	-	0	-	-	-	0	0.0
Total Credits	18	21.5	22.5	27	24	23	24	6	166	100



MAHENDRA ENGINEERING COLLEGE (Autonomous) DEPARTMENT OF MECHANICAL ENGINEERING



Professional Elective Courses: Verticals

Thermal Engineering	Design Engineering	Manufacturing and Materials Engineering	Industrial System and Design	Mobility Systems	Robotics and Automation
24ME15101	24ME15201 Design	24ME15301 Composite	24ME15401	24ME15501Automobile	24ME15601
Renewable Energy	of Jigs, Fixtures and Press Tools	Materials, Processing and Application	Maintenance Engineering	Engineering	Industrial Robotics
24ME15102 Gas	24ME15202 Process	24ME15302 Computer	24ME15402 Digital	24ME15502 Conventional	24ME15602
Dynamics and Jet	Planning and Cost	Intergraded	Manufacturing and IoT	and Futuristic Vehicle	Hydraulics and
Propulsion	Estimation	Manufacturing		Technology	Pneumatics System
24ME15103 Power	24ME15203	24ME15303	24ME15403	24ME15503 Renewable	24ME15603 Sensors
Plant Engineering	Geometric	Engineering Economics	Manufacturing	Powered Off Highway	and Instrumentation
	Dimension, Tolerance	and Cost Analysis	Information Systems	Vehicles and Emission	
	and Modeling*			Control Technology	
24ME15104	24ME15204Value	24ME15304	24ME15404 Industrial	24ME15504 Vehicle Health	24ME15604
Refrigeration and Air	Engineering	Smart Materials and	Safety	Monitoring, Maintenance	Embedded Systems
Conditioning		Applications		and Safety	and Programming
24ME15105 Heating	24ME15205 Additive	24ME15305 Non-	24ME15405 Plant	24ME15505 CAE and CFD	24ME15605 Smart
Ventilation and Air	Manufacturing and	Destructive Testing	Layout and Material	Approach in Future	Mobility and
Conditioning	Wireframe		Handling	Mobility	Intelligent Vehicles
	Modeling**				
24ME15106	24ME15206	24ME15306 Supply	24ME15406 Industrial	24ME15506 Hybrid and	24ME15606
Computational Fluid	Computational Solid	Chain Management	Engineering and	Electric Vehicle	Electrical Drives and
Dynamics	Mechanics		Management	Technology	Actuators

Course code	Course Name	H	ours/w	eek	Credit	Maximum marks
	To a local de Maria II	L	T	P	С	
24MA12101	Engineering Mathematics-I (Common to all Branches)	3	1	0	4	100
	To enable the students to:					
	• Learn the types of matrices and linear a	algebra ii	n a con	nprehen	sive manner	•
	• Familiarize with functions of several v	ariables	and its	applica	tions toengir	neering.
Objective(s)	 Define the geometric aspects of curvate of differential calculus. 	ure, radiı	ıs of cı	ırvature	e, evolutes ar	nd envelopesas application
	Explain various techniques of integrati					
	Learn double and triple integrals and g	ive their	represe	entation	as area and	
UNIT-I	Matrices					9+3
	ypes - Rank of matrix -Solving system of					
	the matrix - Cayley-Hamilton Theorem, Dis Reduce the quadratic form to canonical form.	agonaliza	ation o	t real	and symmet	ric matrices by Orthogon
UNIT-II	Differential Calculus of Several Variable	P C				9+3
	f implicit functions – Partial derivatives – To		votivo	Enlar	's theorem	
Taylor's series f	or functions of two variables - Maxima and					
undetermined mu	ıltipliers.					
UNIT-III	Applications of Differential Calculus					9+3
	tesian co-ordinates— Centre and radius of curvenals and their properties.	ature – C	Circle o	f curvat	ture – Evolu	tes – Envelopes – Evolute
UNIT-IV	Integral Calculus					9+3
Definite and Ind	efinite integrals - Substitution rule - Techniqu	es of Inte	egratio	n: Integ	gration by pa	rts, Trigonometric integral
•	ibstitutions, Integration of rational functions b	y partial	fractio	n, Integ	gration of irr	ational functions - Improp
	cations to Engineering problems.					0.2
UNIT-V	Multiple Integrals					9+3
	in Cartesian co-ordinates – Change of order inates – Volume as triple integral – Change					
problems.	mates – volume as triple integral – Change	or varia	DIES III	double	e integrals.	Applications to Engineern
<u> </u>				Total 1	hours	60
	At the end of the course the students will	ha abla t	0.	Total	liours	<u> </u>
				aatara (and invorce	of a given matrix and
	diagonalize symmetric matrix by ortho	gonal tra	nsforn	nations,	solve system	
Outcome(s)	Determine maxima and minima of fund					
	Apply the concepts of differential calculate	_	-	_		
	Apply different methods of integration		<u> </u>	•	oblems.	
TEVT DOOL	Compute the area and volume by using	multiple	ıntegra	us.		
$\frac{\textbf{TEXT BOOK}:}{1} B.S. G_1$	ewal, Higher Engineering Mathematics, Khani	na Dublia	here 2	017		
	ewar, Higher Engineering Mathematics, Kham Stewart, Calculus with Early Transcendental fu					
REFERENCES			Jongag	c, 2013	•	
	 Kreyszig, Advanced Engineering Mathematics, 	John W	iley &	Sons, 2	016.	
_	ulia I ania C. Damett. Advanced Engineering N	1 athama	tion M	oC morry	ЦП 2012	
2 Ray W	ylie, Louis C. Barrett, Advanced Engineering N	viamema	ucs, ivi	curaw-	пш, 2015.	

Ben Orlin, Change is the Only Constant: The Wisdom of Calculus in a Madcap World, Pearson 2018.

3

PO CO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	2	2	2	-	-	-	-	-	-	2	2	2	1
CO2	3	3	2	2	2	-	-	-	-	-	-	2	2	2	1
CO3	3	3	2	2	2	-	-	-	-	-	-	2	2	2	2
CO4	3	3	2	2	2	-	-	-	-	-	-	2	2	2	2
CO5	3	3	2	2	2	-	-	-	-	-	-	2	2	2	2

	Course Name	H	ours/w	eek	Credit	Maximum marks
	Communicative English	L	T	P	С	
24HS11001	(Common to all B.E/B.Tech Degree Programmes)	3	0	0	3	100
Objective(s)	 To help learners to improve their knowle To enable them to use vocabulary appro To support learners to acquire listening a To facilitate them to develop their readin To equip them with writing skills needed 	priately and spea ng skills	in diffe king sl by fan	erent aca cills niliarizin	ng different	types of reading strategies
UNIT-I					•	9
Speaking — Introdi Reading — Skimm Writing - Leave/0	ng to Short Conversations (Formal and Information Oneself and Others ing and Scanning-Reading Comprehension Part Don Duty application, Bonafide Certificate-requabulary – Parts of Speech, Articles, Prefixes	assages uisition,	Check			hoice Questions
UNIT-II	abulary — raits or Speech, Articles, Fichixes	and Sun	IIACS			9
Speaking —Word I Reading — Short si Writing - Recomm	•					e Editor
UNIT-III	Junary – Semence Famern, Tenses, British I	erms an	u Ame	iicaii E	quivaients	9
Writing - Letter V Placing Order	eading and Fill up the Gaps Vriting – Permission Letter (In-Plant Trainin	g/Indust	rial Vi	sit). Bu	siness letters	
	cabulary - Modal Verbs, Voice- Active	_				
	cabulary – Modal Verbs, Voice- Active	_				
Expressions UNIT-IV Listening - Listening Speaking - Taking Reading - Reading Writing - Poster M	ng to Audio Lectures g part in Casual Conversation	Voice,	Passiv	re Voic	e and Impe	ersonal Passive, Numerica 9
Expressions UNIT-IV Listening - Listening Speaking - Taking Reading - Reading Writing - Poster M	Ing to Audio Lectures g part in Casual Conversation g Advertisements Making, and Job Application	Voice,	Passiv	re Voic	e and Impe	ersonal Passive, Numeric
Expressions UNIT-IV Listening - Listening Reading - Reading Writing - Poster M Grammar & Voca UNIT-V Listening - Listen Speaking - Descri Reading - Transco Writing - Review	Ing to Audio Lectures g part in Casual Conversation g Advertisements Making, and Job Application abulary – Cause and Effect Expressions, Que ing to Academic lectures bing Objects oding (Conversion of Flow Chart, Bar chart, I writing (Films & Books), Essay Writing	Voice,	Passiv gs, Ger	unds an	e and Impe	Passive, Numerical 9 , One word substitution 9
Expressions UNIT-IV Listening - Listening Reading - Reading Writing - Poster M Grammar & Voca UNIT-V Listening - Listen Speaking - Descri Reading - Transco Writing - Review	Ing to Audio Lectures g part in Casual Conversation g Advertisements Making, and Job Application abulary – Cause and Effect Expressions, Que ing to Academic lectures bing Objects oding (Conversion of Flow Chart, Bar chart, I	Voice,	Passiv gs, Ger	unds an	e and Impe	9 One word substitution 9 nal Compounds

TEXT	BOOK:
1	Murphy, Raymond, English Grammar in Use, Fifth Edition. Cambridge University Press, New Delhi, 2019
2	N.P.Sudharshana and C.Savitha, English For Technical Communication, Cambridge University Press, New Delhi,
	2016
REFEI	RENCES:
1	Lewis Norman, Word Power Made Easy, Goyal Publishers: New Delhi. 2020.
2	Ashraf Rizvi. Effective Technical Communication, Tata McGraw Hill, 2017.
3	Jack C. Richards with Jonathan Hull and Susan Proctor, <i>Interchange</i> . 4 th Edition, Cambridge University Press, New
	Delhi, 2016
EXTE	NSIVE READING:
1	Khera, Shiv. You can Win. Macmillan, Delhi. 2014
WEBS	SITES:
1	http://www.englishclub.com
2	http://www.talkenglish.com
3	https:// www.ted.com/talks
4	https://nptel.ac.in/

PO CO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2	-	_	2	_	-	-	2	3	1	2	-	_	-
CO2	2	2	-	-	2	-	-	-	2	3	1	2	-	-	-
CO3	2	2	-	-	2	-	-	-	2	3	1	2	-	-	-
CO4	2	1	-	-	3	-	-	-	2	3	1	3	-	-	-
CO5	2	2	-	-	2	-	-	-	3	3	2	3	-	-	-

Course code	Course Name	Н	ours/w	eek	Credit	Maximum marks
24CY12001	Engineering Chemistry	L	T	P	С	100
	To make the students familiar with: • The treatment of water used for domes			al purpo	ose.	
Objective(s)	 Various types of polymers in our day to The basic principle and preparation me The Construction and applications of d The preparation, properties and combu 	thods of	of Nano	of batter		
UNIT-I	Water Technology					9
Types of water - A treatment – disinfle efficiency of using osmosis - Internal	Alkalinity, types and determination - Hardness ection methods (Chlorination, ozonation, UV g hard water in boilers – external conditioning conditioning (phosphate, calgon and carbonad BIS guidelines for drinking water.	treatm g – dem	nent) – nineraliz	Boiler f zation pi	eed water – rec rocess, Electro	quirements – Decreased lialysis process, reverse
UNIT-II	Polymer Chemistry					9
of polymerization	ssification of polymers – Natural and synthetic - Types and mechanism of polymerization: A prices & applications of selected commodity and Epoxy resin). Nanochemistry	Addition	ı (Free	Radical); condensation	and copolymerization -
	<u> </u>					
mechanical and manotube and nan	on between molecules, nanoparticles and but agnetic) - Types of nanomaterials: Definition towire - Synthesis of nanomaterials: laser at and MWCNT- Applications (Medicine, Agric	, prope ablation	rties an ı, Sol g	d uses ogel, Syn	of –nanoparticles thesis of Carbo	s, nanocluster, nanorod,
UNIT-IV	Energy Storage Device			,		9
Lithium ion batter	- Primary battery - dry cell - Secondary baties - Battery used in EV application - Nuclear generation (block diagram only) - Fuel cell	r energ	y – Fiss	sion and	Fusion reaction	
UNIT-V	Fuels and Combustion			•		9
metallurgical coke higher and lower	(Otto Hoffmann method) - Petroleum - manu calorific values- theoretical calculation of cagas analysis (ORSAT Method).	facture	of synt	hetic pe	trol (Bergius pro	ocess) - calorific value -
•					Total hours	45
	At the end of the course the student will be	able to				
	• Explain the various water quality parapplications.					domestic and industria
Outcome(s)	 Classify the reaction mechanism, synthes Develop the essential concepts of nanosc for Engineering. 	ience a	nd nanc	otechnolo	ogy in designing	g the nanomaterial
	Compare the working principles of batterIllustrate the suitable fuels for engineerin		_	_		
TEXT BOOK:						
	and Monica Jain, "Engineering Chemistry", I					
2021.	P., Ravikrishnan A., "Engineering Chemistry"					
	, Umare S.S, "Engineering Chemistry", S. Cha S.M., "Introduction to Nanoscience" Oxford U				New Delhi 2019	
4 Lindsay						

REFER	RENCES:
1	Dr.C.K.Charles and Dr.G.Ramachandran, "Applied Chemistry", CARS Publishers, Chennai, 2015
2	Sivasankar B., "Engineering Chemistry", Tata McGraw-Hill Publishing Company, Ltd., New Delhi, 2012.
3	Linden's "Handbook of Batteries", Thomas B. Reddy, Fourth Edition McGraw-Hill, New York, 2011.
4	Shikha Agarwal,"Engineering Chemistry-Fundamental and Application",Cambridge University press,Delhi,Second Edition,2019.

PO CO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	-	-	1	-	-	1	-	-	-	-	1	-	-	-
CO2	2	-	-	1	-	-	1	-	-	-	-	1	-	-	-
CO3	3	-	-	1	-	-	-	-	-	-	-	1	-	-	-
CO4	3	-	-	-	-	-	1	-	-	-	-	1	-	-	-
CO5	3	1	1	-	-	-	1	-	-	-	-	1	-	-	-

code	Course Name	Н	ours/w	eek	Credit	Maximum marks
24GE13101	Engineering Drawing	L	T	P	C	100
240113101	(Common to Non circuit Branches)	2	0	2	3	
Objective(s)	 To impart knowledge on the import engineering and technology. To train students in basic geometr engineering applications. To develop the ability to visualize and To enable the students to understand developments. To familiarize students with the covisualization. 	ical cor draw or l and dr	nstructi thogra raw pr	ons, er	ngineering ojections of solids	curves, and scales used in points, lines, and planes., sectioned solids, and their pective projections for 3D
UNIT-I	Plane Curves and Free Hand Sketching					9
engineering practic cycloid –construction of D Visualization conclusion of views-	ng of drawing sheets – Lettering and dimerices: Conics –Construction of ellipse, parabotion of involutes of square and circle – Dragonal and Vernier scales. Cepts and Free Hand sketching: Visualization Free hand sketching of multiple views from picture.	ola and awing on principotential victorial vic	hypert of tang ples –I	oola by gents an Represe	eccentricited normal to the normal of a second seco	y method – Construction of the above curves, Scales: Three Dimensional objects –
UNIT-II	Projection of Points, Lines and Plane Sur	faces				9
(only First angle	jection- principles-Principal planes-First angle projections) inclined to both the principal plot and traces Projection of planes (polygonal othod.	lanes -D	etermi	nation	of true leng	gths and true inclinations by
UNIT-III	Projection of Solids					9
Projection of simi	ple solids like prisms, pyramids, cylinder, cor	ne and tr	uncate	d solids	when the	axis is inclined to one of the
-	y rotating object method and auxiliary plane m					ums is memica to one of the
-	y rotating object method and auxiliary plane market Projection of Sectioned Solids and Development	nethod.	of Sur	faces		9
principal planes by UNIT-IV Sectioning of abor perpendicular to the		opment cutting	plane i	s incline	urfaces of s	9 ne of the principal planes and simple and sectioned solids –
principal planes by UNIT-IV Sectioning of abor perpendicular to the	Projection of Sectioned Solids and Develo ve solids in simple vertical position when the he other – obtaining true shape of section. De	opment cutting	plane i	s incline	urfaces of s	9 ne of the principal planes and simple and sectioned solids –
principal planes by UNIT-IV Sectioning of abor perpendicular to the Prisms, pyramids UNIT-V Principles of ison pyramids, cylinder	Projection of Sectioned Solids and Develove solids in simple vertical position when the he other – obtaining true shape of section. Decylinders and cones. Development of lateral successions.	cutting personal cuttin	plane in the plane	s inclined atteral so with coordinate so with coordinate so with coordinate so with coordinate so with a second so with a sec	urfaces of s ut-outs and e solids ar positions a	ne of the principal planes and simple and sectioned solids – holes. 9 and truncated solids - Prisms,
principal planes by UNIT-IV Sectioning of abor perpendicular to the Prisms, pyramids UNIT-V Principles of ison pyramids, cylinder	Projection of Sectioned Solids and Development of section. Description of Section Sect	cutting personal cuttin	plane in the plane	s inclined atteral so with coordinate so with coordinate so with coordinate so with coordinate so with a second so with a sec	urfaces of s ut-outs and e solids ar positions a	ne of the principal planes and simple and sectioned solids – holes. 9 and truncated solids - Prisms, and miscellaneous problems.
UNIT-IV Sectioning of abore perpendicular to the Prisms, pyramids UNIT-V Principles of ison pyramids, cylinder Perspective project Outcome(s)	Projection of Sectioned Solids and Development of section. Description of Section Sect	cutting personal cuttin	plane in the plane	s inclined attends at ray memory at ray memory, lines, a coned solution.	le solids ar positions a method. Total he cal construct. Ind planes. lids.	9 ne of the principal planes and simple and sectioned solids – holes. 9 nd truncated solids - Prisms, and miscellaneous problems. ours 45 etions.
UNIT-IV Sectioning of abore perpendicular to the Prisms, pyramids UNIT-V Principles of ison pyramids, cylinder Perspective project Outcome(s) TEXT BOOK:	Projection of Sectioned Solids and Developed versions in simple vertical position when the he other – obtaining true shape of section. Decylinders and cones. Development of lateral surface in the second section – isometric scale – Isometric projection – isometric scale – Isometric ers, cones – combination of two solid object etion of simple solids-Prisms, pyramids and cy Apply the fundamentals of engineering Construct various plane curves and scale Visualize and draw orthographic projections of section of surfaces of solids and apply	cutting projects in sin linders the drawing es used tions of olids and y isomet	plane in the plane	s incline lateral s s with control of simple vertical al ray me eometrical incering , lines, a oned sold perspe	e solids ar positions a method. Total he cal construction of the cal construc	ne of the principal planes and simple and sectioned solids – holes. 9 and truncated solids - Prisms, and miscellaneous problems. ours 45 etions.
Principal planes by UNIT-IV Sectioning of abore perpendicular to the Prisms, pyramids UNIT-V Principles of isomorphyramids, cylinder Perspective projective projective Outcome(s) TEXT BOOK: 1 S.Gowri	Projection of Sectioned Solids and Developer solids in simple vertical position when the he other – obtaining true shape of section. Decylinders and cones. Development of lateral surface Isometric and Perspective Projections netric projection – isometric scale –Isometric ers, cones- combination of two solid object etion of simple solids-Prisms, pyramids and cy Apply the fundamentals of engineering Construct various plane curves and scale Visualize and draw orthographic projections of s	cutting prelopment cutting c	plane i ent of lof solid tions of mple voy visu g and g in enging points, d section vikas	s inclined lateral solutions with construction of simple vertical all ray members are solutions. The solutions are solutions are solutions are solutions. The solutions are solutions are solutions are solutions. The solutions are solutions are solutions are solutions are solutions. The solutions are solutions are solutions are solutions are solutions.	e solids ar positions a method. Total hacal construction planes. Lids. Ctive projection New Description of the control of the	ne of the principal planes and simple and sectioned solids – holes. 9 and truncated solids - Prisms, and miscellaneous problems. ours 45 etions.

REFER	RENCES:
1	M.B. Shah and B.C. Rana, "Engineering Drawing", Pearson Education 2005.
2	K. R. Gopalakrishnana, "Engineering Drawing" (Vol.I&II), Subhas Publications 1998.
3	Basant Agarwal and Agarwal C.M., "Engineering Drawing", Tata McGraw Hill Publishing Company Limited, New Delhi, 2008.
4	Dhananjay A.Jolhe, "Engineering Drawing with an introduction to AutoCAD" Tata McGraw Hill Publishing Company Limited 2008.

PO CO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12
CO1	3	2	-	-	1	-	-	-	-	1	-	-
CO2	3	2	-	-	1	-	-	-	-	1	-	-
CO3	3	2	-	-	1	-	-	-	-	1	-	-
CO4	3	2	-	-	1	-	-	-	-	1	-	-
CO5	3	2	-	-	1	-	-	-	-	1	-	-



MAHENDRA ENGINEERING COLLEGE

Autonomous | Accredited by NAAC with 'A++' Grade (Cycle-2)
Accredited by NBA Tier-I (WA) UG: CSE, ECE, EEE

fahendhirapuri, Mallasamudram (W), Namakkal (Dt) - 637 503, Tamil Nadu
04288-288 500 / 521 / 522 | www.mahendra.info



Regulations 2024

	Re	egulations	s 2024			
	(Common to al	Semester		grammas	`	
Course Code	Course Name		riods/Wee		Credit	Maximum Marks
24HS11002	தமிழர் மரபு	L 1	T 0	P 0	C 1	100
அலகு 1	மொழிமற்றும் இலக்கியம்	1	U	U		3
இந்தியமொழி	l க் குடும்பங்கள்–திராவிடமொழிகள்–த	நமிழ்ஒருசெ	சம்மொழி –	தமிழ்செவ்	வியக்கங்கள்	ச ங்கஇலக்கியத்தின்
சமயச் சார்பற்	றதன்மை–சங்கஇலக்கியத்தில் பகிர்	தல் அறம்	– திருக்	குறளில்பே	மலாண்மைக்	கருத்துக்கள்–தமிழ்ச்
காப்பியங்கள்,	தமிழகத்தில்சமணபௌத்தசமயங <u>்</u>	களின்	தாக்கம்	் –பக்த	நிஇலக்கியம்,	ஆழ்வார்கள்மற்றுப்
நாயன்மார்கள்	— சிற்றிலங்கியங்கள்—தமிழில்நவீனஇ	இலக்கியத்த	தின் வளர்	ச்சி –தமி	ழ்இலக்கிய எ	வளர்ச்சியில்பாரதியார்
மற்றும் பாரதித	ாசன் ஆகியோரின் பங்களிப்பு.					
அலகு 2	மரபு–பாறைஓவியங்கள்முதல்நவீ	னஒவியங்	கள்வரை-	சிற்பக் க		3
நடுகல்முதல்ந	 வீனசிற்பங்கள்வரை—ஐம்பொன் சிை	லகள்–பழங்	பகுடியினர்	மற்றும்	அவர்கள்தயா	ரிக்கும் கைவினைப்
பொருட்கள்,ெ	பாம்மைகள்–தேர் செய்யும்	கலை சுடு	மண்	சிற்பங்க	ள்–நாட்டுப்புற	த் தெய்வங்கள்-
குமரிமுனையி	ல்திருவள்ளுவர் சிலை–இசைக் கருவ	பிகள்–மிருத	தங்கம், பன	ന്റ, ഖ്ജൈ	ா, யாழ், நாதள்	லவரம் – தமிழர்களின்
0 0	ரதாரவாழ்வில்கோவில்களின் பங்கு.				•	
அலகு 3	நாட்டுப்புறக் கலைகள்மற்றும் வீர	ரவிளையா	ட்டுகள்			3
தெருக்கூத்துக	நரகாட்டம், வில்லுப்பாட்டு, கணியான்	கூத்து, ஒ	யிலாட்டம்,	, தோல்பா	வைக் கூத்து,	சிலம்பாட்டம், வளரி,
புலியாட்டம், தட	மிழா்களின் விளையாட்டுகள் .					
அலகு 4	தமிழா்களின் திணைக் கோட்பாடு	தெள்				3
தமிழகத்தின்	தாவரங்களும் விலங்குகளும் – ெ	தால்காப்பி	யம் மற்று	ம் சங்கஇ)லக்கியத்தில்	அகம் மற்றும் புறக்
கோட்பாடுகள்-	–தமிழர்கள்போற்றிய அறக்கோட்ட	பாடு—சங்க <i>்</i>	காலத்தில்த	தமிழகத்தி	ல்எழுத்தறிவு	ம் கல்வியும் –
சங்ககாலநகரா		_	சங்கக	ாலத்தில்	ரற்றுமதிமற்றுப்	ற இறக்குமதி–
	நகளில்சோழா்களின் வெற்றி.			8.0		O P
அலகு 5	இந்தியதேசியஇயக்கம் மற்றும் இந்	தியபண்பா	ட் டிற்குத்	தமிழா்கல	ரின் பங்களிப்	ц 3
	லப்போரில்தமிழாகளின் பங்கு—இந்	தியாவின்	பிறப்பகு	திகளில்த	மிழ்ப் பண்ப	ாட்டின் தாக்கம் -
) யக்கம் – இந்தியமருத்துவத்தில்,ச					
	களின் அச்சுவரலாறு.		Trough III			J. J.
No 1 Marin Marin					TO	TAL – 15 PERIODS



MAHENDRA ENGINEERING COLLEGE
Autonomous | Accredited by NAAC with 'A++' Grade (Cycle-2)
Accredited by NBA Tier-I (WA) UG: CSE, ECE, EEE
Mahendhirapuri, Mallasamudram (W), Namakkal (Dt) - 637 503, Tamil Nadu
04288-288 500 / 521 / 522 | www.mahendra.info



Regulations 2024

	Semester - (Common to all B.E./B.Te		gramn	nes)		
Course code	Course Name		eriods/		Credit	Maximun marks
24HS11002	HERITAGE OF TAMILS	L	T	P	C	100
		1	0	0	1	100
UNIT-I	LANGUAGE AND LITERATURE				J.,	3
- Management I Land - Bakthi L literature in Tan	mil – Secular Nature of Sangam Literatu Principles in Thirukural - Tamil Epics iterature Azhwars and Nayanmars - For nil - Contribution of Bharathiyar and Bh HERITAGE - ROCK ART PAINT	and Im ms of n arathid	pact of ninor F hasan	f Buddhis Poetry - D	sm & Jaini evelopmer	sm in Tami
UNIT-II	SCULPTURE	ings	TO M	ODERN	ARI –	3
Making of mus Temples in Soci	ssive Terracotta sculptures, Village desical instruments - Mridhangam, Parai, ial and Economic Life of Tamils.	eities, 7 Veena	Thiruva ii, Yaz	alluvar S h and Na	tatue at K adhaswarar	anyakumari n - Role o
UNIT-III	FOLK AND MARTIAL ARTS					3
Valari, Tiger da	aragattam, VilluPattu, KaniyanKoothunce - Sports and Games of Tamils.	, Oyilla	ittam,	Leather p	ouppetry, S	ilambattam
UNIT-IV	THINAI CONCEPT OF TAMILS					3
Aram Concept of	n of Tamils &Aham and Puram Concept of Tamils - Education and Literacy duri Export and Import during Sangam Age -	ng San	gam A	ge - Anci	ient Cities	Literature and Ports o
UNIT-V	CONTRIBUTION OF TAMILS MOVEMENT AND INDIAN CULT	S TO			ATIONAL	L 3
Contribution of	Tamils to Indian Freedom Struggle - Th	e Cultu	ral Inf	luence of	Tamils over	er the other
Medicine – Insc	Self-Respect Movement - Role of Siddh riptions & Manuscripts – Print History of	a Medi	cine in	Indigeno	us Systems	s of

	TOTAL – 15 PERIODS
TEX	T BOOK ANDREFERENCE BOOKS
1.	தமிழகவரலாறு–மக்களும் பண்பாடும் – கே.கே. பிள்ளை (வெளியீடுதமிழ்நாடுபாடநூல்மற்றும் கல்வியியல்பணிகள்கழகம்)
2.	கணினித் தமிழ்–முனைவா் இல. சுந்தரம் (விகடன் பிரசுரம்)
3.	கீழடி–வைகைநதிக்கரையில்சங்ககாலநகரநாகரிகம் (தொல்லியல்துறைவெளியீடு)
4.	பொருநை—ஆற்றங்கரைநாகரிகம் (தொல்லியல்துறைவெளியீடு)
5.	Social Life of Tamils (Dr.K.K.Pillay) A joint publication of TNTB & ESC and RMRL – (in print)
6.	Social Life of the Tamils - The Classical Period (Dr.S.Singaravelu) (Published by: International Institute of Tamil Studies.
7.	Historical Heritage of the Tamils (Dr.S.V.Subaramanian, Dr.K.D. Thirunavukkarasu) (Published by: International Institute of Tamil Studies).
8.	The Contributions of the Tamils to Indian Culture (Dr.M.Valarmathi) (Published by: International Institute of Tamil Studies.)
9.	Keeladi - 'Sangam City Civilization on the banks of river Vaigai' (Jointly Published by: Department of Archaeology & Tamil Nadu Text Book and Educational Services Corporation, Tamil Nadu)
10	Studies in the History of India with Special Reference to Tamil Nadu (Dr.K.K.Pillay) (Publishedby: The Author)
11.	Porunai Civilization (Jointly Published by: Department of Archaeology & Tamil Nadu Text Bookand Educational Services Corporation, Tamil Nadu)
12.	Journey of Civilization Indus to Vaigai (R.Balakrishnan) (Published by: RMRL) – Reference Book.

				Ho	ırs/W	eek	Credit	Maximum
	Course	e Code	Course Name	L	T	P	С	marks
	241	HS21001	Personality Development Practice	0	0	2	1	100
Obje	ective(s)		 To develop listening and speaking skills of presentations, attending interviews and part To enhance the non-verbal and social intercommunicators To enable learners to hone their linguistic (2) 	icipati eractio	ng in d n skill	iscussi s of st	ions udents for	becoming effective
			LIST OF EXPERIMEN	NTS				
	1	Importance of	of Communication Skills					
	2	Building Vo	cabulary (Basic level)					
	3	Stage Dynan	nics (Group PPT Presentation)					
	4	Predicting th	e Content of a Given Article (Newspaper, Maga	azine, e	etc.,)			
	5	Common Err	ors in English					
	6	Interview Sk	ills					
	7	Presentation	skills					
	8	Group Discu	ssion					
	9	Soft Skills (S	Self-Confidence, Team Work, Time Managemen	nt, Ad	aptabil	ity, Op	enness to	Criticism)
	10	Creative Wri	ting - Any Essay type (Descriptive, Narrative e					
				<u>, </u>	Fotal	hours	45	
			the course, the students will be able to	~				
Outo	come(s)		stand the language proficiency and its technique the resume with organized details	S				
		_	op soft skills to excel in their career					
REI	FERENC		F					
1	Joshi, Ma	anmohan, Sof	t Skills, 1st Edition. Bookboon, 2017					
2		Meenakshi & S w Delhi. 2013	Sangeeta Sharma. Technical Communication: P	rincipl	es and	Praction	ce, Ed.III,	Oxford University
WE	BSITES							
1		www.ted.com/	/talks					
2		iizziz.com						
3	www.pdf	drive.com						
4	https://np	otel.ac.in/						
AC'	TIVITY	:						

COs Vs POs and PSOs Mapping

Worksheets for relevant topics

PO CO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	-	1	-	2	1	-	1	2	3	1	2	-	-	-
CO2	2	-	2	-	2	1	-	1	3	3	2	2	-	-	-
CO3	2	-	2	-	2	2	-	2	3	3	2	3	-	-	-

Cou	ırse	G. N	Ho	urs/W	eek	Credit	Maximum
Co		Course Name	L	T	P	C	marks
240	CY22001	Chemistry Laboratory	0	0	3	1.5	100
Objective(s)		 To inculcate experimental skills to test b as, alkalinity, hardness, DO and chloride To induce the students to familiarize wit potentiometry and conductometry in the To design and plan the experimental pro 	h electro determin	analyti ation c	ical tec	chniques su urities in aq	ch as, pH metry, ueous solutions.
		LIST OF EXPERIM	ENTS				
1	Determinati	on of Total, Temporary & Permanent hardne	ss of wate	er usin	g EDT	'A method.	
2	Determinati	on of the Alkalinity level of a water sample.					
3	Determinati	on of Chloride content of water sample by A	rgentome	try.			
4	Determinati	on of DO content of water sample using Win	kler's me	thod.			
5	Determinati	on of molecular weight of polyvinyl alcohol	using Vis	comet	ry.		
6	Estimation	of Iron content of the given solution using Po	tentiomet	ry.			
7	Determinati	on of strength of given hydrochloric acid usin	ng pH me	ter.			
8		etric titration of strong acid vs strong base.	<u> </u>				
9		on of strength of acids in a mixture using Con	nductome	try.			
10		of sulphate in a solution using Conductometry			•		
	<u> </u>			Fotal		45	
Outcome(s)	Explain DO, andExperin	on of this course, students will have the know the essential principles and their analysis of d chloride. Then with different types of instruments for are	water qua				
	_	k and accurate results. e the normality of different types of materials	cuch as F	NA at	nd Feri	rous ion	
TEXT BOOK		the normanty of different types of materials	such as i	v / i ai	id i cii	ous ion.	
1		b Manual, Department of Chemistry, Mahend	ra Engine	eering	Colleg	ge, Mallasar	nudram, 2022.
2	Chemistry lal	Manual, Department of Chemistry, Mahend	lra Engine	eering	Colleg	ge, Mallasar	nudram, 2020.
REFERENCI							
1		nistry theory and practice by O. P. Vermani a					
2	Chemical An	R. C. Denney, J.D. Barnes, M. Thomas and I alysis (2009).					
3	Kolthoff I.M.	and Sandell E.B. et al. Quantitative chemica COs Vs POs and PSOs M		, Mcm	illan,	Madras 198	80

COs Vs POs and PSOs Mapping

PO CO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	_	-	-	_	-	_	1	2	-	-	-	-	-	-
CO2	3	-	-	2	-	-	-	1	2	-	-	-	-	-	-
CO3	2	3	-	2	-	-	-	1	2	-	-	-	-	-	-

Course code	Course Name	Но	ours/w	eek	Credit	Maximum marks
24GE23101	Computer Aided Design and	L	Т	P	С	100
24GE25101	Drafting Laboratory	0	0	3	1.5	100
	 To produce accurate orthographic, so Computer-Aided Design (CAD) met 		, and is	sometric	c drawings	using conventional and
Objective(s)	To effectively apply CAD software	in devel	oping 6	enginee	ring graph	ics.
	 To understand the application of soluthrough practical CAD exercises. 	id mode	eling an	d surfa	ce develop	ment techniques

Projection of Solids – Introduction to CAD - Projection of solids: prisms, pyramids, cylinders, cones (axis inclined to one plane).

- Projection of a cylinder with its axis inclined to HP
- Projection of a cone with its axis inclined to VP

Section of Solids and Development of Surfaces - Sectioning of solids (prisms, pyramids, cylinders, cones) using inclined cutting plane to one reference plane and perpendicular to the other – True shape of section. Development of lateral surfaces including solids with cylindrical cutouts.

- Sectional view of a truncated cone and cylinder
- Sectional view of a prism and pyramid
- Development of lateral surfaces of simple and truncated solids (prisms, pyramids, cylinders and cones)
- Development of lateral surfaces of solids with cylindrical cutouts, perpendicular to the axis.

Isometric and Perspective Projections - Isometric scale, projection of solids (prisms, pyramids, cylinders, cones) – Perspective projections using visual ray method.

- Isometric projection of a cylinders and cones
- Isometric projection of a truncated prism and pyramid
- Perspective projection of a pyramid
- Perspective projection of a cylinder

LIST OF EQUIPMENTS

- 1. Hardware with graphics facility 30 No.
- 2. Drafting and Modeling software 30 users

Total hours: 30

Outcome(s)

- Use Computer-Aided Drafting (CAD) software to construct and modify engineering drawings
- Use CAD software to develop sectional drawings, development of surfaces and apply appropriate dimensioning practices.
- Use CAD software to produce isometric and perspective projections

COs Vs POs and PSOs Mapping

PO CO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12
CO1	1	2	-	3	3	-	-	1	-	1	-	1
CO2	1	2	-	3	3	-	-	1	-	1	-	1
CO3	1	2	-	3	3	-	-	1	-	1	-	1
Avg.	1	2	-	3	3	-	-	1	-	1	-	1

Course code	Course Name	H	ours/w	eek	Credit	Maximum m	Aaximum marks	
24MA12201	Engineering Mathematics - II	L	T	P	C			
24MA12201		3	1	0	4	100		
Objective(s)	 To enable the students to: Define vector function, operators and integrals. Explain different types of higher order various methods to solve the equations Learn Laplace transform, inverse L equations. 	ordinar	y differ	ential e	equations wi	thvariable coeffici	ents and	
	 Know about functions of complex mapping. Learn about Taylor's and Laurent's 		-		-	_		
UNIT-I	evaluating complex integrals. Vector Calculus					9+3	3	
	e and Curl – Directional derivative – Irrot	tational	and so	lenoida	1 vector fie			
	plane, Gauss divergence theorem and Stok							
	rface and volume integrals.				81			
UNIT-II	Ordinary Differential Equations of Hig	gher O	rders			9+3	3	
•	order linear differential equations with coon, Legendre's type differential equations					•		
UNIT-III	Laplace Transform					9+3	₹	
	ies of Laplace Transform, Laplace transfor	m of pe	eriodic 1	functio	ns. Finding			
	ls, convolution theorem, solving Initial valu							
UNIT-IV	Analytic Functions	•	•			9+3	3	
	lex variable, Cauchy-Riemann equations –							
•	Harmonic conjugate – Construction of anal	lytic fu	nctions	– Con	formal map	ping: $w = z + c$, cz ,	1/z, an	
Bilinear transformati						0.0	•	
UNIT-V	Complex Integration	?a intoo			ad Canalani	9+3		
proof) – Taylor and	 Statement and applications of Cauchy Laurent expansions –Types of Singularit of residue theorem to evaluate real integral 	ies-Sing	gular po	oints –	Residues -			
•	Ğ				Total h	ours 60		
Outcome(s)	 At the end of the course the students will be Solve problems related to vector differential equation. Solve higher order differential equation. Describe Laplace transform and its predifferential equation using Laplace transform. Solve Analytic functions, harmonic further expand the functions as Taylor's and 	ons with operties ansform unctions	on, line, n variable s inverse technic s, confor	le coefi e Lapla ques. rmal m	ficients. ce transforn apping and	n and the solution of the applications.		
						<u> </u>		
ГЕХТ ВООК :	· · · · · · · · · · · · · · · · · · ·							
	l, Higher Engineering Mathematics, Khanna	a Publis	shers, 20)17.				
	l, Higher Engineering Mathematics, Khanna szig, Advanced Engineering Mathematics,				018.			
1 B.S. Grewal 2 Erwin Krey REFERENCES:	szig, Advanced Engineering Mathematics,	John W	iley & S	Sons, 2	018.			
1 B.S. Grewal 2 Erwin Krey REFERENCES: 1 Michael D.	szig, Advanced Engineering Mathematics, . Greenberg, Advanced Engineering Mathem	John W natics, F	iley & S Pearson	Sons, 2 2013.				
1 B.S. Grewal 2 Erwin Krey REFERENCES: 1 Michael D. 2 Lokenath D	szig, Advanced Engineering Mathematics,	John W natics, F sforms	iley & S Pearson and The	Sons, 2 2013. eir App	lications, Cl			

PO CO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	2	2	2	-	-	-	-	-	-	2	2	2	3
CO2	3	3	2	2	2	-	-	-	-	-	-	2	2	2	2
CO3	3	3	2	2	2	-	-	-	-	-	-	2	2	2	2
CO4	3	3	2	2	2	-	-	-	-	-	-	2	2	2	1
CO5	3	3	2	2	2	-	-	-	-	-	-	2	2	2	1

Course code	Course Name	Н	ours/w	eek	Credit	M	aximum marks
24PY12001	Engineering Physics	L	Т	P	С		100
241 112001	(For all branches)	3	0	0	3		100
Objective(s)	 To provide fundamental knowledge Physics and different kinds of Engine To correlate the principles with applie 	eering M	laterials	•	Î		of Matter, Quantum
UNIT-I	Laser and Fiber Optics						9
Types of lasers - CO	ple of spontaneous emission, stimulated a 2, Nd: YAG – Fiber optics: principle, nun index and mode) – losses associated	nerical a	perture	and acc	ceptance ang	gle - ty	pes of optical fibers
UNIT-II	Ultrasonics						9
effect- piezoelectric Destructive Testing -	ction – magnetostriction effect - magnetogenerator – properties – Cavitations - V – pulse echo system through transmission dical applications-medical endoscope. Properties of Matter	Velocity	measur	rement	– acoustic	gratin	g – SONAR - Non
	rain diagram and its uses - factors affecting	14.	1	1	1.4	41.	
deformations – twis cantilever: theory an due to bending in bea	ting couple - torsion pendulum: theory d experiment – uniform and non-uniform ams.	and exp	erimen	t - ber	nding of be	ams -	bending moment – aped girders - stress
UNIT-IV	Quantum Physics						9
and its physical signi	 Planck's theory (derivation) –wave par ficance – Schrödinger's wave equation – gid box – scanning tunneling microscope- 	time inc	lepende	nt and	time depend		•
UNIT-V	Advanced Engineering Materials						9
Metallic glasses – Or Biomaterials: First, s	pe-memory alloys: Martensite, Austenite igin – Preparation – Structure, mechanica econd and third generation biomaterials – cine: Skin and Blood interfacing implants	l and ele Classifi	ctrical p	oropert	ies.		• •
	<u> </u>				Total h	ours	45
Outcome(s)	 After completing the course the students Understand the basics of Laser, Fiber Gain knowledge about Ultrasonic's to Have the necessary understanding or Get Knowledge on basics concepts or 	heir app Propert of Quantu	lications ies of m im Phys	s in var naterial sics wit	rious engine s and their u th their App	ering f uses. lication	ields. ns.
	• Understand the properties of SMA, r						Pirotions.
TEXT BOOK :	Understand the properties of SMA, r.						
1 Dr. G. Senthi	l kumar - Engineering Physics-VRB Publi					ion 202	
1 Dr. G. Senthi 2 Dr. P.K. Pala	l kumar - Engineering Physics-VRB Publinisamy, "Engineering Physics", Sci tech	Publicati	ions, Ch	ennai,	2022.	ion 202	
1 Dr. G. Senthi 2 Dr. P.K. Pala 3 Biomaterial S	I kumar - Engineering Physics-VRB Publinisamy, "Engineering Physics", Sci tech is cience and Engineering- JB Park- Plenum	Publicati n Press, 1	ons, Ch	ennai, k(2014	2022. 4).		22.
 Dr. G. Senthi Dr. P.K. Pala Biomaterial S M N Avadha 	I kumar - Engineering Physics-VRB Publinisamy, "Engineering Physics", Sci tech Ecience and Engineering- JB Park- Plenumulu, A Textbook of Engineering Physics	Publicati n Press, 1 (2008), 5	ions, Ch NewYor S. Chan	ennai, k(2014 d Publi	2022. 4). shing, New	Delhi	22.
 Dr. G. Senthi Dr. P.K. Pala Biomaterial S M N Avadhar Bhattacharya 	I kumar - Engineering Physics-VRB Publinisamy, "Engineering Physics", Sci tech is cience and Engineering- JB Park- Plenum	Publicati n Press, 1 (2008), 5	ions, Ch NewYor S. Chan	ennai, k(2014 d Publi	2022. 4). shing, New	Delhi	22.
1 Dr. G. Senthi 2 Dr. P.K. Pala 3 Biomaterial S 4 M N Avadha 5 Bhattacharya REFERENCES:	I kumar - Engineering Physics-VRB Publicisamy, "Engineering Physics", Sci tech in cience and Engineering- JB Park- Plenum Physics of Engineering Physics D.K. & Poonam, T. —Engineering Physics	Publicati n Press, 1 (2008), 5 ics. Oxfo	ions, Ch New Yor S. Chan ord Univ	ennai, k(2014 d Publi versity	2022. 4). shing, New Press, 2015.	Delhi	22.
1 Dr. G. Senthi 2 Dr. P.K. Pala 3 Biomaterial S 4 M N Avadha 5 Bhattacharya REFERENCES: 1 Pillai S O, "E	I kumar - Engineering Physics-VRB Publinisamy, "Engineering Physics", Sci tech Ecience and Engineering- JB Park- Plenumulu, A Textbook of Engineering Physics	Publication Press, No. (2008), Sics. Oxfo	ions, Ch NewYor S. Chan ord Univ	ennai, k(2014 d Publi versity	2022. 4). shing, New Press, 2015.	Delhi.	22.

3	Introduction to Quantum Mechanics- J Griffiths-2nd edition(2016).
4	Halliday.D, Resnick.R. & Walker.J, Principles of Physics (2020), Wiley.
5	Serway, R.A. & Jewett, J.W. —Physics for Scientists and Engineers. Cengage Learning, 2010.
6	William T. Silfvast, Laser Fundamentals (2014), Cambridge University Press.

PO CO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	2	2	2	-	1	-	-	-	-	2	2	2	1
CO2	3	2	2	2	2	-	1	-	-	-	-	2	2	2	1
CO3	3	2	2	2	2	-	2	-	-	-	-	2	2	3	1
CO4	3	2	2	2	2	-	1	-	-	-	-	2	2	2	1
CO5	3	2	2	2	2	-	2	-	-	-	-	2	2	3	1

Course code	Course Name	Но	ours/w	eek	Credit	Maximum marks
	Problem Solving Techniques	L	Т	P	С	
24CS13001	Using C	3	0	0	3	100
Objective(s)	 The student should be made to: Understand the basics of computer a Learn the basic concepts of C Progra Know the arrays and functions in C Be familiar with pointers and structure Learn the file handling techniques and 	amming.		rs in C		
UNIT-I	Problem Solving Aspects					9
olving Aspects: A lgorithms (iteration,	re – Software – Processor – Memory – I/O Igorithms Pseudo code, Flowchart-Steps recursion) – Steps for Creating and Runni list - Factorial Computation - Fibonacci S	in Proing prog	blem S rams -I	Solving	s – simple	strategies for developin
U NIT-II	C Programming Basics					9
Variables – Data Typ operations – Decision	gramming – Header files – Structure of a Gres – Expressions-, Expression Evaluation, Making and Branching – Looping statem	Type co	onversi	on Stat	ements – op	erators – Input and Outpu
JNIT-III	Arrays and Function					9
Function – definition	 One-Dimensional Arrays – Two and mu of function – Declaration of function – Fu alue – Pass by reference – Recursion - Pro 	ınction p	rototyp	e – Ty		
UNIT-IV	Pointers and Structures	<u> </u>				9
Pointers with Function	– Initialization - Pointer variables, Pointer ons- Introduction to Structure – structure de fusion with Arrays- Unions – Storage class	efinition				
JNIT-V	File Processing					9
	ile functions – Types of file processing: Senents – C Preprocessor directives: Macros	_				<u> </u>
inprementing user de	Simed neader thes				Total h	ours 45
Outcome(s)	 Upon completion of this course, students Illustrate algorithms for real time prol Explain the syntax of C Programming Summarize the concept of arrays and Apply the concepts of pointers and step Develop the concepts of files and preport 	blems the g function tructure	rough v		problem so	ving techniques
TEXT BOOK:	I					
	d Ajay Mittal, "Computer Fundamentals ation, 2016	and Pro	gramm	ing in (C", Dorling	Kindersley (India)Pvt. L
REFERENCES:	·					
	"How to Solve it by Computer" Prentice I	Hall of I	ndia, D	elhi., 2	010.	
E Balagurusa	my, "Computer Programming", First Edit	tion, Tat	a McG	raw Hi	ll Education	(India) Private Ltd, Nev

Delhi., 2013.

- 4 M.Rajaram and P.Uma Maheshwari "Computer Programming with C", Pearson Education., 2013.
- 5 NPTEL course, Problem Solving Through Programming in C, https://nptel.ac.in/courses/106105171
- 6 NPTEL course, Introduction to Programming in C, https://nptel.ac.in/courses/106104128

PO CO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	1	2	-	-	-	-	-	-	-	-	3	-	-
CO2	3	2	1	1	-	-	-	-	-	-	-	-	2	-	-
CO3	3	2	1	2	-	-	-	-	-	-	-	-	2	-	-
CO4	3	2	1	2	-	-	-	-	-	-	-	-	2	-	-
CO5	3	2	1	2	-	-	-	-	-	-	-	-	2	-	-

Course code	Course Name	Но	urs/we	eek	Credit	М	aximum marks
	Basics of Electrical and	L	Т	P	C		100
24EE13001	Electronics Engineering	3	0	0	3		100
Objective(s)	 To study the basic concepts of elect To understand the operation of mag To study the concepts of semicondu To acquire knowledge on the conce To impart knowledge on the basic of 	netic control of the	rcuits a vices ntegrate	and elected circuit	ctrical mac	hines	
UNIT-I	Electrical Circuits and Measurements noff's Law- Voltage and Current Sources-	Racics	of Res	ictance	Inductan	re and	Ganacitance- Series
and Parallel circuits-	Average value and RMS value – Power a Instruments – Energy Meter-Residential w	and Pov	wer Fac	tor- C			
UNIT-II	Electrical Machines						9
Working Principle: I	netic circuits, Faraday's law, Lenz's Law, Floc Machines -Single phase Transformer – alitative treatment only).						
UNIT-III	Semiconductor Devices						9
	Characteristics – Half wave and Full wave Insistor, FET, JFET-Characteristics.	Rectifie	rs –Zer	ner dio	de- Charact	eristics	
UNIT-IV	Digital ICS and Microcontroller						9
	Logic gates - Demorgan's Theorem -						ractor, Multiplexer,
Demultiplexer - Pin I UNIT-V	Details and Architecture of Microprocessor Communication Systems	(8086)	and M1	crocon	troller (805	1).	9
	nalog and Digital Signals – Modulation ar	nd Den	odulati	on: Pr	inciples of	A mpli	
Modulations (Quali	tative Treatment). Communication Systems Approach only)				•	•	
					Total l	ours	45
Outcome(s)	 At the end of the course, students will be all Summarize the concepts of electrical c Illustrate the constructional features an Explain the operation of semiconducto Interpret the concepts of integrated circ Discuss the basic concepts of Communication 	ircuits d work r devic cuits	ing prin	nciple (•		ines
TEXT BOOK:							
1 V.K Mehta a Edition, 2016	and Rohit Mehta, "Principle of Electrical I	Engine	ering a	nd Ele	ctronics" S	Chan	d & Company, Thir
2 S. Salivahana Edition, 2011	n, N. Suresh kumar and A. Vallavanraj, "E	Electron	ic Devi	ices an	d Circuits"	, Tata	McGraw Hill, Secon
3 Edward Hugh	es, "Hughes Electrical and Electronic Tech	nology	', Pears	on Edu	ucation, ten	th Edit	ion 2008.
4 David A. Bell	l, "Electronic Devices and Circuits", Oxford	l Unive	rsity Pr	ess, Fi	fth Edition	, 2008.	
REFERENCES:							
	enter, "Introducing Electronics Devices and						
2 William H. H Sixth, Edition	ayt, J.V. Jack, E. Kemmebly and steven M., 2002.	Durbii	n, "Eng	ineerin	g Circuit A	nalysis	s", Tata McGraw Hil

- J. Millman&Halkins, SatyebrantaJit, "Electronic Devices & Circuits", Tata McGraw Hill, Second Edition, 2008.
- 4 **NPTEL**

Prof. L. Umanand, Basic Electrical Technology, IISc Bangalore https://nptel.ac.in/courses/108108076
Prof. M.B. Patil Basic Electronics IIT Bombay https://onlinecourses.nptel.ac.in/noc21_ee55/preview

PO CO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	-	-	-	-	1	-	-	-	1	-	1	1	-	-
CO2	3	-	-	-	-	1	-	-	-	1	-	1	1	-	-
CO3	2	-	-	-	-	1	-	-	-	1	-	1	1	-	-
CO4	3	-	-	-	-	1	-	-	-	1	-	1	1	-	-
CO5	2	-	-	-	-	1	-	-	-	1	-	1	1	-	-

UNIT-I Introduction to Me transmissibility- Lar moments, Coplanar fof a particle in space UNIT-II Free body diagram - Moment of a force a of a moment- Varign	Engineering Mechanics (Common to Non Circuit Branches) Students should develop the ability to: Work comfortably with basic enginee structures. Model the problem using good free-body Apply pertinent mathematical, physical solve and analyze the problem. Understand the meaning of centers of integration methods. Gain knowledge in basic design concepts Statics of Particle Chanics — Fundamental Principles -Units me's theorem, Parallelogram and triangular forces—Resolution and Composition of forces are Equivalent systems of forces - Single equivalents of Statics of Rigid Body Types of supports and their reactions-required bout a point and about an axis—Vectorial representation's theorem — Single equivalent force -Equivalent force -Equivale	diagram and eng gravity of statics and Dia Law of s – Equilibration for the control of the contr	mensions and a gineerin (mass) s and dy mension f forces ibrium ree.	ynamic ns – I s- Vector	equilibrium anical pripoids and response sof the paragraph of laws of	mequations. inciples to the systemoment of inertia contribution. 9 Mechanics- Principle resentation of forces the space - Equilibrium particular and the system process of the
UNIT-I Introduction to Me transmissibility- Lar moments, Coplanar f of a particle in space UNIT-II Free body diagram - Moment of a force a of a moment- Varign	 Students should develop the ability to: Work comfortably with basic engineer structures. Model the problem using good free-body Apply pertinent mathematical, physical solve and analyze the problem. Understand the meaning of centers of integration methods. Gain knowledge in basic design concepts Statics of Particle Chanics – Fundamental Principles -Units me's theorem, Parallelogram and triangular forces—Resolution and Composition of forces are Equivalent systems of forces - Single equiveral Statics of Rigid Body Types of supports and their reactions-requision a point and about an axis—Vectorial regulation. 	ring me diagram and eng gravity of statics and Dia Law of s – Equilivalent for irements oresentati	echanics as and a gineerin (mass) s and dy mension f forces ibrium rce.	s concercion concercion se con	epts required the equilibrium than ical principles and representations of the particles - Force icles - Force	mequations. inciples to the systemoment of inertia contribution. 9 Mechanics- Principle resentation of forces the space - Equilibrium particular and the system process of the
UNIT-I Introduction to Me transmissibility- Lar moments, Coplanar f of a particle in space UNIT-II Free body diagram - Moment of a force a of a moment- Varign	 Work comfortably with basic enginee structures. Model the problem using good free-body Apply pertinent mathematical, physical solve and analyze the problem. Understand the meaning of centers of integration methods. Gain knowledge in basic design concepts Statics of Particle Chanics – Fundamental Principles -Units me's theorem, Parallelogram and triangular forces—Resolution and Composition of forces are Equivalent systems of forces - Single equiverage Statics of Rigid Body Types of supports and their reactions-requision a point and about an axis—Vectorial regulation. 	diagram and eng gravity of statics and Dia Law of s – Equilibration for the control of the contr	mensions and a gineerin (mass) s and dy mension f forces ibrium ree.	ynamic ns – I s- Vector	equilibrium anical pripoids and response sof the paragraph of laws of	mequations. inciples to the systemoment of inertia contribution. 9 Mechanics- Principle resentation of forces the space - Equilibrium particular and the system process of the
Introduction to Me transmissibility- Lar moments, Coplanar f of a particle in space UNIT-II Free body diagram - Moment of a force a of a moment- Varign	chanics – Fundamental Principles -Units me's theorem, Parallelogram and triangular forces– Resolution and Composition of forces - Equivalent systems of forces - Single equivalents of Rigid Body Types of supports and their reactions-requibout a point and about an axis– Vectorial rep	Law of s – Equilibrated for irements or contact	f forces ibrium rce.	s- Vector of parti	torial repre	Mechanics- Principle resentation of forces ces in space - Equilib
transmissibility- Lar moments, Coplanar for a particle in space UNIT-II Free body diagram - Moment of a force a of a moment- Varigin	me's theorem, Parallelogram and triangular forces—Resolution and Composition of forces - Equivalent systems of forces - Single equivariations of Rigid Body Types of supports and their reactions-requisions a point and about an axis—Vectorial regulations.	Law of s – Equilibrated for irements or contact	f forces ibrium rce.	s- Vector of parti	torial repre	resentation of forces ces in space - Equilib
Free body diagram - Moment of a force a of a moment- Varign	- Types of supports and their reactions-requibout a point and about an axis- Vectorial rep	presentati			1111	
Moment of a force a of a moment- Varign	bout a point and about an axis- Vectorial rep	presentati			1111	
UINII-III	D 4 60 4	iiorium (momen	ts and coup	ples – Scalar compo mensions.
	Properties of Sections					9
using standard formulareas by integration -	alar, circular, triangular areas by integration - ula – Theorems of Pappus and Guldinus – So – T section, I section, Angle section, Hollow neorem – Product of inertia of plane areas -P gular section.	econd mo	oment o	of area g standa	— Rectan ard formula	ngular, circular, trian a –Parallel axis theor
	Dynamics of Particles					9
D'Alembert's princip	ocity and acceleration, their relationship – ble – Work Energy Equation of particles – Impact – coefficient of restitution.					
UNIT-V	Friction					9
	vs of sliding friction -Laws of Coloumb frict ion - equilibrium analysis of simple contact fr s.				•	
					Total hou	urs 45
Outcome(s) Er • • •	Analyze the engineering problems in case of Calculate the reaction forces of various sup Evaluate various geometrical properties like surfaces and solids. Solve the problems involving dynamics of Define the effects of friction and its applica	of equilib ports on te centroi	the struid, cent	actural in the control of the contro	members. ravity, mor	
TEXT BOOK:	Define the effects of friction and its applica	uons, ais	so comp	Juic V	arious ilici	nonai components.
	peller, "Engineering Mechanics – Statics and	l Dynam	nics", 1	1 th ed.,	Pearson E	Education Asia Pvt.
2009.	- -	-	-			

	Tata McGraw-Hill International Edition, 2010.
3	Dr.N.Koteeswaran, "Engineering Mechanics Statics and Dynamics", Sri Balaji Publications 9th Rv.Ed., S.Chand & Co Ltd, 2013.
4	Vela Murali, "Engineering Mechanics", Oxford University Press 2010.
REFE	RENCES:
1	M.S. Palanichamy and S. Nagam, "Engineering Mechanics – Statics & Dynamics", 3 rd ed., Tata McGraw-Hill, 2004.
2	S. Rajasekaran, G. Sankarasubramanian, "Fundamentals of Engineering Mechanics", 3 rd ed., Vikas Publishing House Pvt. Ltd, 2009.
3	Kumar, K.L., "Engineering Mechanics", 3 rd Revised Edition, Tata McGraw-Hill Publishing company, New Delhi 2008.
4	Irving H. Shames, "Engineering Mechanics – Statics and Dynamics", 4 th ed., – Pearson Education Asia Pvt. Ltd., 2005.

PO CO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2	3	-	-	1	-	1	-	-	-	1	3	-	-
CO2	2	2	3	-	_	1	-	1	-	-	-	1	3	-	-
CO3	2	2	3	-	-	1	-	1	-	-	-	1	3	-	-
CO4	2	2	3	-	-	1	-	1	-	-	-	1	3	-	-
CO5	2	2	3	-	-	1	-	1	-	-	-	1	3	-	-

MAHENDRA ENGINEERING COLLEGE

Autonomous | Accredited by NAAC with 'A++' Grade (Cycle-2)
Accredited by NBA Tier-I (WA) UG: CSE, ECE, EEE
fahendhirapuri, Mallasamudram (W), Namakkal (Dt) - 637 503, Tamil Nadu



04288-288 500 / 521 / 522 | www.mahendra.info

	Regula	tions 202	24			
		ester - II	D			
Course Code	(Common to all B.E Course Name		. Prograi riods/We		Credit	Maximum Marks
24HS11003	தமிழரும் தொழில்நுட்பமும்	L 1	T 0	P 0	C 1	100
அலகு 1	நெசவுமற்றும் பானைத் தொழில்நுட்பம்	1	U	1 0		3
சங்ககாலத்தில்		தொழில்ற	நட்பம்	_	கருப்புசி	வப்புபாண்டங்கள
அலகு 2	வடிவமைப்பும <u>ற்று</u> ம் கட்டிடத் தொழில்ந	بذيية				3
மாமல்லபுரச் க நாயக்கர் கா	ல்கட்டுமானபொருட்களும் நடுகல்லும் – ரிற்பங்களும்,கோவில்களும் – சோழர் காவ லக் கோயில்கள்–மாதிரிகட்டமைப்புகள்	்த்துப் பெ பற்றி அற	ருங்கோய நிதல், ம	பில்கள்ம <u>ர்</u> துரைமீன	றும் பிறவழிட ாட்சிஅம்மன்	ராட்டுத் தலங்கள் ஆலயம் மற்று
கலை. அலகு 3 கப்பல்கட்டும் சான்றுகளாக(கல்மணிகள்,	செம்புமற்றும் தங்கநாணயங்கள்–நாணய கண்ணாடிமணிகள்–சுடுமண் மணிகள்–ச	தொழிற்சா ங்கள் அச்ச	லை-இரு முத்தல்-ப	ம்பைஉரு . மணிஉரு.	க்குதல், யாக்கும் ெ	3 எஃகு–வரலாற்று தாழிற்சாலைகள்
கலை. அலகு 3 கப்பல்கட்டும் சான்றுகளாக கல்மணிகள், சிலப்பதிகாரத்	உற்பத்தித் தொழில்நுட்பம் கலை–உலோகவியல்–இரும்புத் செம்புமற்றும் தங்கநாணயங்கள்–நாணய	தொழிற்சா ங்கள் அச்ச ங்குமணிச	லை–இரும முத்தல்–ட எ்–எலும்	ம்பைஉரு . மணிஉரு.	க்குதல், யாக்கும் ெ	3 எஃகு–வரலாற்று தாழிற்சாலைகள்
கலை. அலகு 3 கப்பல்கட்டும் சான்றுகளாக கல்மணிகள், சிலப்பதிகாரத் அலகு 4 அணை, ஏரி கால்நடைகளு கடல்சார் அற்	உற்பத்தித் தொழில்நுட்பம் கலை—உலோகவியல்—இரும்புத் செ செம்புமற்றும் தங்கநாணயங்கள்—நாணய கண்ணாடிமணிகள்—சுடுமண் மணிகள்—ச தில்மணிகளின் வகைகள். வேளாண்மைமற்றும் நீர்ப்பாசனத் தொடி , குளங்கள், மதகு—சோழர்காலக் குமி க்காகவடிவமைக்கப்பட்ட கிணறுகள்—வே வ்டி–மீன்வளம் – முத்து மற்றும் முத்துக்கு	தொழிற்சா ங்கள் அச்ச ங்குமணிச நில்நுட்பம் நித் தூப் ராண்மைப	லை–இரும நடித்தல்–ட ள்–எலும் மபின் மு ம்ற்றும் சே	ம்பை சூர் மணி துண் நக்கியத்த வளாண் எ	க்குதல், யாக்கும் ெ எடுகள்–தொல் வம் – கா மைச் சார்ந்த	3 எஃகு–வரலாற்று தாழிற்சாலைகள் லியல்சான்றுகள் 3 ல்நடைபராமரிப்பு செயல்பாடுகள் பஅறிவு–அறிவுசா
கலை. அலகு 3 கப்பல்கட்டும் சான்றுகளாக கல்மணிகள், சிலப்பதிகாரத் அலகு 4 அணை, ஏரி கால்நடைகளு கடல்சார் அறி சமூகம்.	உற்பத்தித் தொழில்நுட்பம் கலை—உலோகவியல்—இரும்புத் செம்புமற்றும் தங்கநாணயங்கள்—நாணய கண்ணாடிமணிகள்—சுடுமண் மணிகள்—ச தில்மணிகளின் வகைகள். வேளாண்மைமற்றும் நீர்ப்பாசனத் தொரு , குளங்கள், மதகு—சோழர்காலக் குமி க்காகவடிவமைக்கப்பட்ட கிணறுகள்—வே வ்டி—மீன்வளம் — முத்து மற்றும் முத்துக்கு	தொழிற்சா ங்கள் அச்ச ங்குமணிச நில்நுட்பம் நித் தூய் ராண்மைப நளித்தல்—(லை–இரு ஈடித்தல்–ட ள்–எலும் பபின் மு ற்றும் சே	ம்பை உரும மணி உரு நடித் துண் நக்கியத்த வளாண் எ _ல் குறித்	க்குதல், வாக்கும் ெ எடுகள்–தொல் வம் – கா மைச் சார்ந்த தே பண்டைய	3 எஃகு–வரலாற்று தாழிற்சாலைகள் வியல்சான்றுகள் 3 ல்நடைபராமரிப்பு செயல்பாடுகள் பஅறிவு–அறிவுசா
கலை. அலகு 3 கப்பல்கட்டும் சான்றுகளாக கல்மணிகள், சிலப்பதிகாரத் அலகு 4 அணை, ஏரி கால்நடைகளு கடல்சார் அறி சமூகம். அலகு 5	உற்பத்தித் தொழில்நுட்பம் கலை—உலோகவியல்—இரும்புத் செம்புமற்றும் தங்கநாணயங்கள்—நாணய கண்ணாடிமணிகள்—சுடுமண் மணிகள்—ச தில்மணிகளின் வகைகள். வேளாண்மைமற்றும் நீர்ப்பாசனத் தொரு , குளங்கள், மதகு—சோழர்காலக் குமி க்காகவடிவமைக்கப்பட்ட கிணறுகள்—வே வ்டி—மீன்வளம் — முத்து மற்றும் முத்துக்கு	நொழிற்சாஎ ங்குமணிச நில்நுட்பம் நித் துாப் நளித்தல்—(லை–இரு ஈடித்தல்–ட ள்–எலும் பபின் மு ற்றும் சே	ம்பைஉரு மணிஉரு நபுத் துண் நக்கியத்து வளாண் டல் குறித்	க்குதல், வாக்கும் ெ எடுகள்–தொல் வம் – கா மைச் சார்ந்த தே பண்டைய	3 எஃகு–வரலாற்று தாழிற்சாலைகள் லியல்சான்றுகள் 3 ல்நடைபராமரிப்பு செயல்பாடுகள் அறிவு–அறிவுசா 3 ன்பதிப்புசெய்தல்



MAHENDRA ENGINEERING COLLEGE

Autonomous | Accredited by NAAC with 'A++' Grade (Cycle-2)
Accredited by NBA Tier-I (WA) UG: CSE, ECE, EEE
fahendhirapuri, Mallasamudram (W), Namakkal (Dt) - 637 503, Tamil Nadu
04288-288 500 / 521 / 522 | www.mahendra.info



Regulations 2024

Semester - II

(Common to all B.E./ B.Tech. Programmes)

Course code	Course Name	Pe	eriods/v	veek	Credit	Maximun marks	
24HS11003	TAMILS AND TECHNOLOGY	L	T	P	C	100	
		1	0	0	1		
UNIT-I	WEAVING AND CERAMIC TECHNO	DLOG	Y			3	

Weaving Industry during Sangam Age - Ceramic technology - Black and Red Ware Potteries (BRW) - Graffiti on Potteries.

UNIT-II HERITAGE - ROCK ART PAINTINGS TO MODERN ART – SCULPTURE

Designing and Structural construction House & Designs in household materials during Sangam Age - Building materials and Hero stones of Sangam age - Details of Stage Constructions in Silappathikaram - Sculptures and Temples of Mamallapuram - Great Temples of Cholas and other worship places - Temples of Nayaka Period - Type study (Madurai Meenakshi Temple)-ThirumalaiNayakarMahal - Chetti Nadu Houses, Indo - Saracenic architecture at Madras during British Period.

UNIT-III MANUFACTURING TECHNOLOGY 3

Art of Ship Building - Metallurgical studies - Iron industry - Iron smelting, steel -Copper and gold-Coins as source of history - Minting of Coins - Beads making-industries Stone beads - Glass beads - Terracotta beads - Shell beads/ bone beats - Archeological evidences - Gem stone types described in Silappathikaram.

UNIT-IV AGRICULTURE AND IRRIGATION TECHNOLOGY 3

Dam, Tank, ponds, Sluice, Significance of KumizhiThoompu of Chola Period, Animal Husbandry - Wells designed for cattle use - Agriculture and Agro Processing - Knowledge of Sea - Fisheries - Pearl - Conche diving - Ancient Knowledge of Ocean - Knowledge Specific Society.

UNIT-V SCIENTIFIC TAMIL & TAMIL COMPUTING 3

Development of Scientific Tamil - Tamil computing - Digitalization of Tamil Books - Development of Tamil Software - Tamil Virtual Academy - Tamil Digital Library - Online Tamil Dictionaries - Sorkuvai Project.

TOTAL HOURS 15

1.	தமிழகவரலாறு–மக்களும் பண்பாடும் – கே.கே. பிள்ளை (வெளியீடுதமிழ்நாடுபாடநூல்மற்றும் கல்வியியல்பணிகள்கழகம்)
2.	கணினித் தமிழ்–முனைவர் இல. சுந்தரம் (விகடன் பிரசுரம்)
3.	கீழடி—வைகைநதிக்கரையில்சங்ககாலநகரநாகரிகம் (தொல்லியல்துறைவெளியீடு)
4.	பொருநை—ஆற்றங்கரைநாகரிகம் (தொல்லியல்துறைவெளியீடு)
5.	Social Life of Tamils (Dr.K.K.Pillay) A joint publication of TNTB & ESC and RMRL – (in print)
6.	Social Life of the Tamils - The Classical Period (Dr.S.Singaravelu) (Published by: International Institute of Tamil Studies.
7.	Historical Heritage of the Tamils (Dr.S.V.Subaramanian, Dr.K.D. Thirunavukkarasu) (Published by: International Institute of Tamil Studies).
8.	The Contributions of the Tamils to Indian Culture (Dr.M.Valarmathi) (Published by: International Institute of Tamil Studies.)
9.	Keeladi - 'Sangam City Civilization on the banks of river Vaigai' (Jointly Published by: Department of Archaeology & Tamil Nadu Text Book and Educational Services Corporation, Tamil Nadu)
10	Studies in the History of India with Special Reference to Tamil Nadu (Dr.K.K.Pillay) (Publishedby: The Author)
11.	Porunai Civilization (Jointly Published by: Department of Archaeology & Tamil Nadu Text Bookand Educational Services Corporation, Tamil Nadu)
12.	Journey of Civilization Indus to Vaigai (R.Balakrishnan) (Published by: RMRL) - Reference Book.

Cou	ırse		Но	urs/W	'eek	Credit	Maximum						
Co	ode	Course Name	L	T	P	C	marks						
24	PY22001	Physics Laboratory (For All Branches)	0	0	3	1.5	100						
Objective(s)		To provide exposure to the students wit practices for all branches.	h hands o	on expe	erience	on various	basic Physics						
		LIST OF EXPERIM	ENTS										
1		nation of Wavelength, and particle size using ination of acceptance angle in an optical fiber											
2		on of velocity of sound and compressibility of		- Ultra	sonic i	nterferomet	er.						
3	Determination of Thickness of a thin wire-Air Wedge												
4	Determinati	Determination of wavelength of mercury spectrum – spectrometer grating											
5	Determinati	on of Young's modulus by Non uniform bene	ding meth	nod									
6	Determinati	on of viscosity of liquid – Poiseuilles method	1										
7	Determinati	on of Rigidity modulus -Torsional Pendulum	-										
8	Determinati	on of Band gap of a semiconductor-PN Diod	e										
9		on of Young's modulus by Uniform bending y 7 Experiments)	method										
		* *	,	Total	hours	45							
Outcome(s)	p • A ri • D	Apply experimental techniques to measure fur particle size, and material constants using optionally and interpret experimental data to design gightly modulus, and viscosity of fluids throus Demonstrate proficiency in performing semical electrical and acoustic properties of materials.	cs and matermine n gh approp	echani nechan priate i	cal me ical pr nstrun	thods. operties likenentation.	e Young's modulus						
REFEREN													
1	-	ratory Manual (2023), Department of Physics			gineer	ing College	, Namakkal.						
2		B.Sc Practical Physics, 5th Edn. (2015), R. (ad NY	Dell.!							
3		3.Sc. Practical Physics (2001), S. Chand and and Pamekrishna, A. K. Iba (2012), A. Tayt					Mohal New Dalhi						
5	Indu Prakash and Ramakrishna, A. K. Jha (2012), A Text Book of Practical Physics, Kitab Mahal, New Del D. P. Khandelwal, A Laboratory Manual of Physics: For Undergraduate Classes (1985), Vani Educational books, New Delhi.												

PO CO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	1	3	1	1	1	1	1	1	1	1	1	3	1	3
CO2	3	1	3	1	1	1	1	1	1	1	1	1	3	1	3
CO3	1	3	1	1	1	1	1	1	1	1	1	1	1	3	1

Co	urse	C	Ho	urs/W	'eek	Credit	Maximum						
Co	ode	Course Name	L	T	P	C	marks						
24	CS23001	Problem Solving Techniques Using C Laboratory (Common to All Branches)	0	0	3	1.5	100						
Objective(s)			derstand developing applications using Office package. mulate problems and implement algorithms using Scratch and Raptor tool ke use of arrays and functions in C. arn how to use pointer concepts.										
		LIST OF EXPERIM											
1	The Same To	io-data Using MS Word With Appropriate Pa o Recipients Using Mail Merge											
2	Create budge	et planning of your family with cell referencing	g, formul	ae, cor	ndition	al formattir	ng using Excel						
3	Create a Prog	gram flow to illustrate the use of Variables and	Constan	ts usir	ng Scra	tch Tool							
4	Construct flo	owchart to find the Factorial for a given number	er Using	Rapto	r								
5	Students man	k generation using decision statements											
6	Calculator us	sing switch statement											
7	Prime number	er generation and to check whether the given n	umber is	armst	rong o	r not using	looping						
8	Greatest nun	nber using array (one dimensional)											
9	Matrix multi	plication using array (two dimensional)											
10	Check the gi	ven string is palindrome or not.											
11	Write a C Propointer	rogram to swap two numbers using two functi	ions one	using	pointe	r and other	one without using						
12	Factorial cale	culation and Fibonacci series using function											
13	Student mark	s sheet using structures											
14	Copy text fro	om one file to other File											
			,	Γotal	hours	30							
Outcome(s)	DemonsSolve thDevelop	Upon completion of this course , students will be able to • Demonstrate the applications of Office Packages • Solve the real world problems using Scratch and Raptor Tool • Develop programs using arrays and functions in C. • Illustrate the working of pointers in C											

PO CO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	2	1	1	1	1	2	-	-	-	-	-	-	-
CO2	3	3	3	2	1	1	1	2	-	-	-	-	-	-	-
CO3	3	3	3	2	2	1	2	3	-	-	-	-	-	-	-
CO4	3	3	3	3	2	1	2	3	-	-	-	-	-	-	-
CO5	3	3	3	3	2	1	2	3	-	-	-	-	-	-	-

Course code	Course Name	Ho	ours/w	eek	Credit	Maxi	mum marks
24GE23001	Engineering Practices	L	Т	P	С		100
24GE23001	Laboratory	0	0	3	1.5		100
Objective(s)	 To understand the fundamentals of various carpentry joints. To understand the basic manufacturing lathe and drilling operations. To learn the concepts of electrical wiring To study the concepts of electronic devices. 	proces	sses and	d perfo	rm simple		
LIST OF EXP	ERIMENTS						
	Civil and Mechanical En	ıgineeı	ring Pr	actice	es		
	carpentry joints T-joint, Lap-joint, Dovetail Jetions with different joining components.	oint					CO1
•	s of Two Galvanised Iron Pipe						
	of arc welding of butt joints, lap joints and te	e ioints	S.				CO2
•	of sheet metal tray and funnel	J					
	n turning and step turning using lathe						
7. Drilling ope							
	Electrical and Electronic	c Engi	neerin	g Prac	ctices		
1. Residential	House Wiring using Switches, Fuse, Indicate	or, Lam	p and E	nergy	meter		CO3
•	CFL and LED Lamp Wiring						
	nt of Voltage, Current and Power						
	nt of Energy using Single Phase Energy Mete						
•	ractice –Assembly of Electronic Components	S					CO4
	of Logic Gates						
	eristics of PN Junction and Zener Diode						
8. Half Wave	and Full Wave Rectifiers						
						Tot	tal hours: 30
Outcome(s)	 At the end of the course, students will be a Acquire the knowledge about Plumbing pipes. Fabricate the models of sheet metal and turning and drilling operations. Demonstrate the domestic wiring and p 	g & Car l weldir	pentry	s and F			
	Demonstrate the operation of Electric C				on Diode.		

PO CO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12
CO1	1	-	-	3	1	-	-	-	-	1	-	1
CO2	1	-	-	3	1	-	-	-	-	1	-	1
CO3	1	2	-	3	1	-	-	-	-	1	-	1
CO4	1	2	-	3	1	-	-	-	-	1	-	1
Avg.		2	-	3	1	-	-	-	-	1	-	1

Course code	Course Name	Но	urs/we	eek	Credit	M	aximum marks
	Transforms and Partial Differential	L	Т	P	С		100
24MA12301	Equations	3	1	0	4		100
Objective(s)	ics of I	operties and apply Fourier series. blems using Fourier					
UNIT-I	Z -Transforms and Difference Equation						9+3
	entary properties – Inverse Z-transform – Pace equations – Solution of difference equat					od-Coi	nvolution theorem -
UNIT-II	Fourier Transforms						9+3
	rem (without proof) – Fourier transform pa - Convolution theorem – Parseval's identity.		ne and (Cosine	transforms	s – Prop	perties – Transforms
UNIT-III	Fourier Series						9+3
	s – General Fourier series – Odd and even f – Harmonic Analysis.	unction	s – Hal	f range	sine series	– Half	range cosine series
UNIT-IV	Partial Differential Equations						9+3
Formation of partial di	fferential equations – Solutions of standard typ	es of fir	st order	partial	differential	equation	ns – Lagrange's linear
equation – Homogeneo	ous linear partial differential equations of second	and hig	her orde	er with	constant coe	fficients	
UNIT-V	Applications of Partial Differential Equ	ıations					9+3
	ensional wave equation – One dimensional of heat conduction (Insulated edges exclude						
	i of heat conduction (misalated cages energe						an coordinates.
annongronar equation	Tor nour conduction (insulated edges entrac				Total l	nours	60
Outcome(s)	At the end of the course, the students will be Apply the knowledge of Z-transform to Solve the problems using Fourier integer Apply Fourier series techniques in solve Formulate and solve first and higher of Solve real time Engineering problems	o the argral and ving hearder par	alysis of convolution of the con	ution t proble ferentia	al filters ar heorem tec m used in v	nd discr hnique various	ete signals.
	At the end of the course, the students will be Apply the knowledge of Z-transform to Solve the problems using Fourier integer Apply Fourier series techniques in solve Formulate and solve first and higher or	o the argral and ving hearder par	alysis of convolution of the con	ution t proble ferentia	al filters ar heorem tec m used in v	nd discr hnique various	ete signals.
Outcome(s) TEXT BOOK: 1 Dr.P.Kandasa	At the end of the course, the students will be Apply the knowledge of Z-transform to Solve the problems using Fourier integer Apply Fourier series techniques in solve Formulate and solve first and higher or	o the argral and ving her rder parties using F	alysis of convol at flow rtial diff artial d	ution t proble ferentia ifferen	al filters ar heorem tec m used in v al equations tial equatic	nd discr hnique various s.	ete signals.
Outcome(s) TEXT BOOK: 1 Dr.P.Kandasa company Ltd 2 Ramana B.V.	At the end of the course, the students will be Apply the knowledge of Z-transform to Solve the problems using Fourier intege. • Apply Fourier series techniques in solve Formulate and solve first and higher of Solve real time Engineering problems. amy, Dr.K.Thilagavathy and Dr.K.Gunava	o the argral and ving he rder partusing F	nalysis of convol at flow trial diff artial d	ution t proble ferentia ifferen ring M	al filters ar heorem tec m used in v al equations tial equation athematics	nd discr hnique various s. ns.	ete signals. situations. e – III'',S.Chand &
Outcome(s) TEXT BOOK: 1 Dr.P.Kandasa company Ltd	At the end of the course, the students will to Apply the knowledge of Z-transform to Solve the problems using Fourier integonal Apply Fourier series techniques in solve Formulate and solve first and higher of Solve real time Engineering problems army, Dr.K.Thilagavathy and Dr.K.Gunava. New Delhi, 2012.	o the argral and ving he rder partusing F	nalysis of convol at flow trial diff artial d	ution t proble ferentia ifferen ring M	al filters ar heorem tec m used in v al equations tial equation athematics	nd discr hnique various s. ns.	ete signals. situations. e – III'',S.Chand &
Outcome(s) TEXT BOOK: 1 Dr.P.Kandasa company Ltd 2 Ramana B.V. REFERENCES:	At the end of the course, the students will to Apply the knowledge of Z-transform to Solve the problems using Fourier integonal Apply Fourier series techniques in solve Formulate and solve first and higher of Solve real time Engineering problems army, Dr.K.Thilagavathy and Dr.K.Gunava. New Delhi, 2012.	o the argral and ving herder parties using Fundamental thy, "E	convolute flow the convolute flow the convolute flow the convolute flow the convolute flow flow flow flow flow flow flow flow	ution t proble Ferentia ifferen ring M ublishi	al filters ar heorem tec m used in val equations tial equations athematics	nd discr hnique various s. ns.	ete signals. situations. e – III'',S.Chand &
Outcome(s) TEXT BOOK: 1 Dr.P.Kandasa company Ltd 2 Ramana B.V. REFERENCES: 1 Erwin Kreysz	At the end of the course, the students will be Apply the knowledge of Z-transform to Solve the problems using Fourier intege. Apply Fourier series techniques in solve Formulate and solve first and higher of Solve real time Engineering problems army, Dr.K.Thilagavathy and Dr.K.Gunavat. New Delhi, 2012.	o the argral and ving her der parties using Factors, "E	nalysis of convolution of the co	ution t proble ferentia ifferen ring M ublishi	al filters ar heorem tec m used in val equations tial equation athematics ng Company, 2010.	nd discr hnique various s. nns. Volum	ete signals. situations. e – III'',S.Chand &

PO CO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	2	1	-	-	-	-	-	-	-	2	-	-	-
CO2	3	3	2	1	-	-	-	-	-	-	-	2	-	-	-
CO3	3	3	2	1	-	-	-	-	-	-	-	2	-	-	-
CO4	3	3	3	1	-	-	-	-	-	-	-	2	-	-	-
CO5	3	3	3	2	-	-	-	-	-	-	-	3	-	-	-

Course co	de	Course Name	Ho	ours/w	eek	Credit	Maximum marks
		N	L	T	P	С	400
24ME1430	01	Material Science and Metallurgy	3	0	0	3	100
Objective(s)		 To impart knowledge on the structure To understand the advantages of heat To Learn ferrous and non-ferrous mee To understand need and application o To learn powder metallurgy processes 	treatm tals for f polyn	ent and variou	the m s appli	ethod of he cations	eat treatmentprocesses.
UNIT-	-I	Alloys and Phase Diagrams					9
peritectic reacti	ions, iron	olid solutions, substitutional and inters carbon equilibrium diagram. Classific properties and application.					
UNIT-II Heat Treatment							9
Isothermal trans test - Austemp	formation dering, mar	stress relief, recrystallisation and spher liagrams- cooling curves superimposed o tempering – case hardening, carburizi uum and Plasma hardening.	n isoth	ermal c	liagran	n- Harden a	bility, Jominy end quench
UNIT-1	Ш	Ferrous and Non-Ferrous Metals					9
Grey, white, m	alleable, sp Al-Cu –	s on steel- α and β stabilisers— stainles pheroidal — alloy cast irons, Copper a precipitation strengthening treatment —	nd cop	per al	loys -	Brass, B	ronze and Cupronickel -
UNIT-1	IV	Non-Metallic Materials					9
	perties and	r, Properties and applications of various applications of Al2O3, SiC, Si3N4, PSZ Composites.					
UNIT-	V	Powder Metallurgy					9
Powder metallu Applications of	~ .	s, Preparation of powders, Characteris tallurgy	tics of	metal	powd	ers, Mixin	g, Compacting, Sintering
					To	tal hours	45
Outcome	 interpret the phase diagrams of ma Describe the concept of heat treatr Classify and Distinguish different 	ne concept of heat treatment of steels & strengthening mechanisms and Distinguish different types of cast irons, steels and non ferrous alloys pes and manufacturing of polymers and composite materials.					
TEXT BOOK	:						
1		I., "Introduction to Physical Metallurgy",					
2		Callister, "Material Science and Engine					
3	Lawrence H. Van Vlack, "Elements of Material Science and Engineering", Pearson publications, 2011.						

REFERENCES:							
1	Raghavan.V, "Materials Science and Engineering", Prentice Hall of India Pvt. Ltd., 2015.						
2.	Kenneth G.Budinski and Michael K. Budinski, "Engineering Materials", Prentice Hall of India Private Limited. 2019.						
3	Rajput.R.K "Material Science and Engineering", SK Kataria & Sons, 2009.						

PO CO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	_	_	_	_	1	_	_	_	-	-	1	-	3	-
CO2	3	_	_	_	_	1	_	_	_	-	-	1	_	3	-
CO3	3	-	-	-	-	1	-	-	-	-	-	1	-	3	-
CO4	3	_	_	_	_	1	_	_	_	_	_	1	_	3	-
CO5	3	-	-	-	-	1	-	-	-	-	-	1	-	3	-

Course code	Course Name	Н	ours/w	eek	Credit	Maximum ma	rks
24ME14302	Manufacturing Processes	L	T	P	C	100	
24WIE143U2	Wandiacturing Trocesses	3	0	0	3	100	
Objective(s)	 To illustrate the working princip To learn and apply the working principle To analyse the working principles To learn the working principles To study and practice the working 	principles of but of sheet	es of valle defo	arious rmatio formin	metal joining n of metals. g process.		
UNIT-I	Metal Casting Processes				-		9
testing – Cores –Ty Furnaces; Principle	nd Mould – Type of patterns - Pattern ypes and applications – Moulding machi of special casting processes : Shell - in less – Stir casting; Defects in Sand casting	nes– T	ypes an	d appl	ications, Me	lting furnaces: Blast	and Cupola
UN11-11	Metal Joining Processes						9
TIG, MIG, Submer	cesses - Arc welding equipments - Electinged, Plasma arc welding, Laser beam - Gas welding - Equipments used - Full Weld defects.	welding	g proce	sses. S	Solid state w	elding –Friction, Ex	plosive and
UNIT-III	Metal Forming Processes						9
	ion of rolling processes- Rolling mill- e forming- electromagnetic forming- Ele					lling defects. Formin	g: Forming
	ion of rolling processes- Rolling miller forming- electromagnetic forming- Ele Theory of Metal Cutting and Sheet	ctro hy	draulic	formi		lling defects. Formin	g: Forming 9
methods- Explosive UNIT-IV Material removal p Cutting tool materi	e forming- electromagnetic forming- Ele	Metal p forma h- Cutt	draulic Formination- Sing flui	forming ingle a	ng. and multi-poeet metal ch	oint cutting- Orthogonaracteristics – Typic	9 nal cutting-
methods- Explosive UNIT-IV Material removal p Cutting tool materi	Theory of Metal Cutting and Sheet rocesses- Types of machine tools- Chipals- Tool wear- Tool life- Surface finish	Metal p forma h- Cutt	draulic Formination- Sing flui	forming ingle a	ng. and multi-poeet metal ch	oint cutting- Orthogonaracteristics – Typic	9 nal cutting-
methods- Explosive UNIT-IV Material removal p Cutting tool materi bending and drawin UNIT-V Lathe: Specification	Theory of Metal Cutting and Sheet rocesses- Types of machine tools- Chipals- Tool wear- Tool life- Surface finish operations – Stretch forming operation	Metal p forma h- Cutti ns – Fo	draulic Formination- Sing fluirmabili	forming lingle a dsSh ty of s	and multi-po eet metal ch heet metal –	pint cutting- Orthogonaracteristics – Typic Test methods. Principle of capstan	9 nal cutting al shearing
methods- Explosive UNIT-IV Material removal p Cutting tool materi bending and drawin UNIT-V Lathe: Specification	Theory of Metal Cutting and Sheet rocesses- Types of machine tools- Chip als- Tool wear- Tool life- Surface finish ag operations – Stretch forming operation Turning and Hole Making ns of centre lathe- Operations performe	Metal p forma h- Cutti ns – Fo	draulic Formination- Sing fluirmabili	forming lingle a dsSh ty of s	and multi-po eet metal ch heet metal –	pint cutting- Orthogonaracteristics – Typic Test methods. Principle of capstan	9 nal cutting al shearing
methods- Explosive UNIT-IV Material removal p Cutting tool materi bending and drawin UNIT-V Lathe: Specification	Theory of Metal Cutting and Sheet rocesses- Types of machine tools- Chip als- Tool wear- Tool life- Surface finish ag operations – Stretch forming operation Turning and Hole Making ns of centre lathe- Operations performe	methods of welching pro	Formination- Sing fluitremability and calling produced to cold voicesses	forming lingle a dsSh ty of s s and a Other asting cocesse workin and m	and multi-poeet metal cheet metal — attachments- Hole – Mak defects. s used for g methods of ake simple s	oint cutting- Orthogonaracteristics — Typic Test methods. Principle of capstaining Operations. Total hours industrial fabrication f metals. theet metal components	9 nal cutting al shearing 9 n and turrer 45 n process.
methods- Explosive UNIT-IV Material removal p Cutting tool materi bending and drawin UNIT-V Lathe: Specification lathes. Hole making	Theory of Metal Cutting and Sheet Trocesses- Types of machine tools- Chipals- Tool wear- Tool life- Surface finish ag operations – Stretch forming operation Turning and Hole Making In sof centre lathe- Operations performed: drilling – Introduction, Reaming, Borium et al. Select the different types et al. Summarize various hot work explain the sheet metal form et outline the construction feat	methods of welching pro	Formination- Sing fluitremability and calling produced to cold voicesses	forming lingle a dsSh ty of s s and a Other asting cocesse workin and m	and multi-poeet metal cheet metal — attachments- Hole – Mak defects. s used for g methods of ake simple s	oint cutting- Orthogonaracteristics — Typic Test methods. Principle of capstaining Operations. Total hours industrial fabrication f metals. theet metal components	9 nal cutting al shearing 9 n and turre 45 n process.
methods- Explosive UNIT-IV Material removal p Cutting tool materi bending and drawin UNIT-V Lathe: Specification lathes. Hole making Outcome(s)	Theory of Metal Cutting and Sheet Trocesses- Types of machine tools- Chipals- Tool wear- Tool life- Surface finish ag operations – Stretch forming operation Turning and Hole Making In sof centre lathe- Operations performed: drilling – Introduction, Reaming, Borium et al. Select the different types et al. Summarize various hot work explain the sheet metal form et outline the construction feat	methods of welching produces an	draulic Formination- Sing fluitremability essories oping — s and calling pr d cold vocesses d opera	forming single a dsSh ty of s s and a Other asting o ocesse workin and m ations p	and multi-poeet metal cheet metal — attachments- Hole – Mak defects. s used for seg methods of ake simple segret or metal attachments-	oint cutting- Orthogonaracteristics – Typic Test methods. Principle of capstaring Operations. Total hours industrial fabrication f metals. theet metal componentathe and drilling	9 nal cutting al shearing 9 n and turre 45 n process.
Material removal p Cutting tool materi bending and drawin UNIT-V Lathe: Specification lathes. Hole making Outcome(s) TEXT BOOL Sharma, P.C.	Theory of Metal Cutting and Sheet Theory of Metal Cutting and Sheet Trocesses- Types of machine tools- Chipals- Tool wear- Tool life- Surface finish ag operations – Stretch forming operation Turning and Hole Making In sof centre lathe- Operations performed: drilling – Introduction, Reaming, Borium established by Select the different types established by Summarize various hot work explain the sheet metal form established by Outline the construction feat K: "A Text Book of Production Technology thury S.K. and Hajra Choudhury A.K., ""	methods of welching pro-	draulic Formination- Sing fluit rmabilit rmabili	forming lingle a dsSh ty of s s and a Other asting cocesse workin and m ations p	and multi-poeet metal cheet metal — attachments- Hole — Mak defects. s used for g methods o ake simple sperformed in	oint cutting- Orthogonaracteristics — Typic Test methods. Principle of capstaring Operations. Total hours industrial fabrication f metals. Theet metal componentathe and drilling , 2004.	9 nal cutting al shearing 9 n and turre 45 n process. nts.
Material removal p Cutting tool materi bending and drawin UNIT-V Lathe: Specification lathes. Hole making Outcome(s) TEXT BOOL Sharma, P.C. Hajra Choud Publications,	Theory of Metal Cutting and Sheet Theory of Metal Cutting and Sheet Trocesses- Types of machine tools- Chipals- Tool wear- Tool life- Surface finish ag operations – Stretch forming operation Turning and Hole Making In sof centre lathe- Operations performed: drilling – Introduction, Reaming, Borium established by Select the different types established by Summarize various hot work explain the sheet metal form established by Outline the construction feat K: "A Text Book of Production Technology thury S.K. and Hajra Choudhury A.K., ""	methods of weld wing produces an egy", S.C.Elemen	draulic Formin Ation- Sing fluit Trabilic Essories Esping — Sand cat	forming lingle a dsSh ty of s s and a Other asting cocesse workin and m ations p	and multi-poeet metal cheet metal — attachments- Hole — Mak defects. s used for g methods o ake simple so performed in mpany, Ltd., arring Techn	oint cutting- Orthogonaracteristics – Typic Test methods. Principle of capstaring Operations. Total hours industrial fabrication f metals. theet metal componentathe and drilling , 2004. ology Vol. I'', Media	9 nal cutting al shearing 9 n and turre 45 n process. nts.

REFE	REFERENCES:							
1	Rao P.N., Manufacturing Technology Vol. I, Foundry, Forming and Welding, TMH, 5 th Edition, 2018.							
2	Rao P.N., Manufacturing Technology Vol. II, Metal cutting and Machine Tools, McGraw-Hill Education, 4 th Edition, 2018.							
3	Kalpakjian S., "Manufacturing Engineering and Technology", Pearson Education India Edition, 8th Edition, 2020.							

PO CO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	3	_	_	3	3	_	-	-	-	3	3	3	-
CO2	3	2	3	2	3	-	2	-	3	-	-	2	3	3	-
CO3	3	2	3	2	3	-	2	-	3	-	-	2	3	3	-
CO4	3	2	3	2	3	-	2	-	3	-	-	2	3	2	-
CO5	3	-	2	-	-	-	-	-	1	2	-	2	3	2	-

Course code	Course Name	Н	ours/w	eek	Credit	Maxin	num marks		
		L	Т	P	С				
24ME14303	Strength of Materials	3	0	0	3		100		
Objective(s)	 To understand the fundamental coexternal loading. To learn about the transverse loading. To learn about the deformation of some thousand the various method. To learn about the various stresses and the various stresses are stresses. 	ng and shafts a s for ca	bendin and spri	g loads ngs sub ng defle	acting on s jected to to ection of be	tructural consion.	mponents.		
UNIT-I	Stress, Strain and Deformation of Solids 9								
Thermal stresses in si energy- gradually app	Types of basic stresses - Factor of safety- mple and compound bar- Poisson's ratio, vollied, suddenly applied and impact loads.	olumet	ric strai	in, relat		_	constants- strain		
UNIT-II	Transverse Loading on Beams and Stres						9		
simple bending – a	apports and Loads, Shear force and ben assumptions - Shear stress distribution Γ sections and I section.	_		_			•		
UNIT-III	Torsion						9		
Twist and torsion stiff	f circular bars — Shear stress distribution — fness — Compound shafts —Power transmitted d- Leaf springs- elliptical and semi elliptical	d .Heli	cal spri	ings -op			* *		
UNIT-IV	Deflection						9		
	pes and deflections of determinate beatl, Columns and struts— Euler equation and		-		-		•		
UNIT-V	Analysis of Stresses In Two Dimensions						9		
planes of maximum s	nt –normal and tangential stresses on a give hear stress, analytical method and Mohr's c e-changes in dimensions and volume.	_	_	_	_	_	_		
					Total hour	'S	45		
	 After successful completion of the course, t Explain the Basic concepts of stress Analyze beams to determine shear f be in a position to assess the behavior 	and str	ain in o bendin	of solid g mom	s. ents and ax				
 Outcome(s) Design shafts to transmit required power and springs for its maximum energy storage capac Evaluate the slope and deflection of beams and buckling loads of columns under different bo conditions. Analysis of Stresses in two dimensions in principal stresses, principal strains and Stress thin cylindrical and spherical shells under internal pressure. 							ifferent boundary		
TEXT BOOK:									
1. Bansal R.l	K. "A Text Book of Strength of materials, L	axmi F	Publicat	ions (P), New Dell	ni, 6th Editio	on, 2022.		
2. Ferdinand Eight Edit	Beer, E. Johnston, John DeWolf and David ion, 2020	Mazui	rek Me	chanics	of Materia	s", McGrav	v-Hill Book Co,		

3.	R.K.Rajput, ,"Strength of Materials", S.Chand Publications, 2015.
4.	Jindal U.C., "Strength of Materials", Asian Books Pvt. Ltd., New Delhi, 2012.
REFERI	ENCES:
1.	Popov E.P, "Engineering Mechanics of Solids", Prentice-Hall of India, New Delhi, 2015.
2.	Strength of materials by S.Ramamrutham, Dhanpat Rai & Co. (P) Ltd, 2014.
3.	Subramanian R, "Strength of materials", Oxford University Press, New Delhi, 2 nd Edition 2011

PO CO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	3	3	2	1	-	1	2	-	-	1	2	2	-
CO2	3	3	3	3	2	1	-	1	2	-	-	1	2	2	-
CO3	3	3	3	3	2	1	-	1	2	-	-	1	2	2	-
CO4	3	3	3	3	2	1	-	1	2	-	-	1	2	2	-
CO5	3	3	3	3	2	1	-	1	2	-	-	1	2	2	-

Course code	Course Name	Hours/week C			Credit	Maximum n	narks
24ME14304	Engineering Thermodynamics	L	T	P	С	10	0
2401214304	Engineering Thermodynamics	3	0	0	3	10	o .
Objective(s)	 To understand principles of thermod simple physical systems. To provide an in-depth study of thermodynamic relations, Principle of To enlighten the basic concepts of value. To understand the various gas laws mixtures in estimating enthalpy, entr 	thern of Psyc apour p and ec	nodyna hometr ower c	amic ric and cycles s of s	principles, d Properties state and ap	thermodynamics s of pure substance oply them to solve	of state, basic s.
UNIT-I	Basic Concept and First Law						9
thermodynamics. La	nermodynamic systems - closed, open a w of conversion of energy. – Concept of pplication to closed and open systems, st ics.	f tempe	rature	and l	neat. Molar	specific heat of a	gas. First law of
UNIT-II	Second Law						9
Second law of thern	nodynamics - Kelvin's and Clausius sta	tement	s of se	econd	law. Reve	rsibility and irreve	rsibility. Carnot
	le, reversed Carnot cycle, efficiency, COl				py, entropy	of ideal gas.	
UNIT-III	Properties of Pure Substance and Ste bstances – Thermodynamic properties of						9
T-V, T-S, H-S diagr processes. Standard	ams, PVT surfaces, thermodynamic prop Rankine cycle and Reheat cycle.	perties	of stea	m. C			ugh a non- flow
UNIT-IV	Ideal and Real Gases and Thermodyn operties ideal and real gases, equation				Low Vos	der Weel's equet	9
_	or— Dalton's law of partial pressure, T-I		_			•	
Joule –Thomson coe	• •	TCIati	0113, IV	ıax w (on s relation	ns, Clausius Ciape	yron equations,
UNIT-V	Psychrometry						9
	sychometric charts, property calculations	s of air	vapou	ır mix	ctures. Psyc	chometric process	
	Latent heat exchange processes. Adiabat				•		
						Total hours	45
Outcome(s)	 Describe the basic concepts of therm Solve the problems by using the second Calculate the thermodynamic propert Distinguish the behavior of real & identification Apply the psychometric concepts in the property of the psychometric concepts in the psychological property of the psychological p	ond law ties of p eal gas	of the pure su es and	rmod Ibstan deriv	ynamics. ices using tl	ne steam table.	
TEXTBOOK:							
1 P.K.Nag, "F	Engineering Thermodynamics", TMH, No	ew Del	hi, 201	3			
-	"Engineering Thermodynamics" Laxmi				Delhi,2010)	
31	engel and Michale A Boles, Thermodyna						2002
REFERENCES:			8		<u> </u>	, = , -	
	, "Thermodynamics", 3 rd Ed. McGraw-H	ill, 199	5.				
2. Arora C.P, "	Thermodynamics", Tata McGraw-Hill, N	New De	lhi, 20	03.			
	other, Craig W, Somerton, "Thermodynan				", Schaum	Outline Series, Tata	a McGraw-Hill,

PO CO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	_	_	-	_	1	1	_	-	_	_	1	_	-	3
CO2	2	3	-	-	-	1	1	-	-	-	-	1	-	-	3
CO3	2	3	-	-	-	1	-	-	-	-	-	-	-	-	3
CO4	1	2	3	-	-	1	-	-	-	-	-	-	-	-	3
CO5	2	3	-	-	-	1	1	-	-	-	-	1	-	-	3

Course code	Course Name	Но	ours/w	eek	Credit	M	Maximum marks	
	Environmental Science and	L	T	P	С			
24CY11001	Sustainability	2	0	0	0		100	
	To make the students familiar with:							
Objective(s)	 The importance of Environment and E The basic concepts of biodiversity and The causes, effects and prevention me The social issues of the environment a The concept of sustainable development and social aspects of sustainability, re 	d emphaeasures of and National Control	size on of envir ional la s and ap	onmen ws for oprecia	tal pollution	n. it prote	ction.	
UNIT-I	Environment & Ecosystem						9	
tructure and function	d Importance of Environment – Need for on of an ecosystem – energy flow in the nof the terrestrial (Forest and Grass land)	ne ecosy	stem -		•		-	
UNIT-II	Biodiversity and Its Conservation						9	
liversity nation – h	ction – definition - genetic, species and econot-spots of biodiversity – threats to bioversity: In-situ and ex-situ conservation of	odiversi	ty – er	ndange	red and en	demic		
UNIT-III	Environmental Pollution						9	
nanagement: causes	effects and control measures of: (a) A , effects and control methods of municipal ividual in prevention of pollution – pollution	al solid	wastes	– E-w	aste and p	lastic v		
UNIT-IV	Social Issues & Environmental Impact	t Assess	ment				9	
Social issues – Clim	ate change, global warming, acid rain, ozo ion act - EIA: EIA structure- methods of ba							
Environment protecti	aspects of EIA - methods for impact identif		•				anagement of impe	
Environment protecti tudies - operational a	aspects of EIA - methods for impact identif Sustainability and Management	fication.					6	
Environment protection tudies - operational studies - UNIT-V Development , GDP sunsustainability to su	Sustainability and Management ,Sustainability- concept, needs and challengestainability - millennium development goal.	ges - eco	onomic		ainable De	velopm	6 stainability - from nent Goals - targets	
Environment protectistudies - operational substitution UNIT-V Development , GDP substitution unsustainability to su	Sustainability and Management ,Sustainability- concept, needs and challengestainability - millennium development goalention areas.	ges - ecols, and p	onomic			velopm	6 stainability - from	
Environment protectistudies - operational a UNIT-V Development , GDP	Sustainability and Management ,Sustainability- concept, needs and challengestainability - millennium development goal.	ges - ecols, and per able to the varion and be essential inable disconnected.	onomic protocol ypes of iety of a e familial legisla	Ecosynnimals ar with ation o	Total hastem. s, plants and control men environm	nours I micro easures ental la	6 stainability - from nent Goals - targets 45 obial species.	
Environment protective tudies - operational and tudies - operational and tunitary to sum of the sum	Sustainability and Management Sustainability-concept, needs and challengestainability - millennium development goal ention areas. At the end of the course the student will be Explain the importance of Environme Classify the biodiversity and measure Identify the different types of Pollutio List out the environmental issues and Recognize the different goals of susta	ges - ecols, and per able to the varion and be essential inable disconnected.	onomic protocol ypes of iety of a e familial legisla	Ecosynnimals ar with ation o	Total hastem. s, plants and control men environm	nours I micro easures ental la	6 stainability - from nent Goals - targets 45 obial species.	

	Chennai, 2014.
4	Allen, D. T. and Shonnard, D. R., Sustainability Engineering: Concepts, Design and Case Studies, Prentice Hall.
REFE	RENCES:
	R.K. Trivedi, "Handbook of Environmental Laws, Rules, Guidelines, Compliances and Standards", Vol. I and II, Enviro Media.
2	Gilbert M.Masters, "Introduction to Environmental Engineering and Science", 3 nd Edition, Pearson Education, 2023.
3	Dharmendra S. Sengar, "Environmental law", Prentice hall of India PVT LTD, New Delhi, 2007.

PO CO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	-	-	-	-	1	2	2	-	-	-	1	-	-	-
CO2	2	-	-	-	-	1	2	-	-	-	-	1	-	-	-
CO3	3	-	-	-	-	2	3	-	-	-	-	1	-	-	-
CO4	3	-	-	-	-	2	3	-	-	-	-	1	-	-	-
CO5	3	-	-	-	-	2	3	-	-	-	-	1	-	-	-

Cor	urse		Hou	ırs/W	'eek	Credit	Maximum
Co	ode	Course Name	L	T	P	C	marks
24ME	224301	Strength of Materials Laboratory	0	0	3	1.5	100
Objective(s)		 To supplement the theoretical knowledge testing for determining the strength of would enable the student to have a clear stiffness. To expose the students to the testing of forces and determination of their characteric 	materia r under	als un estandi ent m	ider ex ng of aterial	tternally ap the design	oplied loads. This for strength and
		LIST OF EXPERIMEN	NTS				
1	Tension	test on a mild steel rod					
2	Double s	hear test on mild steel					
3	Torsion t	est on mild steel rod					
4	Impact to	est on metal specimen					
5	Hardness	s test on metals - Brinnell and Rockwell Hardness					
6	Deflection	on test on cantilever beam					
7	Deflection	on test on simply supported beam.					
8		sion test on open coiled helical springs					
9		sion test on closed coil helical springs					
10	Test on C	Cement					
11	Verificat	ion of Maxwell's reciprocal theorems.					
			7	Γotal	hours	45	
LIST OF E	QUIPME	NTS					
1	Universa	l Tensile Testing machine with double Shear attach	ment –	1 No			
2	Torsion	Testing Machine -1 No.					
3	Impact T	esting Machine -1 No.					
4		Iardness Testing Machine -1 No.					
5	Rockwel	l Hardness Testing Machine -1 No.					
6	Spring T	esting Machine for tensile and compressive loads -	1 No.				
7		lier's apparatus -1 No.					
8		pparatus -1 No.					
9	Mortar c	ube moulds- 5 Nos.					
Outcome(s)		 The students will have the required knowledge components of structural elements experiment 		e area	of testi	ing of mate	rials and

PO CO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	_	_	3	-	_	-	3	1	-	-	3	3	1	-
CO2	2	-	-	3	-	-	-	3	1	-	-	3	3	1	-
CO3	2	-	-	3	-	-	-	3	1	-	-	3	3	1	-

Course code	Course Name	Но	urs/w	eek	Credit	Maximum marks							
24141524202	Computer Aided Machine	L	T	P	C	100							
24ME24302	Drawing Laboratory	1	0	2	2	100							
	To make the students understandab	le on dr	awings	of mac	hine compo	onents as per standard.							
Objectives	• To familiarize the students w components.	ith Inc	lian s	tandard	ls on dra	wing practices of engineering							
	•	To gain practical experience in 3D part, assembly modeling and drafting using design tool.											
UNIT-I	Introduction to machine drawing 4												
	sentation of common machine elements sections – Parts not usually sectioned.	such as	screws	, bolts,	nuts, keys	, gears, bearings, couplings, webs,							
UNIT-II	Production Drawing					4							
	e Components and Assemblies; Fasteners Work holding devices, IC Engines Comp		ints. Bo	olts & N	luts, Cotter	joints and couplings. Assemblies –							
UNIT-III	Two Dimensional Drafting					7							
Two dimensional	modeling and drafting.												
UNIT-IV	Three Dimensional Modeling					15							
Three Dimensional	Modeling of Bearings, Tool and Work ho	lding d	evices.			-							
UNIT-V	Three Dimensional Modeling					15							
IC Engines Compor	nents and Assemblies.												
		otal ho				45							
	Upon completion of this course, the stude												
Outcomes	• Demonstrate the drawing standards	-											
	• Design the part drawings, sectional				•	•							
	Design the part, assembly modeling	g and dr	afting o	of engir	neering con	nponents as per standards.							
LIST OF EQUIP	PMENTS (for a batch of 30 students)												

- 1. Hardware with graphics facility 30 No.
- 2. Drafting and Modeling software 30 users
- 3. Laser Printer or Plotter to print / plot drawings 1 No

PO CO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2	3	-	3	1	1	_	_	-	-	1	3	-	-
CO2	2	2	3	-	3	1	1	-	-	-	-	1	3	-	-
CO3	2	2	3	-	3	1	1	-	-	-	-	1	3	-	-

Course code	Course Name	Н	ours/w	eek	Credit	M	aximum marks
	Statistics And Numerical Methods	L	T	P	C		
24MA12405	(Chemical & Mechanical Engineering)	3	1	0	4		100
Objective(s)	 To enable students to Study the types of small sample tests Acquire the knowledge of design of e Understand the solution of algebrai solve linear system of equations by d Interpolate the values of a function approximations. Evaluate the derivatives using finite numerical integration methods. 	experime c and the control of the co	transcer d iterat Lagrang	ive met ge's, N	thods. fewton's an	d cubi	c spline polynomial
UNIT-I	Testing of Hypothesis						9+3
Measures of Centra difference of means	of probability- Conditional probability-Stati I tendency: Mean Median and Mode Sam (Large and small samples) – Test for sing independents of attributes.	pling d	listribut	ions –	Test for sin	ngle m	ean, proportion and
UNIT-II	Design of Experiments						9+3
Completely Random Design	ized Design – Randomized Block Design -	- Latin	Square	Design	$1 - 2^2 & 2^3 - 1$	Factori	al Design – Taguchi
UNIT-III	Numerical Solution Of Equations						9+3
system of equations	ic and transcendental equation – Iteration a -Gaussian elimination and Gauss-Jordon a						
	version by Gauss Jordon method	incurou-	- Iterat			,,, , , , , , , , , , , , , , , , , ,	
UNIT-IV	version by Gauss Jordon method Interpolation and Approximation						9+3
UNIT-IV Review of difference	version by Gauss Jordon method	divided					9+3 ewton's forward and
UNIT-IV Review of difference backward difference UNIT-V	version by Gauss Jordon method Interpolation and Approximation e operators – Lagrange's and Newton's interpolation – Interpolating with a cubic s Numerical Differentiation and Integration	divided pline. gration	differe	ence in	terpolation	- Ne	9+3 ewton's forward and
UNIT-IV Review of difference backward difference UNIT-V Differentiation using Simpson's 1/3 and 3	version by Gauss Jordon method Interpolation and Approximation e operators – Lagrange's and Newton's interpolation – Interpolating with a cubic specific s	divided pline. gration plation	differen	ence in	nterpolation	- Ne	9+3 ewton's forward and 9+3 n by trapezoidal and
UNIT-IV Review of difference backward difference UNIT-V Differentiation using	version by Gauss Jordon method Interpolation and Approximation e operators – Lagrange's and Newton's interpolation – Interpolating with a cubic so Numerical Differentiation and Integrated Section (Newton's forward and backward interpolation).	divided pline. gration plation	differen	ence in	nterpolation	- Ne	9+3 ewton's forward and 9+3 n by trapezoidal and
UNIT-IV Review of difference backward difference UNIT-V Differentiation using Simpson's 1/3 and 3	Interpolation and Approximation The operators — Lagrange's and Newton's interpolation — Interpolating with a cubic so interpolation — Interpolation and Integers — Interpolation — Inte	divided pline. gration plation uadrature of experind trans	different formula form	ence in Nur nulae –	nerical inte Double inte Total h	- Ne	9+3 ewton's forward and 9+3 n by trapezoidal and using trapezoidal and 60 m of linear equation
UNIT-IV Review of difference backward difference UNIT-V Differentiation using Simpson's 1/3 and 3 Simpson's rules.	Interpolation and Approximation e operators — Lagrange's and Newton's interpolation — Interpolating with a cubic so Numerical Differentiation and Integrated Newton's forward and backward interpolation — Two and Three point Gaussian quality — Analyze testing of hypothesis. • Solve the problems involving design of Compute the solution of algebraic annumerically.	divided pline. gration plation uadrature of experind trans	different formula form	ence in Nur nulae –	nerical inte Double inte Total h	- Ne	9+3 ewton's forward and 9+3 n by trapezoidal and using trapezoidal and 60
UNIT-IV Review of difference backward difference UNIT-V Differentiation using Simpson's 1/3 and 3 Simpson's rules. Outcome(s) TEXT BOOK:	Interpolation and Approximation The operators — Lagrange's and Newton's interpolation — Interpolating with a cubic so interpolation — Interpolation and Integers — Interpolation — Inte	divided pline. gration plation under a turn of experience a transmission to steep a tegration of the steep a tegratic of the steep a tegration of tegrati	formulate forms. scender solve or using	ence in A -Nurulae -	nerical inte Double inte Total h	- Ne	9+3 ewton's forward and 9+3 n by trapezoidal and using trapezoidal and 60 m of linear equation tions.

REFE	REFERENCES:							
1	Gupta S.C. and Kapoor V.K., "Fundamentals of Mathematical Statistics", Sultan Chand & Sons, New Delhi, 2020.							
2	Veerarajan.T, and Ramachandran, T., "Numerical Methods with programming in C", Tata McGraw Hill, 2007.							
3	Chapra, S. C and Canale, R. P. "Numerical Methods for Engineers", Tata McGraw-Hill, New Delhi, 2015.							

PO CO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	3	-	-	-	-	-	_	-	-	2	3	2	2
CO2	3	3	3	-	-	-	-	-	-	-	-	2	3	2	2
CO3	3	3	3	-	-	-	-	-	-	-	-	2	3	2	2
CO4	3	3	3	-	-	-	-	-	-	-	-	2	3	2	2
CO5	3	3	3	-	-	-	-	-	-	-	-	2	3	2	2

Course code	Course Name	Ho	ours/w	eek	Credit	M	aximum marks
		L	T	P	С		
24ME14303	Fluid Mechanics and Machinery	3	0	0	3		100
Objective(s)	 To discuss the properties and character To discuss the basic concept of bound flow through the pipes To understand the importance of dimer To understand the concepts of pumps a To enumerate the fundamental knowle 	dary lag nsional and thei	yer thic analysi r applic	kness s ations	and find th	e majo	r & minor losses i
U NIT-I	Fluid Properties and Flow Characterist	ics					9
and gas laws -capill control volume to co	ns. Properties of fluids – specific gravity, sarity and surface tension. flow characteristic continuity equation- Euler and Bernoulli's elecity measurement (orifice, venturimeter and	ics: cor equation	ncepts on ap	of syste	em and con	trol vo	lumeapplication of
U NIT-II	Flow Through Circular Conduit						9
and moody diagram	h circular conduits and circular annuli. Turn. Boundary layer concepts – types of bour in flow through pipes. Equivalent pipes, s.	ndary 1	ayer th	ickness	s. Major &	minor	losses- series an
U NIT-III	Dimensional Analysis						9
	s: Buckingham's Π theorem- dimensionless of dimensionless parameters. need for						
UNIT-IV	Pumps	umen	sionar a	inary 51.	s – memoc	15 OI UI	9
performance charac diagrams, work sav velocity components	d category -classification of centrifugal p teristic curves - working of reciprocating ed by air vessels. theory of roto-dynamic at entry and exit of the rotor- velocity triang	g pum c mach	ps, disc	charge,	slip, perc	entage	of slip, Indicatio
UNIT-V	Turbines						9
principles, velocity t	bines – Impulse and reaction turbines, periangles, work done, efficiencies, hydraulics for turbines –governing of turbine.		-				
					Total l	nours	45
Outcome(s)	 Determine properties and characteristies Estimate the flow rates, pressure changes Discuss the importance of dimensional Estimate the efficiency of different pure Apply mathematical knowledge on per 	ges, min and mand mps wit	nor and odel and th the st	alysis udy of	characteris		
TEXT BOOK:							
1 Bansal, R.K 2015.	., "Fluid Mechanics and Hydraulics Machin	ies", N	inth edi	tion, L	axmi Publi	cations	(P) Ltd., New Dell
	"A text book of Fluid Mechanics and pelhi 2009	Hydra	ulic M	achines	s", 5 th Edi	tion, S	S.Chand & Compar
· /:	y, Fluid Mechanics and Hydralic Machines,	S.Char	nd & Co	. Ltd. I	Edition, 201	15.	

REFE	CRENCES:
1	D.S. Kumar, "Fluid Mechanics and Fluid Power Engineering", 2 nd Edition, SK. Katania and Sons, New Delhi, 2010
2	Pijush K Kundu, Irq M Cohen, Fluid Mechanics, Academic Press-2008.
3	Kumar. K.L., "Engineering Fluid Mechanics", 14 th Edition, Eurasia Publishing House (P) Ltd., New Delhi, New Edition -2016.
4	Ramamrutham. S, "Fluid Mechanics, Hydraulics and Fluid Machines", Dhanpat Rai & Sons, Delhi, 2005.
5	Som, S.K., and Biswas, G., "Introduction to Fluid Mechanics and Fluid Machines", by S K Som; G Biswas. Print book. English. 2004. 2 nd Edition. New Delhi, India: Tata McGraw-Hill.

PO CO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	2	1	1	1	1	1	1	1	1	2	3	2	3
CO2	3	3	2	1	1	1	1	1	1	1	1	2	3	3	3
CO3	3	2	2	1	1	1	1	1	1	1	1	2	3	2	3
CO4	3	3	2	1	1	1	1	1	1	1	1	2	3	3	3
CO5	3	3	2	1	1	1	1	1	1	1	1	2	3	3	3

Course code	Course Name	Н	lours	/week	Credit	Maximum marks
24ME14402	Metrology and Measurements	L	T	P	C	100
24MIL14402	With blogy and Witasurements	3	0	0	3	100
Objective(s)	 To describe the basics of standards and measu To illustrate various length and angle measuris Knowledge of computer aided inspection help This course offers a platform for the design an This course provides a comprehensive knowledge 	ng instru s the mo d impler	ments dern o nenta	s. day aut tion of	SQC syste	m.
UNIT-I	Basics of Metrology					9
	trology – Need – Elements – Work piece, Instrumerrs–Errors in Measurements–Types–Control–Types of			– Envii	onment –t	heir effect on Precision
UNIT-II	Linear and Angular Measuring Instruments					9
concepts of interes	nstruments – Evolution – Types – Classification – Lehange ability and selective assembly–Angular gauges, spirit levels and sine bar–Angle alignment te	measur	ing i	nstrum	ents-Types	 Bevel protractor
UNIT-III	Advances in Metrology					9
Communican at 1. 1		-annlice	ations	. 10000	•	" locar interferences
laser scanning gau projection compara	d laser metrology: Co-ordinate measuring machine age, non-contact and in- process inspection, vision, Tool makers microscope.	* *				ring machine, Optica
laser scanning gau projection compara UNIT-IV	nge, non-contact and in- process inspection, vision tor, Tool makers microscope. Statistical Quality Control	on syste	em. L	ength	bar measu	ring machine, Optica
laser scanning gau projection compara UNIT-IV Introduction - Defin for Variables - X ba	ige, non-contact and in- process inspection, vision, Tool makers microscope.	auses - S	SQC I	Benefit Process	s and Limicapability	9 tations. Control Charts
laser scanning gau projection compara UNIT-IV Introduction - Defin for Variables - X ba for attributes-Fracti	rige, non-contact and in- process inspection, vision tor, Tool makers microscope. Statistical Quality Control Inition of Quality - Chance Causes and assignable Caur and R charts, Standard deviation charts - run up -	auses - S	SQC I	Benefit Process	s and Limicapability	9 tations. Control Charts
laser scanning gau projection compara UNIT-IV Introduction - Defin for Variables - X ba for attributes-Fractic chart. UNIT-V Introduction to Tra Springs - Proving F Gauges and its On	rige, non-contact and in- process inspection, vision tor, Tool makers microscope. Statistical Quality Control Inition of Quality - Chance Causes and assignable Car and R charts, Standard deviation charts - run upion defectives-And number of defects-chart sensition. Transducers Instruction - Primary - Secondary and Rings - Diaphragm - Monometer - Bimetals - Electricientation for Measurement - Vibration and Accer	d Tertiar	SQC I	Benefit Process charts	s and Limicapability for Non C	y tations. Control Charts studies. Control Charts Conformities- C and U y ws - Bourdon's Tube and Capacitance - Strain
laser scanning gau projection compara UNIT-IV Introduction - Defin for Variables - X ba for attributes-Fractic chart. UNIT-V Introduction to Tra Springs - Proving F Gauges and its On	rige, non-contact and in- process inspection, vision tor, Tool makers microscope. Statistical Quality Control Inition of Quality - Chance Causes and assignable Car and R charts, Standard deviation charts - run upion defectives-And number of defects-chart sensition. Transducers Instruction - Primary - Secondary and Rings - Diaphragm - Monometer - Bimetals - Electronic tor, Tool makers inspection, vision to the process inspection to the process in the	d Tertiar	SQC I	Benefit Process charts Iechani ce - Inc	s and Limicapability for Non C	y tations. Control Charts studies. Control Charts Conformities- C and U y ws - Bourdon's Tube and Capacitance - Strain ntages and Limitation
laser scanning gau projection compara UNIT-IV Introduction - Defin for Variables - X ba for attributes-Fractic chart. UNIT-V Introduction to Tra Springs - Proving F Gauges and its On	rige, non-contact and in- process inspection, vision tor, Tool makers microscope. Statistical Quality Control Inition of Quality - Chance Causes and assignable Car and R charts, Standard deviation charts - run uption defectives-And number of defects-chart sensition. Transducers Insulated Transducers Insulated Transducers - Classification - Primary - Secondary and Rings - Diaphragm - Monometer - Bimetals - Electricientation for Measurement - Vibration and Acceptate - Torque - Power - Temperature.	auses - S run dow vity- Co	SQC I vn – Fontrol vy - M sistan Meas	Benefit Process charts Lechanice - Inc	s and Limicapability for Non C	y tations. Control Charts studies. Control Charts Conformities- C and U y ws - Bourdon's Tube and Capacitance - Strain ntages and Limitation
laser scanning gau projection compara UNIT-IV Introduction - Defin for Variables - X ba for attributes-Fractic chart. UNIT-V Introduction to Tra Springs - Proving F Gauges and its On	rige, non-contact and in- process inspection, visitor, Tool makers microscope. Statistical Quality Control Inition of Quality - Chance Causes and assignable Car and R charts, Standard deviation charts - run uption defectives-And number of defects-chart sensition. Transducers Insulaters Insulaters - Classification - Primary - Secondary and Rings - Diaphragm - Monometer - Bimetals - Electrication for Measurement - Vibration and Acceptance - Torque - Power - Temperature. Upon completion of this course, the Learners well - Discuss the measurement standards and - Explain the various linear and angular relation - Describe the advanced and computerized - Analyze using statistical control tools to	d Tertiar ical- Resuleration	SQC In SQC In Square Measuring syments aring syments aring stand the square many stand the square many	Benefit Process charts Iechani ce - Inc sureme To	s and Limicapability for Non Cal - Bello ductance and - Advantal hours	y tations. Control Charts studies. Control Charts Conformities- C and U y ws - Bourdon's Tube and Capacitance - Strain ntages and Limitation
laser scanning gauprojection compara UNIT-IV Introduction - Defin for Variables - X based for attributes-Fractionart. UNIT-V Introduction to Trassprings - Proving Fractionarts Gauges and its On Measurement of Fo	Ige, non-contact and in- process inspection, vision tor, Tool makers microscope. Statistical Quality Control Inition of Quality - Chance Causes and assignable Car and R charts, Standard deviation charts - run uption defectives-And number of defects-chart sensition. Transducers Insulaters	d Tertiar ical- Resuleration	SQC In SQC In Square Measuring syments aring syments aring stand the square many stand the square many	Benefit Process charts Iechani ce - Inc sureme To	s and Limicapability for Non Cal - Bello ductance and - Advantal hours	y tations. Control Charts studies. Control Charts Conformities- C and U y ws - Bourdon's Tube and Capacitance - Strain ntages and Limitation
laser scanning gauprojection compara UNIT-IV Introduction - Defin for Variables - X bate for attributes-Fractic chart. UNIT-V Introduction to Tra Springs - Proving Fractional Gauges and its On Measurement of Formula (Section 1988) Outcome(s) TEXTBOOK:	rige, non-contact and in- process inspection, visitor, Tool makers microscope. Statistical Quality Control Inition of Quality - Chance Causes and assignable Car and R charts, Standard deviation charts - run uption defectives-And number of defects-chart sensition. Transducers Insulaters Insulaters - Classification - Primary - Secondary and Rings - Diaphragm - Monometer - Bimetals - Electrication for Measurement - Vibration and Acceptance - Torque - Power - Temperature. Upon completion of this course, the Learners well - Discuss the measurement standards and - Explain the various linear and angular relation - Describe the advanced and computerized - Analyze using statistical control tools to	d Tertiar ical- Resoleration	SQC In SQC In Square Measuring syments aring syments aring stand the square many stand the square many	Benefit Process charts Iechani ce - Inc sureme To	s and Limicapability for Non Cal - Bello ductance and - Advantal hours	y tations. Control Charts studies. Control Charts Conformities- C and U y ws - Bourdon's Tube and Capacitance - Strain ntages and Limitation
laser scanning gau projection compara UNIT-IV Introduction - Defin for Variables - X ba for attributes-Fractichart. UNIT-V Introduction to Tra Springs - Proving F Gauges and its On Measurement of Fo Outcome(s) TEXTBOOK: 1 JainR.K.	Ige, non-contact and in- process inspection, vision tor, Tool makers microscope. Statistical Quality Control Inition of Quality - Chance Causes and assignable Car and R charts, Standard deviation charts - run uption defectives-And number of defects-chart sensition. Transducers Insulaters	auses - S run dow vity- Co d Tertiar ical- Res eleration ill be abl measure measure ad measure o underst insducers	SQC In SQC In Square Measuring syments aring syments aring stand the square many stand the square many	Benefit Process charts Iechani ce - Inc sureme To	s and Limicapability for Non Cal - Bello ductance and - Advantal hours	y tations. Control Charts studies. Control Charts Conformities- C and U y ws - Bourdon's Tube and Capacitance - Strain ntages and Limitation
laser scanning gau projection compara UNIT-IV Introduction - Defin for Variables - X ba for attributes-Fractichart. UNIT-V Introduction to Tra Springs - Proving F Gauges and its On Measurement of Fo Outcome(s) TEXTBOOK: 1 JainR.K.	Inge, non-contact and in- process inspection, vision tor, Tool makers microscope. Statistical Quality Control	auses - S run dow vity- Co d Tertiar ical- Res eleration ill be abl measure measure ad measure o underst insducers	SQC In SQC In Square Measuring syments aring syments aring stand the square many stand the square many	Benefit Process charts Iechani ce - Inc sureme To	s and Limicapability for Non Cal - Bello ductance and - Advantal hours	y tations. Control Charts studies. Control Charts Conformities- C and U y ws - Bourdon's Tube and Capacitance - Strain ntages and Limitation
laser scanning gauprojection compara UNIT-IV Introduction - Defin for Variables - X bate for attributes-Fractic chart. UNIT-V Introduction to Tra Springs - Proving Fractic Gauges and its On Measurement of Formal Measu	Inge, non-contact and in- process inspection, vision tor, Tool makers microscope. Statistical Quality Control	d Tertiar ical- Resuleration ill be ablameasurined measurined measurinsducers 10 0,2013	SQC In SQC In Square Measuring syments aring stand the	Benefit Process charts Iechani ce - Inc sureme To	s and Limicapability for Non Cal - Bello ductance and - Advantal hours	y tations. Control Charts studies. Control Charts Conformities- C and U y ws - Bourdon's Tube and Capacitance - Strain ntages and Limitation

CO Mapping with POs and PSOs

co's	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	1	-	1	-	-	-	1	-	-	-	-	1	1	-
CO2	3	1	-	1	-	-	-	1	-	-	-	-	1	1	-
CO3	3	1	-	1	-	-	-	1	-	-	-	-	1	1	-
CO4	1	2	3	1	-	-	-	1	-	-	-	-	2	1	-
CO5	3	1	-	1	-	-	-	1	-	-	-	-	1	1	-

Course Code	Course Name	Hou	rs/V	Veek	Credit	Maximum
		L	T P C		C	Marks
24HS11006	UNIVERSAL HUMAN VALUES -II	2	1	0	3	100

(Mandatory Credit Course to All UG Programmes to be offered in III / IV Semester)

Pre-requisites: Universal Human Values 1 (Induction Programme) (desirable)

The foundation course "H-102 Universal Human Values: "Understanding Harmony" may be covered in III or IV semester. This course discusses the role of human beings in their family. It also touches issues related to their role in the society and the nature. During the Induction Program, students would get an initial exposure to human values through Universal Human Values 1. This exposure is to be augmented by this compulsory full semester foundation course. The Course has 5 Modules (5 Units): 30 Lectures and 15 Practice sessions (Tutorials).

1. COURSE OBJECTIVES:

The objectives of the course are:

- (i). Development of a holistic perspective based on self-exploration about themselves (human being), family, society and nature/existence.
- (ii). Understanding (or developing clarity) the harmony in the human being, family, society and nature/existence
- (iii). Strengthening of self-reflection for harmonious relationship in family, society
- (iv). Development of commitment and courage to act as human being in ensuring harmony in nature for co-existence.
- (v). Development of holistic principles of harmony and professional ethics for natural acceptance of human values and observe ethical human conduct.

2. COURSE OUTCOMES:

Upon completion of the Course the Learner will be able to:

- Distinguish between values and skills, and highlight the need for Universal Human Values.
- ➤ Describe the need for Harmony and distinguish between happiness and accumulation of physical facilities, etc.
- Relate the value of harmonious relationship in family, society based on trust and respect for happiness and prosperity in their life and profession.
- Outline the role of a human being in ensuring harmony in nature for co-existence.
- Apply the holistic principles of Harmony and Professional Ethics for natural acceptance of human values and observe Ethical Human Conduct.

Module 1: Course Introduction - Need, Basic Guidelines, Content and Process for Value Education

- L 1. Purpose and motivation for the course, recapitulation from Universal Human Values-I (Induction Programme).
- L 2. Self-Exploration—what is it? Its content and process; 'Natural Acceptance' and Experiential Validation-as the process for self-exploration.
- L 3. Continuous Happiness and Prosperity A look at basic Human Aspirations.
- L 4. Right understanding, Relationship and Physical Facility the basic requirements for fulfillment of aspirations of every human being with their correct priority.

- L 5. Understanding Happiness and Prosperity correctly A critical appraisal of the current scenario.
- L 6. Method to fulfill the above human aspirations: understanding and living in harmony at various levels.
- 3 Practice sessions (T1 to T3) To discuss natural acceptance in human being as the innate acceptance for living with responsibility (living in relationship, harmony and co-existence) rather than as arbitrariness in choice based on liking-disliking.

Module 2: Understanding Harmony in the Human Being - Harmony in Myself!

- L 7. Understanding human being as a co-existence of the sentient 'I' and the material 'Body'
- L 8. Understanding the needs of Self ('I') and 'Body'- happiness and physical facility
- L 9. Understanding the Body as an instrument of 'I'(I being the doer, seer and enjoyer)
- L 10.Understanding the characteristics and activities of 'I' and harmony in 'I'
- L 11.Understanding the harmony of I with the Body: Sanyam and Health; correct appraisal of Physical needs, meaning of Prosperity in detail.
- L 12. Programs to ensure Sanyam and Health.
- 3 Practice sessions (T4 to T6) To discuss the role others have played in making material goods available to me. Identifying from one's own life. Differentiate between prosperity and accumulation. Discuss program for ensuring health vs dealing with disease.

Module 3: Understanding Harmony in the Family and Society - Harmony in Human-Human Relationship

- L 13. Understanding values in human-human relationship; meaning of Justice (Nine universal values in relationships) and program for its fulfillment to ensure mutual happiness; Trust and Respect as the foundational values of relationship.
- L 14. Understanding the meaning of Trust; Difference between intention and competence.
- L 15. Understanding the meaning of Respect, Difference between respect and differentiation; the other salient values in relationship.
- L 16. Understanding the harmony in the society (society being an extension of family): Resolution, Prosperity, fearlessness (trust) and co-existence as comprehensive Human Goals.
- L 17. Visualizing a universal harmonious order in Society-Undivided Society, Universal Order-from family to world family.
- 3 Practice sessions (T7 to T9): Include practice sessions to reflect on relationships in family, hostel and institute as extended family, real life examples, teacher-student relationship, goal of education, etc. Discuss Gratitude as a universal value in relationships, scenarios. Elicit examples from students' lives.

Module4: Understanding Harmony in the Nature and Existence - Whole existence as Coexistence

- L 18. Understanding the harmony in the Nature.
- L 19. Interconnectedness and mutual fulfillment among the four orders of nature recyclability and self-regulation in nature.
- L 20. Understanding Existence as Co-existence of mutually interacting units in all pervasive space.
- L 21. Holistic perception of harmony at all levels of existence.
- 2 Practice sessions (T10 to T11): Include practice sessions to discuss human being as cause of imbalance in nature (film "Home" can be used), pollution, depletion of resources and role of technology, etc.

Module 5: Implications of the above Holistic Understanding of Harmony on Professional Ethics L 22. Natural acceptance of human values.

- L 23. Definitiveness of Ethical Human Conduct.
- L 24. Basis for Humanistic Education, Humanistic Constitution and Humanistic Universal Order.
- L 25. Competence in professional ethics: (a). Ability to utilize the professional competence for augmenting universal human order (b). Ability to identify the scope and characteristics of people-friendly and eco-friendly production systems, (c). Ability to identify and develop appropriate technologies and management patterns for above production systems.
- L 26. Case studies of typical holistic technologies, management models and production systems.
- L 27. Strategy for transition from the present state to Universal Human Order: (a). At the level of individual: as socially and ecologically responsible engineers, technologists and managers (b). At the level of society: as mutually enriching institutions and organizations.
- L 28. Definition of Morals, Values and Ethics Integrity Work ethic Service learning Civic virtue Respect for others Living peacefully.
- L 29. Importance of Caring Sharing Honesty Courage Valuing time Cooperation Commitment Empathy Self-confidence Character Spirituality.
- L 30. Introduction to Yoga and meditation for professional excellence and stress management. *Sum up*.
- 4 Practice sessions (T12 to T15) Include Practice Exercises and Case Studies which will be taken up in Practice (Tutorial) Sessions.
- eg. To discuss the conduct as an Engineer or Scientist, etc.

Total hours = 45

3. READINGS:

3.1 Textbook

1. Human Values and Professional Ethics by R R Gaur, R Sangal, G P Bagaria, Excel Books, New Delhi, 2010.

3.2 Reference Books

- 1. Jeevan Vidya: Ek Parichaya, A Nagaraj, Jeevan Vidya Prakashan, Amarkantak, 1999.
- 2. Human Values, A.N. Tripathi, New Age Intl. Publishers, New Delhi, 2004.
- 3. The Story of My Experiments with Truth -by Mohandas Karamchand Gandhi
- 4. Small is Beautiful E. F Schumacher.
- 5. Slow is Beautiful Cecile Andrews.
- 6. Economy of Permanence J C Kumarappa.
- 7. Bharat Mein Angreji Raj Pandit Sunderlal.
- 8. Rediscovering India by Dharampal.
- 9. Hind Swaraj or Indian Home Rule by Mohandas K. Gandhi.
- 10. India Wins Freedom Maulana Abdul Kalam Azad.
- 11. Vivekananda Romain Rolland (English).
- 12. Mika Martin and Roland Scinger, 'Ethics in Engineering', Pearson Education/Prentice Hall, New York 1996.

CO Mapping with POs and PSOs

CO'S	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	1	-	-	-	2	3	3	2	1	-	-	2	1	-
CO2	2	1	-	-	-	2	3	3	2	2	-	-	2	1	-
CO3	1	2	-	-	-	3	2	3	3	2	-	-	2	2	-
CO4	1	1	-	-	-	3	3	2	2	1	-	-	2	2	-
CO5	2	2	-	-	-	3	3	3	2	2	-	-	3	3	-

Co	urse		Но	urs/W	eek	Credit	Maximum				
	ode	Course Name	L	T	P	C	marks				
24MI	E 24401	Fluid Mechanics and Machinery Laboratory	0	0	3	1.5	100				
Objective(s))	Upon Completion of this subject, the studies measurements using different devices a pipes and also perform characteristic st	nd also	perfo	m cal	culation re					
		LIST OF EXPERIME	ENTS								
1	Determina	tion of the Coefficient of discharge of given Ori	fice met	er.							
2	_	tion of the Coefficient of discharge of given Ver									
3	Calculation	n of the rate of flow using Rota meter.									
4	Determina	tion of friction factor for a given set of pipes									
5	Conductin	g experiments and drawing the characteristic cur	rves of c	entrifu	igal p	ump					
6	Conductin	g experiments and drawing the characteristic cur	rves of s	ubmer	gible p	oump					
7	Conductin	g experiments and drawing the characteristic cur	rves of r	ecipro	cating	pump.					
8	_	g experiments and drawing the characteristic cur									
9		g experiments and drawing the characteristic cur									
10	Conductin	g experiments and drawing the characteristics cu									
				Total	hours	s 45					
	-	(for a batch of 30 students)									
1		eter setup -1 No.									
2		eter setup-1 No.									
3		setup-1 No.									
4		analysis setup-1 No.									
5		l pump-1 No.									
6		ole pump setup-1 No.									
7		ting pump setup-1 No.									
8		setup-1 No.									
9		eel setup-1 No.									
10	Francis tur	bine setup -1 No.									
Outcome(s)		Ability to use the measurement equipment				ement					
Catconic(b)		Ability to do performance trust on different fluid machinery									

PO CO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	-	_	3	-	_	-	3	1	-	-	3	3	1	-
CO2	2	-	-	3	-	-	-	3	1	-	-	3	3	1	-
CO3	2	-	-	3	-	-	-	3	1	-	-	3	3	1	-

C		Comment No.	H	ours/W	Veek	Credit	Maximuı — marks
Cou Co		Course Name	L	T	P	C	mai KS
22MF	E24701	Metrology and Measurements Laboratory	0	0	3	1.5	100
Object	tive(s)	 This course provides the practical knowled measurements. To demonstrate the optical measuring instr To explain the importance for handling the 	uments.	ents.	rious mea	asurements like	e linear, angula
		LISTOFEXPERI	MENTS	5			
1	Calibrat	ion of Vernier/ Micrometer/ Dial gauge.					
2	Checkin	g Dimensions of part using slip gauges.					
3	Measure	ements of Gear Tooth Dimensions using Gear T	ooth Ver	nier.			
4	Measure	ement of Angle using sine bar/sine center/ Beve	l Protrac	tor .			
5	Measure	ement of thread parameters using Toolmakers M	licroscop	e/Floati	ng carria	ge Micrometer	•
6	Checkin	g the limits of dimensional tolerances using cor	nparator	s (Mech	anical).		
7	Measure	ement of Temperature using Thermocouple.					
8	Measure	ement of Displacement using LVDT.					
9	Measure	ement of Force using Load Cell.					
10	Measure	ement of taper angle using profile projector.					
			To	tal hou	rs	45	
LIST	OF EQU	IPMENTS					
1	Tool M	laker's Microscope–1No.					
2	Compa	rator- 2No.					
3	SineBa	r-2No.					
4	Gear T	ooth Vernier Caliper-1No.					
5		g carriage Micrometer-1No.					
6		rature measurement setup -1No.					
7		Cellsetup-1No.					
8		projector-1No.					
9		rotractor-1 No.					
10		ugeset-4No.					
11		rcaliper—4No.					
12 13		neter-4 No. eplate–6No.					
13	Surrace	At the end of the course, the students will be	abla ta				
Out	come(s)	 Use the measuring instruments and meas Determine the characteristics of measuring Manipulate the measurement of various 	ure the d	ments.		ous component	es.

CO'S	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	-	-	-	3	-	-	1	3	-	-	-	1	-	-
CO2	3	-	-	-	3	-	-	1	3	-	-	-	1	-	-
CO3	3	-	-	-	3	-	-	1	3	-	-	-	1	-	-

Cou	ırse	Course Ni	Hou	ırs/W	eek	Credit	Maximum
Co	de	Course Name	L	T	P	C	marks
24HS2	21002	Professional Communication Skills (Common to all B.E./B.Tech. Degree Programmes)	0	1	2	2	100
Objec	ctives	 To familiarize students with the stage To help the learners to improve their cr To make them acquire the ability to specific 	reative	skills	y in re	al life situa	tions
		LIST OF EXPERIME	NTS				
1	Introduction	to Professional Communication and SWOT Ar	nalysis				
2	Soft Skills (0	Goal Setting, Empathy, Stress Management, En	notional	Intell	igence	, Conflict F	Resolution)
3	Building Vo	cabulary (Intermediate Level)					
4	Welcome Ac	ddress and Vote of Thanks					
5	Stage Dynan	nics (Body Language and Paralanguage – Indiv	idual P	resenta	ation fo	or 3 minute	s)
6	Framing Que	estions (WH Questions & 'Yes' or 'No' Questions	ons)				
7		chniques - Narrating the Experience					
8	Master of Ce	eremony Skills					
9	Picture Desc	<u> </u>					
10		Speech (Just a Minute)					
10	impromptu c	special (bust a rimace)	r		hours	30	
Outcome(s)	AppDen	the course, the learners will be able to: bly suitable vocabulary in academic and workpla nonstrate communication skills effectively in bo ate documents professionally and make presenta	ace con	texts and w	ritten t		
ТЕХТВООІ	_						
1	·	ohan, Soft Skills, 1st Edition. Bookboon, 2017					
REFERENC 1	EE BOOKS:		- ·			V D 11.	2011
2		a, & Sunita Mishra, Communication Skills for E ra, Personality Development and Soft Skills, O					
WEBSITES	Darun K. Will	ra, reisonanty Development and Sort Skills, O.	AIOIU C	111 VC18	ity FIC	os, INCW DE	AIII, 2011
1	https://www.	ted.com/talks					
2	https://joshtal						
3	https://quizziz						
4	www.pdfdriv	e.com					
5	www.talking	books.com					

CO'S	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	-	-	-	2	3	3	3	2	2	3	3	-	-	-
CO2	2	-	-	-	2	3	3	3	2	2	3	3	-	-	-
CO3	2	-	-	-	2	3	3	3	2	2	3	3	-	-	-

	de	Course Name	H	lours/v	week	Credit		Maximum marks
			L	T	P	С		
24ME14	501	Thermal Engineering	3	0	0	3		100
Objective(s	s)	 To understand fundamental conc To describe the steam nozzles an To understand the basic concepsystem To understand the knowledge on of the systems To enumerate the performance and 	d turbin ts of air refriger	es for compa	leterm ressor nd air	ining the es and to fi	fficience and the second the seco	y of the systems. various efficiencies of the dentifying the performance
UNIT	I G	Gas Power Cycles						9
		d Brayton cycles, calculation of men of four stroke and two stroke engine		ctive p	oressu	re, and air	standa	rd efficiency - actual and
UNIT-	-II S	team Nozzles and Turbines						9
		nozzles, shapes of nozzles, effect of npounding of turbine, velocity diagra						nturated flow, impulse and
UNIT-	ш А	ir Compressors						9
volumetric eff with and with	ficiency, lout inter of	cking principle of various types of Isothermal efficiency and Isentropic cooling.	•			•		
UNIT-								
		Refrigeration and Air Conditioni						9
Refrigerants - system - types	- vapour	Refrigeration and Air Conditionic compression refrigeration cycle - with the concept of room sent mobile air conditioning and refrigeration.	vorking sible he	princip				n system, air conditioning
Refrigerants - system - types	- vapour s and wor	compression refrigeration cycle - v king principles - concept of room sen	vorking sible he	princip				n system, air conditioning
Refrigerants system - types factor, Introdu UNIT- Classification Comparison of	- vapour s and wor uction to r -V In - Compo of petrol a calculation	compression refrigeration cycle - v king principles - concept of room sen mobile air conditioning and refrigerat	working asible he ion. on of two	principat facto o strok	e and	four stroke	heat fa	n system, air conditioning ctor, effective sensible hear s
Refrigerants system - types factor, Introdu UNIT- Classification Comparison of	- vapour s and wor uction to r -V In - Compo of petrol a calculation	compression refrigeration cycle - with king principles - concept of room semble air conditioning and refrigerate contents and their function - Comparison diesel engines - Lubrication systems	working asible he ion. on of two	principat facto o strok	e and	four stroke ems - Batter tion contro	heat fa	n system, air conditioning ctor, effective sensible hear s
Refrigerants system - types factor, Introdu UNIT- Classification Comparison of Performance EGR and SCF	- vapour s and work uction to r -V In - Compoor petrol a calculation	compression refrigeration cycle - with king principles - concept of room semble air conditioning and refrigerate contents and their function - Comparison diesel engines - Lubrication systems	vorking asible he ion. on of tweeter and tweeter cycle of different steam the fair conductor of the conduct	o strok Cooling norms.	e and g system Pollumble to use in sof stit.	four stroke ms - Batter tion control Total internal coream nozzleder the give em for a	heat fa e engine ry and M ol metho hours mbustion es and in en opera	n system, air conditioning ctor, effective sensible hear 9 es – Fuel injection system Magneto Ignition Systems ods – Catalytic converters of the engine. its applications, conditions ating conditions. ar application
Refrigerants system - types factor, Introdu UNIT- Classification Comparison of Performance EGR and SCF Outcom	- vapour s and wor uction to r -V In - Compo of petrol a calculation R me(s)	compression refrigeration cycle - vking principles - concept of room sent mobile air conditioning and refrigerate meternal Combustion Engines ments and their function - Comparison diesel engines - Lubrication systems on Exhaust gas analysis, Pollution of Exhaust gas analysis, Pollution of Upon completion of this course, the Apply the different gas pow Understand the working of for maximum discharge of Evaluate the performance of Design refrigeration and a Get an insight of various comparison.	vorking asible he ion. on of tweeter and tweeter cycle of different steam the fair cord air-condomponer	o strok Cooling norms.	e and g syste Polluble to use in s of stit. Dors und g syst princi	four strokes and sensible four strokes and sensible for a ples of internal control for a ples	heat fa e engine ry and M ol metho hours mbustion es and i en opera particul rnal cor	n system, air conditioning ctor, effective sensible hear s
Refrigerants system - types factor, Introdu UNIT- Classification Comparison of Performance EGR and SCF Outcon	- vapour s and work uction to receive to receive to receive to receive the receive to receive the receive to receive the receive to receive the receiv	compression refrigeration cycle - vking principles - concept of room sen mobile air conditioning and refrigerate the netral Combustion Engines ments and their function - Comparison diesel engines - Lubrication systems - Exhaust gas analysis, Pollution of this course, the Apply the different gas pow Understand the working of for maximum discharge of Evaluate the performance of Design refrigeration and a	working asible he ion. on of tweeter student wer cycle of different steam that air conditions are conditionally c	o strok Cooling norms.	e and g syste Polluble to use in s of stit. ors und g syste princi	four strokes and sensible four strokes and sensible for a ples of integrated at the Edition,	e engine ry and M ol metho hours mbustion es and i en opera particul rnal cor	9 es – Fuel injection system Magneto Ignition Systems ods – Catalytic converters on engine. its applications, conditions ating conditions. ar application mbustion engine

REFERE	NCES:
1	R.S.Khurmi and J.K.Gupta "Thermal Engineering" S.Chand & Company Ltd, 2020
2	Ganesan V." Internal Combustion Engines" 4th Edition, Tata McGraw-Hill 2017.
3	Apora C P, Refrigeration And Air Conditioning, Tata Mcgraw Hill -2015.

CO'S	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	1	-	-	1	-	1	-	-	-	1	1	-	3
CO2	3	3	3	-	-	1	-	1	-	-	-	1	1	-	3
CO3	3	3	1	-	-	1	-	1	-	-	-	1	1	-	3
CO4	3	3	3	-	-	1	-	1	-	-	-	1	1	-	3
CO5	3	2	2	-	-	1	-	1	-	-	-	1	1	-	3

	e code	Course Name	Но	ours/w	eek	Credit	Maximum marks
24ME	14502	Design of Machine Elements (Use of P S G Design Data Book is permitted in	L	T	P	C	100
241112	14502	the End Semester examination)	3	0	0	3	100
Objectiv	ve(s)	 To understand machine members subjected To understand the design of shafts and coup Learn how to design both temporary and per To understand the design procedure for helication To Design and select sliding and rolling control 	lings for maner cal, lea	or varion t joints f spring	ous appl under	ications. various loa	
UNI	IT-I	Steady Stresses and Variable Stresses In Ma			nents		9
properties calculation Factor of	s-Preferre on of prin f safety-th	ne design process-factors influencing machine and numbers, fits and tolerances—Direct, Bending a ciples tresses for various load combinations, econeories of failure—Design based on strength and g, Goodman and Gerber relations.	desig	n ,sele sional s loading	ction o tress eq g–curve	uations—In d beams—c	npact and shock loading- rane hook and'C' frame-
UNI		Shafts and Couplings					9
		nd hollow shafts based on strength, rigidity— Kekeys-Couplings - Rigid coupling- flexible couplings		ferent	types o	f keys- De	sign Keys, keyways and
UNI		Temporary and Permanent Joints	-				9
		s- stress in screwed threads, Bolted joints incl Riveted joints for structures.	uding	eccentr	ric load	ing, Knucl	de joints, Cotter joints-
UNI	Γ-IV	Energy Storing Elements and Engine Comp	onents				9
in rims ar	nd arms f	gs-applications- spring materials-Design of helication engines -Connecting rod and Crankshaft.	al sprin	gs and	leaf spi	ring- Flywl	neels considering stresses
UNI	T-V	Bearings					9
		I .					
		d rolling contact bearings (antifriction bearing) and rolling contact bearings.	-Hydro	odynam	ic jour	nal bearing	s, Sommerfeld Number,
			-Hydro	odynam		nal bearing Total hou	
Selection Outcom	of ball an		ust be a lign ma ength, r and tem orage el	able to: achine r igidity porary ement	nember and des joint or and eng	Total hou under vari sign various	rs 45 able loading. s types of coupling based ading application.
Selection	of ball an	 Upon completion of this course the students me Apply the principle of solid mechanics to des Calculate the diameter of shafts based on street on application. Discus the design Parameters of permanent at Calculate the design parameter for energy storet 	ust be a lign ma ength, r and tem orage el	able to: achine r igidity porary ement	nember and des joint or and eng	Total hou under vari sign various	rs 45 able loading. s types of coupling based ading application.
Selection Outcom	ne(s)	 Upon completion of this course the students me Apply the principle of solid mechanics to des Calculate the diameter of shafts based on street on application. Discus the design Parameters of permanent at Calculate the design parameter for energy storet 	ust be a ign ma ength, r and tem orage el pes of	able to: achine 1 igidity porary ement pearing	nember and des joint or and eng	Total hou under vari ign various various lo	rs 45 able loading. s types of coupling based ading application. nents.
Outcom TEXT F	ne(s) BOOK:	 Upon completion of this course the students me Apply the principle of solid mechanics to des Calculate the diameter of shafts based on street on application. Discuss the design Parameters of permanent a Calculate the design parameter for energy store Compute the design parameters of various ty 	ust be a ign ma ength, r and tem orage el pes of l	able to: achine 1 igidity porary ement bearing	member and des joint or and eng s.	under various logine compo	rs 45 able loading. s types of coupling based ading application. nents.
Outcom TEXT E	ne(s) BOOK: R.S.Khu Bhandar S.Md Ja	Upon completion of this course the students me Apply the principle of solid mechanics to des Calculate the diameter of shafts based on stree on application. Discuss the design Parameters of permanent a Calculate the design parameter for energy sto Compute the design parameters of various ty armi&J.K.Ghupta"A Textbook of Machine Design V,"Design of Machine Elements",3rd Edition,7 laludeen "Machine Design Volume –I Design of	ust be a sign makingth, rend temorage elepes of lone. S.C. TataMc	able to: chine r igidity porary ement bearing hand & Graw-I	member and des joint or and eng s. Compa	under various logine compo	able loading. s types of coupling based ading application. nents.
Outcom TEXT E 1 2	BOOK: R.S.Khu Bhandar S.Md Ja 2014.Ch	Upon completion of this course the students me Apply the principle of solid mechanics to des Calculate the diameter of shafts based on stree on application. Discus the design Parameters of permanent a Calculate the design parameter for energy sto Compute the design parameters of various ty armi&J.K.Ghupta"A Textbook of Machine Design V,"Design of Machine Elements",3rd Edition,7 laludeen "Machine Design Volume –I Design of Machine Design of Machine Design of Machine Design of Machine Design Volume –I Design Vol	ust be a sign makingth, rend temorage elepes of lone. S.C. TataMc	able to: chine r igidity porary ement bearing hand & Graw-I	member and des joint or and eng s. Compa	under various logine compo	able loading. s types of coupling based ading application. nents.
Outcom TEXT E 1 2 3	BOOK: R.S.Khu Bhandar S.Md Ja 2014.Ch ENCES Joseph	Upon completion of this course the students me Apply the principle of solid mechanics to des Calculate the diameter of shafts based on stree on application. Discus the design Parameters of permanent a Calculate the design parameter for energy sto Compute the design parameters of various ty armi&J.K.Ghupta"A Textbook of Machine Design V,"Design of Machine Elements",3rd Edition,7 laludeen "Machine Design Volume –I Design of Machine Design of Machine Design of Machine Design of Machine Design Volume –I Design Vol	ust be a ign ma ingth, r and tem orage el pes of n" S.C TataMc	able to: achine to igidity porary ement bearing hand & Graw-l ne Eler	member and des joint or and eng s. Compa HillBoo ments",	under various logine composition was a various logine composition with the composition was a various logine composition which was a various logine composition was a	able loading. s types of coupling based ading application. nents.
Outcom TEXT E 1 2 3 REFER	BOOK: R.S.Khu Bhandar S.Md Ja 2014.Ch ENCES Joseph Edition,	Upon completion of this course the students me Apply the principle of solid mechanics to des Calculate the diameter of shafts based on stree on application. Discus the design Parameters of permanent a Calculate the design parameter for energy sto Compute the design parameters of various ty Trmi&J.K.Ghupta"A Textbook of Machine Design V,"Design of Machine Elements",3rd Edition,7 Islaludeen "Machine Design Volume –I Design of Mennai. Shigley,Charles Mischke,Richard Budynas and	ust be a ign ma ength, r and tem orage el pes of l ataMc Machi	able to: uchine reigidity porary ement bearing hand & Graw-I ne Eler	member and des joint or and eng s. Compa HillBoo ments",	under various logine composition (2010). Ath edition	able loading. s types of coupling based ading application. nents. Anuradha Publications, Engineering Design",8th

4	Norton R.L, "Design of Machinery", Tata McGraw-Hill Book Co., 2004.
5	Spotts M.F, Shoup T.E., "Design and Machine Elements", Pearson Education, 2004.

CO'S	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2	3	-	-	1	-	1	1	-	-	1	-	1	-
CO2	2	2	3	-	-	1	-	1	1	-	-	1	-	1	-
CO3	2	2	3	-	-	1	1	1	1	1	-	1	-	1	-
CO4	2	2	3	-	-	1	-	1	1	1	-	1	-	1	-
CO5	2	2	3	-	-	1	-	1	1	-	-	-	-	1	-

Course code	Course Name	Но	urs/we	ek	Credit	Ma	aximum marks
		L	T	P	C		400
24ME14503	Manufacturing Technology	3	0	0	3		100
Objective(s)	 To understand the working princip To explore various abrasive machin To study CNC machine tools, their To examine mechanical and electrochem To learn chemical and electrochem 	ining an r comporical ene	d gear onents, argy-bas	cutting and pa sed nor	techniques rt programi n-traditiona	s. ning m l machi	ethods. ning processes.
UNIT-I	Reciprocating machine tools						9
Quill mechanism, R	ne tools: shaper, planer, slotter - Milling: eaming, Boring, Tapping - Sawing machin-push, pull, surface and continuous broaching.	ne: hack	saw, b				
UNIT-II	Abrasive Processes and Gear Cuttin	ng					9
grinding, centreless	grinding wheel – specifications and selection grinding – honing, lapping, super finishing eration, shaping, hobbing.		_	_	_	-	
UNIT-III	CNC Machine Tools and Part Progr	rammi	ng				9
	mproving machining accuracy – structural feed drives. Part programming fundame Mechanical Energy and Electrical 1	entals –	manu	al pro	•		•
equipment used – Pr (EDM)- working Pr	ing – Water Jet Machining – Ultrasonic Mocess parameters – MRR-Variation in techniciples-equipments-Process Parameters-I – Wire cut EDM – Applications.	nniques	used –	Appli	cations. Ele	ectric D	ischarge Machining
UNIT-V	Chemical and Electro-Chemical En	ergy B	ased P	roces	ses		9
	g and Electro-Chemical machining (CF arameters – MRR-Applications. Princip ECH Applications.						1 11 0
					Total l	nours	45
Outcome(s)	 Identify and explain the operation of s Select appropriate abrasive tools and p Develop CNC part programs and unde Analyze the principles and application Evaluate CHM and ECM processes, in 	processe erstand r	s for pr nachine M, WJN	ecision desig A, USI	n finishing to n considera M, and EDM	tasks. itions. M proce	esses.
TEXT BOOK:	(D)						
, , , , , , , , , , , , , , , , , , ,	ry, "Elements of Work Shop Technology –				noters. 2002	2	
	and Zimers Jr., 'CAD/CAM' Prentice Hall				11 ' T 1'	2010	
3 Anand Pande	y, "Modern Machining Processes", Ane Bo	oks Pvt	Ltd., N	new D	eini, India,	2019.	

REFERENCES:

- 1 Rajput R.K, 'Atext book of Manufacturing Technology', Lakshmi Publications, 2007.
- Mikell P.Groover, 'Fundamentals of Modern Manufacturing, Materials, Processes and Systems', John Wiley and Sons, 9th Edition, 2007.
- 3 Jagadeesha T., "Non-Traditional Machining Processes", I.K. International Publishing House Pvt. Ltd., New Delhi, India, 2017
- 4 Carl Sommer, "Non-Traditional Machining Handbook", Advance Publishing., United States, 2000

co's	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	2	1	2	-	-	-	2	-	-	2	2	3	-
CO2	3	2	2	2	2	-	-	-	2	-	-	2	1	3	-
CO3	3	3	3	2	3	-	-	-	2	-	-	2	3	3	-
CO4	3	2	3	3	2	-	-	-	2	-	-	2	2	3	-
CO5	3	2	2	1	2	-	-	-	2	-	-	2	2	3	-

Course code	Course Name	Н	ours/w	eek	Credit	Maximum mark		
		L	T	P	C			
24HS11004	Constitution of India	3	0	0	3		100	
Objective(s)	 To know about the salient features of To gain knowledge about structure a To learn about the structure and func To understand about amendments in To study in detail about the Indian so 	nd functi ctions of Indian C	ions of State G	Union (overnn	Governmen nent.			
UNIT-I	Introduction About Indian Constituti	ion					9	
Indian Constitution	and – Constituent Assembly of India – Find – Preamble – Fundamental Rights – Distuttional Remedies for citizens.	irective 1	Principl			•		
UNIT-II	Structure and Function of Union (Governi	nent				9	
	m – Legislature, Executive. Union Govern President – Vice President – Prime Minister							
UNIT-III	Structure and Function of State G	overnm	ent				9	
(Article 370. 371, 3	tate Government – Structure and Function 71J) for some States. Judicial System in						•	
review.								
UNIT-IV	Constitution Functions, Amendme em – Centre-State Relations – President's				working of	f the Pa	9 rliamentary System	
UNIT-IV Indian Federal Syste in India - Constitu Constitutional Amen the Constitution – T Court. Judicial Revie UNIT-V	<u>'</u>	Rule – Anstitution 61, 73, 7 de Chief .	Assessmal Ame 74, 75, Justice	nent of endmer 86, and of Indi	nts (How 1 91, 94, 95 a and Hon'	and W 5, 100, ble Jud	rliamentary System hy) and Important 101, 118. Savior of ges of the Supreme	
UNIT-IV Indian Federal Syste in India - Constitut Constitutional Amer the Constitution - T Court. Judicial Revie UNIT-V Society: Nature, M Remedies for citize Scheduled Tribes an	em – Centre-State Relations – President's ational Amendments – Methods in Conndments. Amendments – 7,9,10,12,42,44, The Supreme Court of India – The Hon'blew of Parliamentary and Executive function. Indian Society Meaning and definition; Indian Social States – Political Parties and Pressure Ground other Weaker Sections - Special Constitution.	Rule – Anstitution 61, 73, 7 de Chief . ons.	Assessmal Amoral	nent of endmer 86, and of Indi Religion	nts (How d 91, 94, 93 a and Hon' on, Langua Children	and W 5, 100, ble Jud ge in I	rliamentary System hy) and Important 101, 118. Savior of ges of the Supreme 9 ndia; Constitutiona heduled Castes and	
UNIT-IV Indian Federal Syste in India - Constitu Constitutional Amer the Constitution - T Court. Judicial Revie UNIT-V Society: Nature, M Remedies for citize	em – Centre-State Relations – President's ational Amendments – Methods in Conndments. Amendments – 7,9,10,12,42,44, The Supreme Court of India – The Hon'blew of Parliamentary and Executive function. Indian Society Meaning and definition; Indian Social States – Political Parties and Pressure Ground other Weaker Sections - Special Constitution.	Rule – Anstitution 61, 73, 7 de Chief . ons.	Assessmal Amoral	nent of endmer 86, and of Indi Religion	nts (How d 91, 94, 93 a and Hon' on, Langua Children	and W 5, 100, ble Jud ge in I and Sc OBC, S	rliamentary System hy) and Important 101, 118. Savior of ges of the Supreme 9 ndia; Constitutiona heduled Castes and	
UNIT-IV Indian Federal Syste in India - Constitut Constitutional Amer the Constitution – T Court. Judicial Revie UNIT-V Society: Nature, N Remedies for citize Scheduled Tribes an Women, Children &	em – Centre-State Relations – President's ational Amendments – Methods in Conndments. Amendments – 7,9,10,12,42,44, The Supreme Court of India – The Hon'blew of Parliamentary and Executive function. Indian Society Meaning and definition; Indian Social States – Political Parties and Pressure Ground other Weaker Sections - Special Constitution.	Rule – Anstitution 61, 73, 7 de Chief 3 de C	Assessmal Amoral	Religion of the to: d obse em at the aportar udicial	on, Langua; Children SC & ST, Total h	and W 5, 100, ble Jud ge in It and Sc OBC, S nours damenta	rliamentary System hy) and Important 101, 118. Savior of ges of the Supreme 9 ndia; Constitutiona heduled Castes and pecial Provision fo 45	
UNIT-IV Indian Federal Syste in India - Constitu Constitutional Amer the Constitution - T Court. Judicial Revie UNIT-V Society: Nature, N Remedies for citize Scheduled Tribes an Women, Children &	em – Centre-State Relations – President's ational Amendments – Methods in Connuments. Amendments – 7,9,10,12,42,44, The Supreme Court of India – The Hon'blew of Parliamentary and Executive function. Indian Society Meaning and definition; Indian Social States – Political Parties and Pressure Ground other Weaker Sections - Special Constitute Backward Classes. On completion of the course, the learned estimates a Summarize the features of the Indian responsibilities. Explain the functioning of Indian partimportant functionaries. Describe the functioning of State Goes Recognize Amendments in Indian Connumers.	Rule – Anstitution 61, 73, 7 de Chief 3 de C	Assessmal Amoral	Religion of the to: d obse em at the aportar udicial	on, Langua; Children SC & ST, Total h	and W 5, 100, ble Jud ge in It and Sc OBC, S nours damenta	rliamentary System hy) and Important 101, 118. Savior of ges of the Supreme 9 ndia; Constitutiona heduled Castes and pecial Provision for 45	
UNIT-IV Indian Federal Syste in India - Constitut Constitutional Amer the Constitution - T Court. Judicial Revie UNIT-V Society: Nature, N Remedies for citize Scheduled Tribes an Women, Children & Outcome(s) TEXT BOOK:	em – Centre-State Relations – President's ational Amendments – Methods in Connuments. Amendments – 7,9,10,12,42,44, The Supreme Court of India – The Hon'blew of Parliamentary and Executive function. Indian Society Meaning and definition; Indian Social States – Political Parties and Pressure Ground other Weaker Sections - Special Constitute Backward Classes. On completion of the course, the learned estimates a Summarize the features of the Indian responsibilities. Explain the functioning of Indian partimportant functionaries. Describe the functioning of State Goes Recognize Amendments in Indian Connumers.	Rule – Anstitution 61, 73, 7 de Chief Cons. ructure; aps; Right tutional land a Constitution on the constitution of the const	Assessmal American Am	Religion / Omen, ons for dobse em at the properties of the to:	nts (How d 91, 94, 95 a and Hon' on, Langua; Children SC & ST, 6 Total harve the function on the Center and the function areview.	and W 5, 100, ble Jud ge in It and Sc OBC, S nours damenta nd the r ries.	rliamentary System hy) and Importan 101, 118. Savior of ges of the Supremo 9 ndia; Constitutional heduled Castes and pecial Provision for 45 Il duties, rights and	

REFI	REFERENCES:									
1	Sharma, Brij Kishore, "Introduction to the Constitution of India:, Prentice Hall of India, New Delhi.									
2	Maciver and Page, "Society: An Introduction Analysis", Mac Milan India Ltd., New Delhi.									
3	K.L.Sharma, (1997) "Social Stratification in India: Issues and Themes", Jawaharlal Nehru University, New Delhi.									
4	U.R.Gahai, "Indian Political System", New Academic Publishing House, Jalaendhar									
5	R.N. Sharma, "Indian Social Problems", Media Promoters and Publishers Pvt. Ltd.									

CO'S	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	1	1	3	2	3	2	2	2	2	1	3	-	-	-
CO2	2	1	1	3	2	3	2	2	2	2	1	3	-	-	-
CO3	2	1	1	3	2	3	2	2	2	2	1	3	-	-	-
CO4	2	1	1	3	2	3	2	2	2	2	1	3	-	-	-
CO5	2	1	1	3	2	3	2	2	2	2	1	3	-	-	-

Cou	ırse	Counce No.	Но	urs/W	'eek	Credit	Maximum
Co	ode	Course Name	L	T	P	C	marks
24HS	21003	Interview Skills and Soft Skills (Common to all B.E./B.Tech. Degree Programmes)	0	1	2	2	100
Objec	ctives	 To improve the learners reading fluence To help the learners obtain speaking states To make them acquire presentation states 	kills in	both fo	ormal a	and informa	l situation.
		LIST OF EXPERIME	NTS				
1	Employabil	ity Skills (Interpersonal, Intrapersonal, Leader	ship, D	ecision	Maki	ng and Prob	olem Solving)
2		cabulary (Advanced level)					٠,
3	Short Conve	ersations (Situation Based Dialogues)					
4	Art of Story	telling					
5	-	E-mail Writing					
6		ne Page Resume					
7		cills (Mock Interview & Interview Etiquette)					
8		Etiquette (Polite Expressions, Telephone Etiq	uette, C	nline l	Etique	tte)	
9	Group Discu		·				
10	Public Speal						
		·	,	Total	hours	s 30	
Outcome(s)	AnaCrea	the course, the learners will be able to: lyse the content and apply knowledge and skill te profile and other essential documents. honstrate soft skills effectively at the time of in		•		•	y.
TEXTBOOL	K						
1		ohan, Soft Skills, 1st Edition. Bookboon, 2017					
REFERENC	1						
1		akshi & Sangeeta Sharma, <i>Technical Commun</i> ess, New Delhi. 2015.	iication	: Princ	ciples (and Practic	e, Ed.III, Oxford
2	Barun K. Mit	ra, Personality Development and Soft Skills, O	xford U	Jnivers	sity Pre	ess, New De	elhi, 2011
ONLINE W	EBSITES						
1	https://www.	ted.com/talks					
2	https://www.j						
3	https://quizziz						
4	www.pdfdriv						
5	www.talking	books.com					

PO CO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	2	2	2	1	2	2	2	2	3	3	2	2	1
CO2	2	1	1	1	2	1	1	1	2	3	3	3	1	1	1
CO3	2	1	1	1	2	1	1	1	3	3	3	3	1	1	1

Cour	·se	G V	Ho	urs/W	eek	Credit	Maximum
Cod		Course Name	L	T	P	С	marks
24ME2	4501	Thermal Engineering Laboratory	0	0	3	1.5	100
Objectiv	e(s)	 To integrate the concepts, laws and methodologie the analysis of cyclic process. To apply the thermodynamic concepts into variou turbines, Compressors and Refrigeration and Air CLIST OF EXPERIMEN 	is therr	nal app	olicatio	on like I.C	•
1	Valve	Timing and Port Timing Diagrams	~				
2		mance Test on 4-Stroke Diesel Engine					
3		Balance Test on 4-Stroke Diesel Engine					
4		Test on Multi-Cylinder Petrol Engine					
5	Retard	lation Test to find Frictional Power of a Diesel Engine					
6		mination of Viscosity by Red Wood Viscometer					
7	Deterr	mination of Flash Point and Fire Point					
8	Perfor	rmance and Energy Balance Test on a Steam Generator	•				
9	Perfor	rmance and Energy Balance Test on Steam Turbine					
10	Perfor	rmance test on Two Stage Air Compressor					
11	Deterr	mination of COP of a refrigeration system					
12	Deterr	mination of COP of air-conditioning system					
			,	Total 1	hours	45	
LIST OF		PMENTS					
1		ngine – 2 stroke and 4 stroke model -1 each					
2	Red W	Vood Viscometer- 1 No.					
3		ratus for Flash and Fire Point -1 No each					
4		ke Diesel Engine with mechanical loading- 1 No.					
5	4-strol	ke Diesel Engine with electrical loading- 1 No.					
6	Multi	-cylinder Petrol Engine -1 No.					
7	Single	e cylinder Petrol Engine -1 No.					
8	Steam	Boiler with turbine setup.					
9	Refrig	geration test rig-1No.					
10	Air-Co	onditioning test rig-1No.					
Outcome	e(s)	 Identify and explain the different parts of petrol diagrams. Explain and differentiate various types of boils mounting and accessories. To Evaluate the Heat Balance Sheet of IC engine 	ers and				

PO CO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	2	3	1	1	-	-	1	-	-	-	1	-	1	3
CO2	3	2	3	1	1	-	-	1	-	-	-	1	-	1	3
CO3	3	2	3	1	1	-	-	1	-	-	-	1	-	1	3

	~ .	Course Nove	Hou	ırs/W	eek	Credit	Maximum				
Course (Code	Course Name	L	T	P	C	marks				
24ME	24502	Manufacturing Laboratory	0	0	3	1.5	100				
Objective(s)		 To impart hands-on experience in basic moulding, gear cutting, and thread cuttin To familiarize students with the working including lathe, milling, grinding, shapin To develop practical skills in precise production environments, including surface 	g using ng prin ng, and s ion ma	convections convec	entiona setup g mach ng and	al machine, and oper nines.	tools. ations of machines processes used in				
		LIST OF EXPERIME					•				
1	Prepare a m	ould using solid/split patterns in Foundry.									
2	Thread cutti	ng operation in centre lathe									
3	Exercise on	capstan Lathe and Turret lathe									
4	Spur Gear c	utting using Milling machine									
5	Centre less g	grinding									
6	Cylindrical	grinding									
7	Round to sq	uare machining using shaper machining									
8	Tool and cu	tter grinding machine									
9	Internal key	way slotting in slotting machine									
10	Surface grin	ding									
T TOWN OR DO		9		Fotal	hours	45					
	QUIPMENT										
1		olding tool setup -4Nos.									
2	Centre lathe										
3	Turret Lathe										
4	Capstan Lat										
5		Milling Machine -1No									
6		nding Machine -1No									
7	-	Grinding Machine -1No									
8	1										
9	Slotter -1No										
10	+	achine -1No									
11		atter grinder -1No									
12		grinding machine -1No									
Outcome(s)		lity to use different machine tools for finishing of lity to use different machine tools to manufacture.									
		lity to manufacture tools using cutter grinder	g gc	uo.							
	1101	CO MAPPING WITH POS AN	ID DCC	١,,							

PO CO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	-	-	3	-	-	-	3	1	-	-	3	3	1	-
CO2	2	-	-	3	-	-	-	3	1	-	-	3	3	1	-
CO3	2	-	-	3	-	-	-	3	1	-	-	3	3	1	-

		Hou	ırs/W	eek	Credit	Maximum
Course Code	Course Name	L	T	P	C	marks
24ME25501	Internship	0	0	2	1	100
Objective (s)	 Students shall develop the habit to work in a gree. To provide opportunities for students to app. To expose students to industrial working environments. 	ly thei		vledge	in a real	world environment.

Industrial case study should be based on the study of some specific case / issue/ problem related to any Industry. Data should be collected from Industry with the objective of studying some specific case / issue / problem. The Collected data should be analysed using knowledge gained in the curriculum. The Result should be worked out and conclusion should be drawn. A group of maximum of four students may be formed for one case study.

Note: Students have to undergo two weeks internship in an industry between 4th and 5th semester. A report consisting of the problem / issues identified methodology of data collection, method of analysis, results and conclusion should be submitted in the prescribed format at the end of the industrial training and the evaluation will be done by a committee constituted by the HOD. Minimum two presentations should be made as a part of internal evaluation. Each student/group of students must present a PPT for about 30 minutes. The presentation of industrial case study in conferences will be encouraged.

	Total hours 30
Outcome(s)	At the end of the course, the student will be able to:
	 Use of acquired techniques, skills, and modern engineering tools necessary for engineering
	practice
	 Understand their professional and ethical responsibilities.
	 Understanding the impact of engineering solutions in a global, economic, environmental,
	and societal context

PO CO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	3	2	3	3	2	3	1	2	3	2	3	2	2	3
CO2	1	2	1	2	1	2	2	3	2	3	2	2	2	1	1
CO3	2	2	2	2	1	3	3	2	2	2	2	2	1	1	3

Course code	Course Name	Н	ours/w	eek	Credit	Ma	ximum marks
24ME14601	Theory of Machines	L	T	P	С		100
24WIE14001	Theory of Wachines	3	0	0	3		100
Objective(s)	 To understand the concepts of kiner system/machine. To understand the concepts on kine screw jack, clutches and brakes. To understand the dynamic force ana To study the undesirable effects of ur To understand the principles of governments. 	matic an lysis, me	alysis of the state of the stat	of gear static	s and gear	train, th	ne role of friction in
UNIT-I	Basics of Mechanisms and Kinematic	Analysi	S				9
Kutzbach criterion (C Mechanical Advantag Analysis of simple	Kinematic pair, Kinematic chain, Mec Gruebler's equation) -Grashoff's law- Kin ge- Transmission angle. mechanisms (four bar mechanism and y and acceleration; – Coriolis components	nematic I	nversio	ns of f rank n	our-bar cha	in and	slider crank chain -
UNIT-II	Gears and Gear Trains						9
	rs – Gear tooth terminology - Fundament ontact ratio - Interference and undercutting						
UNIT-III	Friction and Dynamic Force Analysis						9
D'Alembert's princip	n in screw jack – Pivot and collar friction ble –Dynamic analysis of four bar mecha furning moment on crankshaft.						
UNIT-IV	Balancing and Free Vibration						9
unbalanced forces. Basic features of vib	alancing – Balancing of rotating masses – oratory systems – Free vibration – Equa						nary and secondary
UNIT-V	n – Whirling of shafts and critical speed.	ations of	motion	- nat	ural frequei	ncy – I	Types of Damping -
	· ·			– nat	ural freque	ncy – I	Types of Damping -
Governors – Types –	n – Whirling of shafts and critical speed. Forced Vibration and Mechanisms fo forcing – Harmonic Forcing – Forced vib - Centrifugal governors – Gravity contro	r Contro	ol nused by	unbal	ance-Vibrat	ion isol	9 ation.
	n – Whirling of shafts and critical speed. Forced Vibration and Mechanisms fo forcing – Harmonic Forcing – Forced vib - Centrifugal governors – Gravity contro	r Contro	ol nused by	unbal	ance-Vibrat	ion isol	9 ation.
Governors – Types –	Forced Vibration and Mechanisms for forcing – Harmonic Forcing – Forced vibration and Security Control Gyroscopic couple. Upon the completion of this course the security analytical or graphical method Compute significant terminology of Apply the concepts of friction and machine members as per design theory ibrations.	r Contro	bused by spring will be celerated d gear the mic for ating and	able to on of s rains uce ana	ance-Vibrat lled centrifu Total I simple and a sing design llysis on re- rocating ma	ion isolugal go nours inversion theorie otating	9 ation. vernors— Effect of 45 ons of mechanisms es. and reciprocating parts balancing and
Governors – Types – friction. Gyroscopes -	Forced Vibration and Mechanisms for forcing – Harmonic Forcing – Forced vibration – Gravity controgenerated entrifugal governors – Gravity controgenerated entrifusal governors – Gravity controgenerated entrifficient	r Contro oration ca oration ca oration ca students or and account gears and d dynamories.	bused by spring will be celerated d gear the foresting and l, gravit	able to on of s rains uce ana	ance-Vibrat lled centrifu Total I simple and a sing design llysis on re- rocating ma	ion isolugal go nours inversion theorie otating	9 ation. vernors— Effect of 45 ons of mechanisms es. and reciprocating parts balancing and

TEXT	BOOK:
1	Khurmi, R.S., and Gupta, J.K., "Theory of Machines", 14th Edition S.Chand & Company, Ltd., New Delhi, 2005
2	Ambekar A. G., Mechanism and Machine Theory, Prentice Hall of India, New Delhi, 2007.
3	S.S. Rattan, "Theory of Machines", Third Edition, Tata McGraw-Hill Publishing Company Ltd., New Delhi, 2009.
REFE	RENCES:
1	V.P.Singh, "Theory of Machines", 7th Edition Dhanpat Rai & co. Ltd., New Delhi, 2009.
2	Ramamurti, V.,' Mechanism and Machine Theory", Second Edition, Narosa Publishing House, 2005.
3	Shigley J.E. and Uicker J.J., "Theory of Machines and Mechanisms", McGraw-Hill, Inc., 1995.
4	Thomas Bevan, "Theory of Machines", CBS Publishers and Distributors, 2005.
5	Ghosh A. and Mallick A.K., "Theory of Mechanisms and Machines", Affiliated East- West Press Pvt. Ltd., New
	Delhi, 1994.
6	Rao J.S. and Dukkipati R.V., "Mechanism and Machine Theory ", Wiley-Eastern Limited, New Delhi, 1992.
7	Sadhu Singh, "Theory of Machines" Pearson Education, 2002.

co's	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	2	2	2	-	-	-	-	1	-	1	3	-	-
CO2	3	3	3	2	2	-	-	-	-	1	-	1	3	2	-
CO3	3	3	3	2	2	-	-	1	1	2	1	2	3	-	-
CO4	3	3	2	3	2	-	-	1	1	2	-	2	3	-	2
CO5	3	3	3	3	2	1	2	1	1	2	-	2	2	-	3

Course code	Course Name	Но	ours/w	eek	Credit	Maximum marks
		L	T	P	C	
24ME14602	Heat and Mass Transfer	3	0	0	3	100
Objective(s)	 To introduce the various modes of wide variety of practical heat transfe To understand the concepts of heat to To provide useful information concests Systems. To learn the thermal analysis and desof mass transfer. 	r proble ransfer erning	ems. through the per	n exten formar	ded surface	s. ign of simple heat transf
UNIT-I	Conduction					9
	Conduction— Cartesian Coordinates — One Extended Surfaces —Heat flow in semi-infi			-		t Conduction – Plane an
UNIT-II	Convection				<u> </u>	9
	vection - Hydrodynamic and Thermal Bou Cylinders, Internal flow through tubes.	ındary	Layer.	Free a	nd Forced (Convection during extern
UNIT-III	Heat Transfer and Heat Exchangers					9
	er flow; evaporator and condensers, over e (LMTD), method of heat exchanger analy Thermal radiation					_
		04	:		: C 1:.	
	emissive power, absorption, transmission, real surfaces; radiation heat exchange be diation shields.					
UNIT-V	Mass Transfer					9
_	fusion Mass Transfer – Fick,,s Law of Diffi m, Heat and Mass Transfer Analogy– Conve		•			
					Total h	ours 45
Outcome(s)	 Understand the basic modes of heat to unsteady state heat transfer through concerns. Interpret and analyze free and forced. Design and analysis of heat exchange. Understand the Principle of Radiation Geometries and basic of Mass Transfer. Apply diffusive and convective mass. 	onducti convec r ı, Evalı er	ion tion uation o	f heat	transfer by	radiation between differe
TEXT BOOK:	113		-1			
1 R.C. Sachdev	a, "Fundamentals of Engineering Heat and	Mass tı	ransfer"	, New	Age Interna	ntional Publishers, 2010
2 Yunus A. Cen	igel, "Heat Transfer A Practical Approach"	– Tata	McGra	w Hill	5thEdition	-2013
REFERENCES:						
	"Heat and Mass Transfer", Tata McGraw F					
2 Kothandarama	an, C.P., "Fundamentals of Heat and Mass"	Transfe	er", Nev	v Age	Internationa	ıl, New Delhi, 2012
3 Ozisik, M.N.,	"Heat Transfer", McGraw Hill Book Co., 2	2013.				

- 4 S.P. Venkateshan, "Heat Transfer", Ane Books, New Delhi, 2014
- Frank P. Incropera and David P. Dewitt, "Fundamentals of Heat and Mass Transfer", John Wiley and Sons, 7th Edition, 2014.

co's	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	2	2	-	1	1	-	-	-	-	1	-	-	3
CO2	3	2	2	2	-	1	1	-	-	-	-	1	-	-	3
CO3	3	2	2	2	-	1	1	-	-	-	-	1	-	-	3
CO4	3	2	2	2	-	1	1	-	-	-	-	1	-	-	3
CO5	3	2	2	1	-	1	1	-	-	-	-	1	-	-	3

Course code	Course Name	Но	ours/w	eek	Credit	M	aximum marks
	Design of Transmission Systems	L	T	P	С		
24ME14603	(Use of PSG Data book is permitted)	3	0	0	3		100
Objective (s)	 To gain knowledge on the principles are Transmission components. To understand the standard procedure at elements spur gears and parallel axis here. To learn the design bevel, worm and cred to learn the concepts of design multi at the concepts of design to came. 	availab elical g ross he	le for Dears. lical gea able sp	esign of Teed gea	of Transmis Fransmission ar box for m	sion o n syste	f Mechanical
UNIT-I	Design of Flexible Drives						9
Selection and desig Chain drives and sp	n of Flat belts and pulleys – Selection and rockets	l desig	n of V	belts a	and pulleys	– Sel	ection and design of
UNIT-II	Design of Spur Gears and Parallel Axis	Helica	l Gear	5			9
Factor of safety - Considerations - Para	peed ratios and number of teeth-Force analy Gear materials – Module and Face width allel axis Helical Gears – Pressure angle in sees. Estimating the size of the helical gears.	n-power	rating	calcu	lations bas	sed on	strength and wear
UNIT-III	Design of Bevel and Worm Gears						9
	Tooth terminology- Design of pair of stra - Terminology. Thermal capacity, Design of Design of Gear Boxes	_	_				
	r forces for spur and helical gear. Geom				Ctandard a	ton #0	
	Design of reduction gearbox- design of mult					тер га	110 – Ray diagram,
UNIT-V	Design of Clutches and Brakes						9
Design of plate clut		al expa	nding r	im clut	ches –Desig	gn of l	orakes – Internal and
external shoe brake	ches – Axial clutches-Cone clutches-Internas.						
					Total l		
	Upon completion of this course, the Learne Apply the concepts of design to belts, Apply the concepts of design to spur, Apply the concepts of design to worm Apply the concepts of design to gear learners.	ers will , chains helical n and b boxes.	drives. gears. evel gea	ars.	Total l		
external shoe brakes Outcome(s)	 Upon completion of this course, the Learne Apply the concepts of design to belts, Apply the concepts of design to spur, Apply the concepts of design to worm 	ers will , chains helical n and b boxes.	drives. gears. evel gea	ars.	Total l		
Outcome(s) TEXT BOOK:	Upon completion of this course, the Learne Apply the concepts of design to belts, Apply the concepts of design to spur, Apply the concepts of design to worm Apply the concepts of design to gear learners.	ers will chains helical a and b boxes. es and c	gears. gears. evel gears.	ars.		nours	
Outcome(s) TEXT BOOK: 1 Bhandari V,	Upon completion of this course, the Learne Apply the concepts of design to belts, Apply the concepts of design to spur, Apply the concepts of design to worm Apply the concepts of design to gear learners.	ers will chains helical n and b boxes. es and c	gears. evel gears. elutches	ars.	Book Co, 20	nours	
Outcome(s) TEXT BOOK: 1 Bhandari V,	Upon completion of this course, the Learne Apply the concepts of design to belts, Apply the concepts of design to spur, Apply the concepts of design to worm Apply the concepts of design to gear to apply the concepts of design to brake "Design of Machine Elements", 3rd Edition,	ers will chains helical n and b boxes. es and c	gears. evel gears. elutches	ars.	Book Co, 20	nours	
Outcome(s) TEXT BOOK: 1 Bhandari V, 2 Prabhu. T.J. REFERENCES: 1 Joseph Shig	Upon completion of this course, the Learne Apply the concepts of design to belts, Apply the concepts of design to spur, Apply the concepts of design to worm Apply the concepts of design to gear to apply the concepts of design to brake "Design of Machine Elements", 3rd Edition, "Design of Transmission Elements", Mani	ers will chains helical n and b boxes. es and c	drives gears. evel gea elutches McGrav Chenn	ars. 7-Hill I	300k Co, 20 0.	010.	45 periods
Outcome(s) TEXT BOOK: 1 Bhandari V, 2 Prabhu. T.J. REFERENCES: 1 Joseph Shig Edition, Tat	Upon completion of this course, the Learne Apply the concepts of design to belts, Apply the concepts of design to spur, Apply the concepts of design to worm Apply the concepts of design to gear to apply the concepts of design to brake "Design of Machine Elements", 3rd Edition, "Design of Transmission Elements", Mani	ers will chains helical n and b boxes. es and control offset.	drives gears. evel gea elutches McGrav Chenn	r-Hill I ai, 200	Book Co, 20 0. nanical Engi	010.	45 periods ag Design", 8 th

Bernard Hamrock, Steven Schmid, Bo Jacobson, "Fundamentals of Machine Elements", 2ndEdition, Tata McGraw-Hill Book Co., 2006.
 Gitin Maitra, L. Prasad "Hand book of Mechanical Design", 2nd Edition, Tata McGraw-Hill, 2001.

CO'S	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2	3	-	-	1	-	1	-	-	-	-	2	1	-
CO2	2	2	3	-	-	1	-	1	-	-	-	-	2	1	-
CO3	2	2	3	-	-	1	-	1	-	-	-	-	2	1	-
CO4	2	2	3	-	-	1	-	1	-	-	-	-	2	1	-
CO5	2	2	3	-	-	1	-	1	-	-	-	-	2	1	-

Course code	Course Name	Н	ours/w	eek	Credit	Maximum marks
		L	T	P	C	
24ME16601	Principles of Management	3	0	0	3	100
Objective(s)	To enable the students to: To understand and the evolution To learn the principles of manage To illustrate the principles, concecontrolling To learn the importance of the principles.	ement epts and	import	ance of	planning, o	
UNIT-I	Introduction to Management and C	Organiz	zations	}		9
organization - Sole j Environment – Curre UNIT-II Nature and purpose	gement – Scientific, human relations ,sy proprietorship, partnership, company-publicant trends and issues in Management. Planning of planning – planning process – types Strategic Management – Planning Tools ar	of plar	nning –	object	enterprises tives – sett	Organization culture and 9 ing objectives – policies
UNIT-III Nature and purpose	Organising Formal and informal organization — organization	ranizatio	n chart	- orga	anization et	9
Nature and purpose staff authority – departments of the department of the course of the department of	 Formal and informal organization – orgartmentalization – delegation of authority ent – HR Planning, Recruitment, selection 	– centra	alizatior	and d	ecentralizat	ructure – types – Line and ion – Job Design - Human
Nature and purpose staff authority – dep	 Formal and informal organization – orgartmentalization – delegation of authority ent – HR Planning, Recruitment, selection 	– centra	alizatior	and d	ecentralizat	ructure – types – Line and ion – Job Design - Human
Nature and purpose staff authority – departments of the control of	Formal and informal organization – orgartmentalization – delegation of authority ent – HR Planning, Recruitment, selection management. Directing vidual and group behaviour – motivation richment – leadership – types and theories	n, Train	nlization ning and otivation ership -	and d d Deve	ecentralizat lopment, P	ructure – types – Line and ion – Job Design - Human erformance Management, 9 vational techniques – job
Nature and purpose staff authority – departments of the control of	Formal and informal organization – orgartmentalization – delegation of authority ent – HR Planning, Recruitment, selection management. Directing vidual and group behaviour – motivation	n, Train	nlization ning and otivation ership -	and d d Deve	ecentralizat lopment, P	ructure – types – Line and ion – Job Design - Human erformance Management, 9 vational techniques – job
Nature and purpose staff authority – deports of the control of the	Formal and informal organization – orgartmentalization – delegation of authority ent – HR Planning, Recruitment, selection management. Directing vidual and group behaviour – motivation richment – leadership – types and theories cation – effective communication – Comm	– centra n, Train on – mo of leade nunication	otivation ership -	n and d l Deve n theoreticomm T.	ecentralizat lopment, Posities – moti unication –	ructure – types – Line and ion – Job Design - Human erformance Management , 9 vational techniques – job process of communication 9 e of computers and IT in
Nature and purpose staff authority – department of the department of the staff authority – department of the staff authority – department of the staff action – job ender of the staff action of the staff	Formal and informal organization – orgartmentalization – delegation of authority ent – HR Planning, Recruitment, selection management. Directing vidual and group behaviour – motivation richment – leadership – types and theories cation – effective communication – Communication – Communication – Controlling of controlling – budgetary and non-budgetary	– centra n, Train on – mo of leade nunication	otivation ership -	n and d l Deve n theoreticomm T.	ecentralizat lopment, Posities – moti unication –	ructure – types – Line and ion – Job Design - Human erformance Management , 9 vational techniques – job process of communication 9 e of computers and IT in ect and preventive control –
Nature and purpose staff authority – deports of the control of the	Formal and informal organization – orgartmentalization – delegation of authority ent – HR Planning, Recruitment, selection management. Directing vidual and group behaviour – motivation richment – leadership – types and theories cation – effective communication – Communication – Communication – Controlling of controlling – budgetary and non-budgetary	on – more of leader ounication dependent of mana organizant processing theorem.	otivation ership control and polyton and p	n and d l Deve n theoreticomm T. techn perform	ries – motiunication – iques – use nance – direction. re direction.	ructure – types – Line and ion – Job Design - Human erformance Management , 9 vational techniques – job process of communication 9 e of computers and IT in ect and preventive control –
Nature and purpose staff authority – department of the control of	Formal and informal organization – orgartmentalization – delegation of authority ent – HR Planning, Recruitment, selection management. Directing vidual and group behaviour – motivation richment – leadership – types and theories cation – effective communication – Communication – Communication – Communication – Communication – Communication – budgetary and non-budgetary and management – Productivity problems and management At the end of the course the students will be described the evolution and functions in the course the students will be described the evolution and functions in the course the students will be described the evolution and functions in the course the students will be described the evolution and functions in the course the students will be described the evolution and functions in the course the students will be described the evolution and functions in the course the students will be described the evolution and functions in the course the students will be described to the course the course the students will be described to the course the c	on – more of leader ounication dependent of mana organizant processing theorem.	otivation ership control and polyton and p	n and d l Deve n theoreticomm T. techn perform	ries – motiunication – iques – use nance – direction. re direction.	ructure – types – Line and ion – Job Design - Human erformance Management , 9 vational techniques – job process of communication 9 e of computers and IT in ect and preventive control –
Nature and purpose staff authority – deparesource Managemer Career planning and UNIT-IV Foundations of indisatisfaction – job enderier in community UNIT-V System and process Management control reporting. Outcome(s) TEXT BOOK:	Formal and informal organization – orgartmentalization – delegation of authority ent – HR Planning, Recruitment, selection management. Directing vidual and group behaviour – motivation richment – leadership – types and theories cation – effective communication – Communication – Communication – Communication – Communication – Communication – budgetary and non-budgetary and management – Productivity problems and management At the end of the course the students will be described the evolution and functions in the course the students will be described the evolution and functions in the course the students will be described the evolution and functions in the course the students will be described the evolution and functions in the course the students will be described the evolution and functions in the course the students will be described the evolution and functions in the course the students will be described the evolution and functions in the course the students will be described to the course the course the students will be described to the course the c	on – more of leaden nunication detary to eather the of mana organization of the organi	otivation ership on and later to: agementation ers in the ries for control	n and d l Deve n theory comm T. techn perform e organ effectiv techni	ries – moti unication – iques – use nance – direction. re direction ques	ructure – types – Line and ion – Job Design - Human erformance Management , 9 vational techniques – job process of communication 9 e of computers and IT in act and preventive control – tours 45

REF	REFERENCES:										
1	Stephen A. Robbins & David A. Decenzo & Mary Coulter, —Fundamentals of Management Pearson Education, 7th Edition, 2011.										
2	Robert Kreitner & Mamata Mohapatra, — Managementl, Biztantra, 2008.										
3	Harold Koontz & Heinz Weihrich —Essentials of management Tata McGraw Hill, 1998										
4	Tripathy PC & Reddy PN, —Principles of Management, Tata McGraw Hill, 1999										

co's	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2	2	2	3	3	2	2	2	3	3	2	-	3	-
CO2	2	2	2	3	3	3	2	2	2	3	3	2	-	3	-
CO3	2	2	2	2	3	3	2	2	2	3	3	2	-	3	-
CO4	2	2	2	3	3	3	2	2	2	3	3	2	-	3	-
CO5	2	2	2	2	3	3	2	2	2	3	3	2	-	3	-

			Hou	ırs/W	eek	Credit	Maximum
Co	urse Code	Course Name	L	Т	P	С	marks
24	ME24601	Theory of Machines Laboratory	0	0	3	1.5	100
Objec	tive(s)	 To supplement the principles learnt in ki To understand how certain measuring de To understand techniques of vibration co 	vices ar		-		
		LIST OF EXPERIME					
1	Kinematics of velocity and a	of 4 bar mechanisms – Slider crank and acceleration	Crank	Rocke	r Me	chanism -	Determination of
2	Kinematics o	f Universal Joints – Determination of velocity a	and acc	eleratio	on		
3	Kinematics o	f Epi-cyclic Gear Trains – Determination of ve	locity ra	tio an	d Torq	Įue.	
4	Governors - 1	Determination of sensitivity, effort, etc. for any	one of	Gover	nors -V	Watt, Porter	, Proell
5	Motorized G	yroscope-Verification of laws -Determination of	of gyros	copic o	couple	•	
6	Whirling of s	haft-Determination of whirling / critical speed of	f shaft i	n trans	sverse	vibration.	
7	Dynamic bal	ancing of rotating masses in different planes.					
8	Determinatio	n of radius of gyration and moment of inertia of I.	C. engir	e conr	ecting	rod using	oscillation metho
9	Vibrating sys	stem – Determination of natural frequency of s	pring m	ass sy	stem w	ithout damp	er.
10	Determinatio	n of natural frequencies of compound pendulur	n using	oscilla	ition n	nethod.	
			, -	Fotal	hours	45	
IST OF E(QUIPMENT	S					
1	Kinematic M	Models to study various mechanisms – 1No.					
2	Universal jo	int apparatus– 1No.					
3	Gear train M	Iodel- 1No.					
4	Governor ap	paratus – Watt or Porter or Proell– 1No.					
5	Motorised g	yroscope- 1No.					
6	Whirling of	shaft apparatus– 1No.					
7	Dynamic ba	lancing machine– 1No.					
8	Connecting	rod– 1No.					
9	Vibration te	st facilities apparatus– 1No.					
10	Compound 1	pendulum apparatus— 1No.					
	At the end of	the course, the student will be able to:					
Dutcome(s)	1	ysis the kinematics of different mechanisms.					
		rmine the radius of gyration and moment of ine		-			
	• Calcu	late the vibration parameters in single degree of	of freed	om sys	tems.		

PO CO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	2	2	2	-	-	_	-	1	_	1	3	-	-
CO2	3	3	2	3	2	-	-	-	-	1	-	1	3	-	-
CO3	3	3	2	3	2	-	-	-	-	1	_	2	-	-	3

		Carrera Name	Ho	urs/W	eek	Credit	Maximum
Course	e Code	Course Name	L	T	P	C	marks
241	ME24602	Heat Transfer Laboratory	0	0	3	1.5	100
Objective(s)		To study the heat transfer phenomena a implementation	_				cient using
		To study the performance of refrigeration		e / com	ponen	its.	
		LIST OF EXPERIME	ENTS				
1	Thermal co	onductivity measurement using guarded plate a	pparatu	S.			
2	Thermal co	onductivity measurement of pipe insulation using	ng lagge	d pipe	appar	atus.	
3	Determinat	ion of heat transfer coefficient under natural co	onvection	n fron	a ver	tical cylinde	r.
4		ion of heat transfer coefficient under forced co					
5		er from pin-fin apparatus (natural & forced cor				•	
6		ion of Stefan – Boltzmann constant.	rection	mode			
7		ion of emissivity of a grey surface.					
8		ess of Parallel / Counter flow heat exchanger.					
	Determinat	ion of COP of a refrigeration system		T ()		4.5	
ICT OF FC	UIPMENT	<u> </u>		Total	hours	s 45	
1 1	-	te apparatus – 1No.					
2		apparatus – 1No.					
3		vection-vertical cylinder apparatus – 1 No.					
4		rection inside tube apparatus – 1No.					
5	-	ratus – 1 No.					
6		zmann apparatus – 1 No.					
7	Emissivity n	neasurement apparatus – 1 No.					
8	Parallel/cou	nter flow heat exchanger apparatus – 1No.					
9	Refrigeratio	n test rig – 1No.					
		ate the overall heat transfer coefficient by usin	g of for	ced and	d natu	ral convection	on modes.
Outcome(s)		nine the Stefan-Boltzmann constant					
	Exami	ne the COP of the Refrigeration					

PO CO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	-	-	-	-	2	-	-	-	-	-	2	-	-	3
CO2	2	3	-	-	-	2	-	-	3	-	-	2	-	-	3
CO3	2	3	-	-	-	2	-	-	3	-	-	2	-	-	3

Course	Commo Nomo	Hou	ırs/W	⁷ eek	Credit	Maximum				
Code	Course Name	L	T	P	C	marks				
24ME36601	Design and Fabrication Project	0	0	4	2	100				
Objective(s)	• The main objective is to give an opportunity fabrication of one or more components of a them.				•	•				
Outcome(s)		this course the students will be able to te the machine element or the mechanical product. orking model of the machine element or the mechanical product.								
	Guideline for Review and E	valua	tion							

The students may be grouped into 2 to 4 and work under a project supervisor. The device/ system/component(s) to be fabricated may be decided in consultation with the supervisor and if possible with an industry. A project report to be submitted by the group and the fabricated model, which will be reviewed and evaluated for internal assessment by a Committee constituted by the Head of the Department. At the end of the semester examination the project work is evaluated based on oral presentation and the project report jointly by external and internal examiners constituted by the Head of the Department.

Total hours 45

CO'S	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	2	3	2	2	3	2	2	1	1	3	3	2	1
CO2	3	3	2	3	2	2	3	2	2	1	1	3	3	2	1

Course code	Course Name	Но	ours/w	eek	Credit	Maximum marks
		L	Т	P	C	100
24ME14701	Industrial Automation	3	0	0	3	100
Objective(s)	 To define automation and Control and To provide knowledge on actuators and To understand about the material hand To underline the basic objectives of a 	d industr ling dev	rial con	trollers automa	s. ation.	
UNIT-I	control technologies relate to these. Introduction to Automation					9
Definition and f	undamentals of automation, reasons for Autonatrol system Advanced automation functions: saf	_				tomated system: Power
UNIT-II	Pneumatics and hydraulics					9
their applications	seumatic devices-Different types of valves, Actus and use of their ISO symbols Synthesis and sydraulics Design of Electro-Pneumatic Circuits us.	design o	of circu	its (up	to 3 cylin	nders)-pneumatic, electro
UNIT-III	Sensors and Transducers					9
Selection of Sens	ximity; Velocity, Motion, Force, Fluid Pressure, ors.	1	,	1	, . ,	8
Accuracy and rep control, Control	Robots and their applications robots, Types, Classifications, Selection of robeatability, Specification of a robot, Robot feedbests for robot joint, Adaptive control, Drives	ack cor	trols: I	Point to	point con	trol and Continuous path
Introduction to a Accuracy and repcontrol, Control applications of ro	robots, Types, Classifications, Selection of robeatability, Specification of a robot, Robot feedbesystem for robot joint, Adaptive control, Drives obots.	ack cor	trols: I	Point to	point con	m, Robot configuration trol and Continuous path
Introduction to a Accuracy and repcontrol, Control applications of round UNIT-V Introduction to Identify Introduction Identify Identification Identification Identify I	robots, Types, Classifications, Selection of robots, Types, Classifications, Selection of robots, Robot feedbaystem for robot joint, Adaptive control, Drives abots. Introduction to IOT and Applications oT – Meaning and features – Basic components	and trai	ntrols: Insmission	Point to on syst	point contems, End e	m, Robot configuration trol and Continuous path effectors, Industrial robot 9 cessing – IoT protocols –
Introduction to a Accuracy and repcontrol, Control applications of round UNIT-V Introduction to Identify Introduction Identify Introduction Identify Introduction Identify Introduction Identify Introduction Identify Identify Introduction Identify Ide	robots, Types, Classifications, Selection of robots, Types, Classifications, Selection of robots, Robot feedby, system for robot joint, Adaptive control, Drives bots. Introduction to IOT and Applications	and trai	ntrols: Insmission	Point to on syst	point contems, End e	m, Robot configuration trol and Continuous path effectors, Industrial robot 9 cessing – IoT protocols -d challenges of IoT.
Introduction to a Accuracy and repcontrol, Control applications of rounting UNIT-V Introduction to Id Security and prive Outcome(s)	robots, Types, Classifications, Selection of robots, Types, Classifications, Selection of robots deatability, Specification of a robot, Robot feedby system for robot joint, Adaptive control, Drives obots. Introduction to IOT and Applications OT – Meaning and features – Basic components – acy – Applications in smart homes, healthcare, in • Describe the automation components ar • Explain automated controls using Pneur • Evaluate the feedback control systems ir • Elucidate the application of Industrial robots • Apply IOT concepts in smart and automated controls in the second controls in the second controls in the second control in the second contro	- Sensor adustry, and systematic an automobotics.	rs, connagricult ms appl d hydra ated sy	Point to on systematic properties of the control of	y, data prod Benefits and Total hou	m, Robot configuration, trol and Continuous path effectors, Industrial robot 9 cessing – IoT protocols – d challenges of IoT.
Introduction to a Accuracy and repcontrol, Control applications of rounting UNIT-V Introduction to Id Security and prive Outcome(s)	robots, Types, Classifications, Selection of robetablity, Specification of a robot, Robot feedbest for robot joint, Adaptive control, Drives obots. Introduction to IOT and Applications OT – Meaning and features – Basic components acy – Applications in smart homes, healthcare, in • Describe the automation components ar • Explain automated controls using Pneur • Evaluate the feedback control systems ir • Elucidate the application of Industrial robots • Apply IOT concepts in smart and autom	- Senson dustry, and systematic and automobotics.	rs, connagricult ms appl d hydra ated sy	Point to on systematic properties of the control of	y, data prod Benefits and Total hou	m, Robot configuration trol and Continuous path effectors, Industrial robo 9 cessing – IoT protocols -d challenges of IoT.
Introduction to a Accuracy and representations of rose unit-v Introduction to Id Security and prive Outcome(s) TEXT BOOK: 1 Mecha	robots, Types, Classifications, Selection of robetability, Specification of a robot, Robot feedbest for robot joint, Adaptive control, Drives obots. Introduction to IOT and Applications OT – Meaning and features – Basic components - acy – Applications in smart homes, healthcare, in Describe the automation components ar Explain automated controls using Pneur Evaluate the feedback control systems if Elucidate the application of Industrial robots in smart and autom Apply IOT concepts in smart and autom tronics – W.Bolton, Pearson Education India, Ne	- Sensor and systematic and automobotics.	rs, connagricult ms appl d hydra ated sy stems.	Point to on systemectivite nectivitesure – l ication nulic system.	y, data prod Benefits and Total hou	m, Robot configuration trol and Continuous path effectors, Industrial robot 9 cessing – IoT protocols - d challenges of IoT. Irs 45
Introduction to a Accuracy and repcontrol, Control applications of rounting UNIT-V Introduction to Id Security and prive Outcome(s) TEXT BOOK: 1 Mechanical A. K. Control of the Accuracy and prive A. K. Control of the Accuracy and prive Accuracy and representations of rounting applications of rounting the Accuracy and prive Accuracy and representations of rounting applications of rounting the Accuracy applications of rounting applications of rounting applications of rounting the Accuracy and representations of rounting applications of rounting applications of rounting the Accuracy and representations of rounting applications of rount	robots, Types, Classifications, Selection of robetablity, Specification of a robot, Robot feedby system for robot joint, Adaptive control, Drives obots. Introduction to IOT and Applications OT – Meaning and features – Basic components acy – Applications in smart homes, healthcare, in • Describe the automation components ar • Explain automated controls using Pneur • Evaluate the feedback control systems ir • Elucidate the application of Industrial re • Apply IOT concepts in smart and automs: tronics – W.Bolton, Pearson Education India, Neuropea, S. K. Arora, "Industrial Automation and Research and Research are represented by the second systems in th	- Senson dustry, and systematic and nautomobotics. mated systematic and systemati	rs, connagricult ms appl d hydra ated sy stems. 2007.	Point to on systematic properties of the control of	y, data prod Benefits and Total hou	m, Robot configuration trol and Continuous path effectors, Industrial robo 9 cessing – IoT protocols -d challenges of IoT. urs 45 w Delhi 2009
Introduction to a Accuracy and representations of round applications of round unit-V Introduction to Id Security and prive Outcome(s) TEXT BOOK 1 Mechan 2 A. K. G. 3 M.P.Gri	robots, Types, Classifications, Selection of robetability, Specification of a robot, Robot feedby system for robot joint, Adaptive control, Drives obots. Introduction to IOT and Applications oT – Meaning and features – Basic components acy – Applications in smart homes, healthcare, in • Describe the automation components ar • Explain automated controls using Pneur • Evaluate the feedback control systems ir • Elucidate the application of Industrial re • Apply IOT concepts in smart and autom tronics – W.Bolton, Pearson Education India, Neurover, "Automation, Production Systems and proover, "Automation, Production Systems and proover, "Automation, Production Systems and proover, "Automation, Production Systems and property in the property of	- Senson dustry, and systematic and nautomobotics. mated systematic and systemati	rs, connagricult ms appl d hydra ated sy stems. 2007.	Point to on systematic properties of the control of	y, data prod Benefits and Total hou	m, Robot configuration trol and Continuous path effectors, Industrial robo 9 cessing – IoT protocols -d challenges of IoT. urs 45
Introduction to a Accuracy and repcontrol, Control applications of rounting UNIT-V Introduction to Id Security and prive Outcome(s) TEXT BOOK 1 Mechan 2 A. K. G 3 M.P.Gr New D 4 Geoffre	robots, Types, Classifications, Selection of robots, Types, Classifications, Selection of robots, Robot feedbesystem for robot joint, Adaptive control, Drives obots. Introduction to IOT and Applications OT – Meaning and features – Basic components – acy – Applications in smart homes, healthcare, in • Describe the automation components ar • Explain automated controls using Pneur • Evaluate the feedback control systems ir • Elucidate the application of Industrial robots – W.Bolton, Pearson Education India, Neuropean, S. K. Arora, "Industrial Automation and Report, "Automation, Production Systems and Pelhi, Fourth Edition, 2016. Tooyer, "Automation, Production Systems and Pelhi, Fourth Edition, 2016. Telephore of the Apply IOT concepts and Winston A. For the Polymer Polymer and Winston A. For the Polymer Polymer Polymer and Winston A. For the Polymer Po	- Sensor and systematic and automobotics. nated systemated systema	rs, connagricult ms appl d hydra ated sy stems. 2007. ' Laxmier Integ	Point to on systematic properties of the propert	y, data prod Benefits and Total hours.	m, Robot configuration trol and Continuous path effectors, Industrial robot 9 cessing – IoT protocols – d challenges of IoT. Irs 45 w Delhi 2009 ring, Pearson Education
Introduction to a Accuracy and repcontrol, Control applications of rounting UNIT-V Introduction to Id Security and prive Outcome(s) TEXT BOOK: 1 Mecha 2 A. K. C. 3 M.P.G. New D. 4 Geoffred CRC P. 5 M.P. C.	robots, Types, Classifications, Selection of robetability, Specification of a robot, Robot feedbest for robot joint, Adaptive control, Drives obots. Introduction to IOT and Applications OT – Meaning and features – Basic components – acy – Applications in smart homes, healthcare, in • Describe the automation components ar • Explain automated controls using Pneur • Evaluate the feedback control systems ir • Elucidate the application of Industrial robots – Apply IOT concepts in smart and autom tronics – W.Bolton, Pearson Education India, Neurover, "Automation, Production Systems and relehi, Fourth Edition, 2016.	- Senson dustry, - Senson dustry, - Senson dustry, - March System attic and automobotics. - March System atticular and automobotics. - March System a	rs, connagricult ms appl d hydra ated sy stems. 2007. 'Laxmier Integ	Point to on systematic properties of the propert	y, data prod Benefits and Total hound.	m, Robot configuration trol and Continuous path effectors, Industrial robo 9 cessing – IoT protocols - d challenges of IoT. urs 45 w Delhi 2009 ring, Pearson Education ufacture and Assembly

1	HMT, "Mechatronics", Tata McGraw-Hill Publishing Company Limited, New Delhi, 2005.
2	Bradley, D.Dawson, N.C. Burd and A.J. Loader, "Mechatronics: Electronics in Products and Processes", CRC Press 1991, First Indian print 2010.
3	Devdas shetty, Richard A. Kolk, "Mechatronics System Design", 2nd Edition, Cengag Learning 2011.

co's	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	1	-	-	-	-	2	-	-	-	-	2	1	3	-
CO2	3	3	3	2	-	-	-	-	-	-	-	2	3	3	-
CO3	3	1	-	-	2	-	-	-	-	-	-	2	1	2	-
CO4	3	3	2	-	2	-	-	-	-	-	-	2	2	2	-
CO5	3	1	-	-	3	2	2	-	-	-	-	2	1	2	-

Course	e code	Course Name	Но	ours/w	eek	Credit	Max	imum marks
			L	T	P	C		100
24ME	14701	Finite Element Analysis	3	0	0	3		100
Objectiv	ve(s)	 Mathematical formulation and solution Fundamentals of 1D Finite elements of 2D Finite elemen	for struc for Vector for struc	tural ar or analy tural ar	alysis /sis. alysis	and Axisyr	nmetric	
UNI	Т.І	Introduction	na name	ericai ii	llegran	OII		9
Historica continuo	l Backgr us model	round – Mathematical Modeling of field probles – Boundary, Initial and Eigen Value problems – Problems – Ritz Technique – Basic concepts of the	– Weigh	nted Re	sidual	Methods – `		ns – Discrete and
UNI	T-II	One-Dimensional Problems						9
of Shape mechanic deflection	functions and he are and N	Second Order Equations – Discretization – Elements and Stiffness matrices and force vectors-at transfer. Longitudinal vibration frequencies a atural frequencies of beams.	Assembland mod	ly of N	1 atrice	s - Solution	n of pro	blems from solid
UNI	Γ-III	Two Dimensional Scalar Variable Problem	ıs					9
Second C Triangula		D Equations involving Scalar Variable Function of the Shape functions and element matrices and vertices and vertices are vertically as a second of the secon		ational	formu	lation–Finite	e Eleme	ent formulation-
UNI	Γ-IV	Two Dimensional Vector Variable Problem	ıs					9
		e problems— Elasticity equations— Plane ement matrices— Assembly— boundary conditions					-	netric problems-
UNI	T-V	Isoparametric Formulation						9
- Serend	ipity ele	te systems – Isoperimetric elements – Shape fur ements – Numerical integration and application ques to Dynamic problems – Introduction to Ana	n to plan	ne stre				
						Total hou	rs	45
Outcom		 Develop mathematical models for boundary Apply the concepts of Finite Element Analy Apply the concepts of Finite Element Analy Apply the concepts of Finite Element Analy Analyze the Isoparametric transformation and 	vsis to so vsis to so vsis to so	olve one olve two	diment diment diment	nsional prob nsional prob nsional prob	lem in st lems in s lems in s	ructural analysis scalar analysis
TEXT E			1 12 0 0	l 				
1	Reddy	J.N., "An Introduction to the Finite Element Met	thod",3"	Editio	n, Tata	McGraw-H	111.2019.	
2	Seshu	P,"Text Book of Finite Element Analysis",Prent	ice-Hall	of India	a Pvt.L	td., New De	elhi.2018	3.
3	Chand Div,20	lrupatla & Belagundu, "Introduction to Finite Eler 019.	ments in	Engine	ering"	,3rd Edition	Prentice,	HallCollege
REFER	ENCES	S:						
1	Rao,S	S., "The Finite Element Method in Engineering",	,3 rd Edit	ion, Bu	tterwo	rth Heinema	nn, 2018	}
2	Logan	,D.L., "A first course in Finite Element Method",	Thomso	n Asia	Pvt.Ltd	d2017.		
3	Rober	t D.Cook, David S.Malkus, Michael E.Plesha, ent Analysis", 4 th Edition, Wiley Student Edition,	Robert .				plication	nsof Finite

co's	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	2	3	-	-	1	-	1	1	-	-	1	1	1	1
CO2	1	2	3	-	-	1	-	1	1	-	-	1	1	1	1
CO3	1	2	3	-	-	1	1	1	1	1	-	1	1	1	1
CO4	1	2	3	-	-	1	-	1	1	1	-	1	1	1	1
CO5	1	2	3	-	-	1	-	1	1	-	-	-	1	1	1

Course code	Course Name	Н	ours/w	eek	Credit	M	aximum marks
24ME14703	Operations Research	L 3	T	P 0	C 3		100
Objective (s)	 To understand the concepts of linear dissimilar circumstances. To find the optimized solutions at a models. To understand the concepts of game production processes. To determine the optimum lot size conditions. To understand the concepts of Proje planning, control and queue systems. 	range theory	mming of condand serventorie	models ditions quencing	using transing models t	portati o optir t of it	on and assignment mize the significant ems under diverse
UNIT-I	Linear Programming Models						9
Linear Programming	of Operation Research, OR Models and type: Introduction & Scope, Problem formula ms – Basic feasible solutions – unrestrice Transportation and Assignment Model	ation, cted va	Graphic	al Me	thod -The		
– MODI method to fi	em: Basic solutions - North West corner land optimal solution- degeneracy in transported Hungarian Method- Maximization proble	rtation			_		-
UNIT-III	Game Theory and Sequencing						9
Algebraic, Graphical	person Zero sum game, Solution with/wit and game problem as a special case of Line sumptions, n Jobs through 2-3 machines, 2	ear Pro	grammi	ng.	ominance ru	ıle, dit	fferent methods like
UNIT-IV	Inventory control and Replacement Mo	odels					9
inventory problems w	troduction, types of inventories, costs assovith no shortages, with shortages. ms: Introduction, replacement of items the					-	
UNIT-V	Project Management and Queuing Moo	dels					9
and PERT techniques	Basic Concept of network Scheduling, R in Project planning and control; crashing of aracteristics of Queuing Model, M/M/1 and	of opera	ations; 1	esourc	e allocation		oplications of CPM
					Total h	ours	45
Outcome(s)	 Upon completion of this course, the stu Apply the concepts of linear progradissimilar circumstances. Calculate the optimal solution of assignment Models. Determine the optimum solution of processing time using game theory a Compute the economic order quantification in the compute of the economic order quantification. Apply the concepts of network of management and queuing models. 	given from to nd sequenties of	minim he solu uencing invent odels.	els to ization tions s. ories a	problems of given p	using roblen s of re	transportation and and improve the eplacement of items

TEXT BOOK:

- 1 Operations Research An Introduction, by- Hamdy A. Taha, Pearson India, 9th Edition, 2014.
- 2 Operations Research- A.P. Verma, S.K. Kataria and Sons, 7th Edition, New Delhi, 2013.
- 3 Operations Research- S. Kalavathy, Vikas Publishing House Private Limited, 4th Edition, New Delhi, 2013.
- 4 Operations Research- R. Panneerselvam, PHI Learning Private Limited, New Delhi, 2nd Edition, 2012.
- 5 Problems in Operations Research by- Prem Kumar Gupta & D.S. Hira, S. Chand Publications, 2010.

REFERENCES:

1 Operations Research: Concepts and Cases" by Hillier and Liberman, McGraw-Hill, 10th Edition, 2017.

CO'S	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	3	-	-	-	1	-	1	-	-	2	-	-	3	-
CO2	2	3	-	-	-	1	-	1	-	-	2	-	-	3	-
CO3	2	3	-	-	-	1	-	1	-	-	2	-	-	3	-
CO4	2	3	-	-	-	1	-	1	-	-	2	-	-	3	-
CO5	2	3	-	-	-	1	-	1	-	-	2	-	-	3	-

Course code	Course Name	Ho	urs/w	eek	Credit	Maximum marks
24ME24701	Industrial Automation Laboratory	L	T	P	C	100
24111224701	industrial Automation Laboratory	0	0	3	1.5	100
Objective(s)	 To gain knowledge in basic electrical, hy single and double-acting cylinders. To know the concept of PLC and Micro-property of the concept of the concept	rocessei	in auto	omation	application	ons.

LIST OF EXPERIMENTS

- 1. Design and testing of direction control circuit using single and double acting cylinder and to demonstrate the working of the circuit.
- 2. Design and testing of pneumatic circuit with double acting cylinder using multiple sequences and to demonstrate the working of the circuit.
- 3. Design and testing of pneumatic circuit with double acting cylinder using push button in electro pneumatic trainer kit and to demonstrate the working of the circuit.
- 4. Design a circuit using timer for controlled retracted motion of a double acting cylinder and to demonstrate the working of the circuit.
- 5. Design and testing of hydraulic circuit with single acting and double acting cylinder using Hydraulic trainer kit to demonstrate the working of the circuit.
- 6. Speed control of a stepper motor with half step and full step resolution.
- 7. Design and demonstrate the sequential circuit using PLC.

systems.

8. Control the speed of PMDC motor using PID controller interfacing.

	Total hours	45
LIST OF EQU	IPMENTS	
1. Basic Pr	eumatic Trainer Kit with Manual controls – 1 No	
2. Basic Pri	eumatic Trainer Kit with Electrical and PLC Control -1 No	
3. Basic Hy	draulic Trainer Kit- 1No	
4. Program	mable Logic Controller unit-1 No	
	Upon completion of the course, students shall be able to:	
	Design the automatic control of single and double acting cylinders using ele	ectrical, hydraulic and
Outcome(s)	pneumatic systems.	
Outcome(s)	Design the PLC and micro controller circuit for automation applications.	
	• Demonstrate the electromechanical devices and stepper motor principles	in automatic control

co's	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2	3	-	2	1	-	1	-	-	-	1	-	3	-
CO2	2	2	3	-	2	1	-	1	-	-	-	1	-	3	-
CO3	2	2	3	-	2	1	-	1	-	-	-	1	-	3	-

CourseCode		Но	urs/V	Veek	Credit	Maximum
	Course Name	L	T	P	C	marks
24ME24702	Simulation Laboratory	0	0	3	1.5	100
Objective(s)	 To expose the students to the techniques generation through CNC simulation softwa. To educate the students on the usage of CA machine simulator To make the students understand the important manufacturing systems 	re by t AM pa	using (ckages	G-codes s and c	s and M-cooutting parts	les. on a virtual CNC
	LIST OF EXPERIM	ENT	S			
CNC SIMULATIO			~			
	CNC Lathe Operations					
	cle, Turning Cycle, Step Turning & Taper Turn	ning				
	g & Grooving					
	- CNC Milling Operations					
-	d Circular interpolation					
b) Mirroring	and Circular Pocketing					
CAE ANALYSIS						
	s of a plate with a circular hole					
	s of rectangular L bracket.					
	s of beams (Cantilever, Simply supported, Fixed	d ends).			
	s analysis of a 2D component.					
	eat transfer analysis of a 2D component.					
6. Convective he	eat transfer analysis of a 2D component.				ı	
			Fotal	hours	45	
	 Develop the tool path layout. 					
Outcome(s)	• Construct and simulate the part programmi	ng.				
	• Conduct static and thermal analysis for eng		ng con	nponen	ts.	

co's	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	2	-	-	3	1	-	1	3	1	-	1	-	-	3
CO2	1	2	-	-	3	1	-	1	3	1	-	1	-	-	3
CO3	1	2	-	-	3	1	-	1	3	1	-	1	-	-	3

Course	Convey Norma	Hou	ırs/W	eek	Credit	Maximum	
Code	Course Name	L	T	P	C	marks	
24ME36701	Project Work (Phase- I)	0	0	6	3	100	
Objective(s)	 To practice the steps involved for the selection To train the students for group activities to accompany 						
Outcome(s)	The students involves in identifying right promaking preliminary works towards phase II of				ring know	rledge on thatarea,	

The project work shall be an experimental / design and fabrication project on any of the topics of Mechanical engineering interest. The head of the department will decide the framing of the project batches. Each of the batches shall consist a minimum of four students. The topic of the project should be different from his/her mini project. A faculty member will always be supervising each group as an internal guide. In case an industrial project is selected by a batch, in addition to the internal guide, there should be an external guide from the industry.

During this semester, each group is required to select a topic for the project. A project evaluation committee will be constituted by head of the department at the beginning of the semester. A brief report of the chosen project should be submitted before the committee within two weeks from the beginning of the VII semester. The committee will give permission for the project after examining the feasibility. In the event of rejection of the topic by the committee, the students should resubmit a new project topic within one week, and get it approved by the committee. After getting the permission, they have to conduct a detailed literature survey, and collect sufficient information and necessary data.

25% of the total work to be done for the project work has to be completed by end of 7th semester. The same team of faculty will evaluate the project phase-I report. This evaluation will form 50% of the internal assessment mark. The remaining 50% of the internal assessment mark will be given at the end of the 8th semester, at the time of completing the project work.

the methal assessment mark will be given at the end of the our semester, at the time of completing the project work.	
Total hours 45	1

co's	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	3	2	2	1	1	2	3	2	2	3	3	3	2

Course code	Course Name	Ho	urs/w	eek	Credit	Maximum marks
24ME15101	Renewable Energy	L T P		C 3	100	
Objective(s)	 To understand the various solar e To understand the application of To understand the Bio energy sou To study the utilization of renew To understand the various types of 	wind energ arces able energ	gy and v y sourc	es for	both domest	·
UNIT-I	Solar Energy			-		9
heating, cooling, c types of solar cell	measurements and prediction - solar the desalination, power generation, drying, is and fabrication. Photovoltaic application eneration schemes. Cost Estimation and Wind Energy	cooking et	c - prii ery cha	nciple o	of photovolta	aic conversion of solar energy,
Resource assessm	ent - types of wind turbines - selection - off shore		•			- power regulation - various
UNIT-III	Bio Energy Sources					9
	nrious processes - Energy through ferme ysis - Bio energy through digestion - Ty					
UNIT-IV	Hydrogen and Fuel Cells					9
Hydrogen generat	and electrochemical principles - basic d ion from algae biological pathways - Sto working - various types - construction a	orage gase	ous, cry			
UNIT-V	Other Types of Energy					9
plants - principles	Ocean energy resources - principles of of ocean wave energy conversion and tues - geothermal energy - types of geoth	tidal energ	y conve	ersion -	- hydropowe	er – site selection, construction
					tal hours 4	15
	Upon completion of the course, stud			to:		
Outcome(s)	• Explain the various solar energ		ons			
()	Analyze the performance of wiDesign a bio-gas digester	na milis				
	 Explain the construction and w 	orking of e	lectroc	hemica	l cells	
	 Explain various methods for ha 	•				
TEXT BOOK:	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1			8	<i>J</i>	
D.P. Kotha Pvt. Ltd, 2	ari K. C. Singal, Rakeshranjan, "Renev 011.	vable Ener	gy Sou	rces ar	nd Emerging	Technologies", PHI Learning
2 Rai G D, "	Non-Conventional Sources of Energy",	6 th Edition	, Khanı	na Publ	ishers, New	Delhi, 2017.
REFERENCES:						
1 Sukhatme	S.P., "Solar Energy", Tata McGraw Hill	, 2008.				

co's	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	3	2	-	-	1	-	-	1	-	2	1	1	3
CO2	3	3	3	2	-	-	1	-	-	1	-	2	1	1	3
CO3	3	3	3	2	-	-	1	-	-	1	-	2	1	1	3
CO4	3	3	3	2	-	-	1	-	-	1	-	2	1	1	3
CO5	3	3	3	2	-	-	1	-	-	1	-	2	1	1	3

Cours	se code	Course Name	Н	ours/w	eek	Credit	Maximum marks
241/41	715102	Con Demonstrate and Lot Described	L	Т	P	C	100
24WIE	E15102	Gas Dynamics and Jet Propulsion	3	0	0	3	100
Objecti	ve(s)	 To understand the basic concept and To understand the basic difference bet To understand the basic concept for co To understand the phenomenon of sho To understand the Rocket engines an 	ween in onstant a	area duc es and i	essible a	and compres	heat transfer.
UN	IT-I	Fundamental of Gas Dynamics	a space	1118110			9
of Elast	icity, So	entum equations of compressible fluid flows -Sound Velocity. Mach waves and Mach cone Use of Gas tables.					
UNI	IT-II	Isentropic Flow With Variable Area					9
		een Isentropic and Adiabatic Processes- Mach on of Mach Number- Impulse Function- Mass Flo					
UNI	T-III	Fanno and Rayleigh Flow					9
	_	onstant area ducts with heat transfer (Rayleign f tables and charts – Generalized gas dynamics.	n flow)	and F	riction	(Fanno flo	w) – variation of flow
UNI	T-IV	Flow With Normal Shocks					9
		ons – Variation of flow parameters across the vergent nozzle with shock, Normal shock in Fan					
UN	IT-V	Space Propulsion					9
		engines – Propellants-feeding systems – Igni y – Staging – Terminal and characteristic velocit			s – spac	ce flights.	
						Total hour	rs 45
Outcon	ne(s)	 Upon the completion of this course the students Explain basic concepts of gas dynamic dimensional fluid flows. Analyze the flow through constant area Compute the flow characteristics using Calculate the flow parameters across no Apply gas dynamics principles in the jet 	es and of duct wi Rayleig rmal sh	describe th fricti th and F ock wa	e the b on and anno f ve	heat transfe low	_
TEXT]	BOOK:		•				
1	S.M. Y	ahya, fundamentals of Compressible Flow, New	Age Int	ernatio	nal (P)	Limited, Ne	ew Delhi, 6 th Ed., 2019
	Anderse	on, J.D., Modern Compressible flow, McGraw H	ill, 3 rd	Edition	n, 2003		
2	ENCES						
		'•					
	1	Somasundaram, Gas Dynamics and Jet Propulsi	ons, Ne	ew Age	Interna	ational Publi	shers, 1996.
REFER	PR.S.L.						shers, 1996.
REFER	PR.S.L.	Somasundaram, Gas Dynamics and Jet Propulsi	ine The	ory, Pre	entice I	Hall., 2001.	

CO'S	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	3	2	-	1	-	1	-	-	-	1	1	1	3
CO2	3	3	3	2	-	1	-	1	-	-	-	1	1	1	3
CO3	3	3	3	2	-	1	-	1	-	-	-	1	1	1	3
CO4	3	3	3	2	-	1	-	1	-	-	-	1	1	1	3
CO5	3	3	3	2	-	1	-	1	-	-	-	1	1	1	3

Course code	Course Name	Но	urs/w	eek	Credit	Maximum marks
24N/IE15102	D. Distance in the second seco	L	T	P	C	100
24ME15103	Power Plant Engineering	3	0	0	3	100
Objective(s)	 To understand the basic working of varie To learn the concepts of steam generat fullest use of thermal power potentialitie To understand the concepts of fuel comb To impart knowledge on nuclear, gas important role in power generation. To understand the concept of power from 	tors, comes of the coustion are turbine,	bustion country nd pollu hydro	and f ution m	iring methon nanagement diesel powe	ods in order to make the systems.
UNIT-I	Introduction to Power Plants					9
	tures - Components and layouts-Working princection of site-Analysis of steam cycles-Rankine					
UNIT-II	Steam Generators					9
circulation boile	ion-Types of Boiler-Fire tube and Water tubers-Fluidized bed boiler-Waste heat recoved enser-Cooling tower-Feed water treatment-Air	ry boile				
UNIT-III						
ONIT-III	Fuel Combustion and Pollution Managem	ent				9
Coal handling a systems-Cyclone	ruel Combustion and Pollution Managem nd preparation-Combustion equipment and fi furnace-Ash handling systems-Electrostatic s-Chimney- ISO and Statutory Requirement.	ring met				s Pulverized coal firin
Coal handling a systems-Cyclone	nd preparation-Combustion equipment and fi furnace-Ash handling systems-Electrostatic	ring met				s Pulverized coal firin
Coal handling a systems-Cyclone Induced draft fan UNIT-IV Principles of nuc Lives-Boiling w temperature gas c Radiation shield Regenerating-Coal	nd preparation-Combustion equipment and fi furnace-Ash handling systems-Electrostatic s-Chimney- ISO and Statutory Requirement. Nuclear and Gas Turbine Power Plants lear energy-Energy from nuclear reactions-Energy atter reactor-Pressurized water reactor- Pressurized water reactor- Pressuring-Waste disposal-Gas turbine power plant mbined cycle power plant	ring met preceptor ergy from surized I reactor-L	r-Fabric n fissio Heavy iquid r	n and Water	fuel Burn u Reactor-Cast breeder	s Pulverized coal firin house-Forced draft and polynomers and Halfas cooled reactor-Hig reactor-reactor materials poling - Reheating and polynomers.
Coal handling a systems-Cyclone Induced draft fan UNIT-IV Principles of nuc Lives-Boiling w temperature gas of Radiation shield Regenerating-ConUNIT-V	nd preparation-Combustion equipment and fi furnace-Ash handling systems-Electrostatic s-Chimney- ISO and Statutory Requirement. Nuclear and Gas Turbine Power Plants lear energy-Energy from nuclear reactions-Energy reactor-Pressurized water reactor- Pressurized water reactor- Pressuring-Waste disposal-Gas turbine power plant mbined cycle power plant Power From Renewable Energy	ergy from surized I reactor-L -Open a	-Fabric n fissio Heavy iquid r nd clo	n and Water netal fased cy	fuel Burn u Reactor-Cast breeder	s Pulverized coal firin house-Forced draft and policy poli
Coal handling a systems-Cyclone Induced draft fan UNIT-IV Principles of nuc Lives-Boiling w temperature gas of Radiation shield Regenerating-Countr-V Hydro Electric P	nd preparation-Combustion equipment and fi furnace-Ash handling systems-Electrostatic s-Chimney- ISO and Statutory Requirement. Nuclear and Gas Turbine Power Plants lear energy-Energy from nuclear reactions-Energy atter reactor-Pressurized water reactor- Pressurized water reactor- Pressuring-Waste disposal-Gas turbine power plant mbined cycle power plant	ergy from surized I reactor-L -Open a	r-Fabric n fissio Heavy iquid r nd clo	n and Water metal fa sed cy	fuel Burn u Reactor-Cast breeder voles-Interco	s Pulverized coal firin house-Forced draft and property of the
Coal handling a systems-Cyclone Induced draft fan UNIT-IV Principles of nuc Lives-Boiling w temperature gas c Radiation shield Regenerating-CoruNIT-V Hydro Electric P Construction and	nd preparation-Combustion equipment and fi furnace-Ash handling systems-Electrostatic s-Chimney- ISO and Statutory Requirement. Nuclear and Gas Turbine Power Plants lear energy-Energy from nuclear reactions-Energy are reactor-Pressurized water reactor- Pressurized water reactor- Pressuring-Waste disposal-Gas turbine power plant mbined cycle power plant Power From Renewable Energy ower Plants — Classification, Typical Layout	ergy from surized I reactor-L -Open a	r-Fabric n fissio Heavy iquid r nd clo	n and Water metal fa sed cy	fuel Burn u Reactor-Cast breeder voles-Interco	s Pulverized coal firin house-Forced draft and 9 up-Decay rates and Half as cooled reactor-Hig reactor-reactor materials poling - Reheating and 9 ding Turbines. Principle and, Biogas and Fuel Ce
Coal handling a systems-Cyclone Induced draft fan UNIT-IV Principles of nuc Lives-Boiling w temperature gas of Radiation shield Regenerating-Con UNIT-V Hydro Electric P Construction and power systems. Outcome(s)	nd preparation-Combustion equipment and fi furnace-Ash handling systems-Electrostatic s-Chimney- ISO and Statutory Requirement. Nuclear and Gas Turbine Power Plants	ergy from surized I reactor-L-Open a and associately, Sociately, S	r-Fabrican fission Heavy iquid rand clo clor The clor ment son and ment son nucle	n and Water metal fased cy comporermal, nciple firing ystems ar pow	fuel Burn u Reactor-C ast breeder veles-Interce ments inclue Geo Therm Total hou of various t methods in er plant.	s Pulverized coal firin house-Forced draft and part of the part of
Coal handling a systems-Cyclone Induced draft fan UNIT-IV Principles of nuc Lives-Boiling w temperature gas of Radiation shield Regenerating-Con UNIT-V Hydro Electric P Construction and power systems. Outcome(s)	nd preparation-Combustion equipment and fi furnace-Ash handling systems-Electrostatic s-Chimney- ISO and Statutory Requirement. Nuclear and Gas Turbine Power Plants	ergy from surized I reactor-L-Open a and associated work combustion manage ors used invarious re	rission fission Heavy iquid rand clo ciated colar The ing pri on and ment san nucle newable.	n and Water metal fa sed cy componermal, nciple firing ystems ar pow	fuel Burn u Reactor-C ast breeder reles-Interce ments inclue Geo Therm Total hou of various t methods in er plant. gy power pl	s Pulverized coal firin house-Forced draft and 9 up-Decay rates and Half as cooled reactor-High reactor-reactor materials cooling - Reheating and 9 ding Turbines. Principle and, Biogas and Fuel Celurs 45 upper of boilers. order to make the fulles and sants.
Coal handling a systems-Cyclone Induced draft fan UNIT-IV Principles of nuc Lives-Boiling w temperature gas of Radiation shield Regenerating-Con UNIT-V Hydro Electric P Construction and power systems. Outcome(s) TEXT BOOK:	nd preparation-Combustion equipment and fi furnace-Ash handling systems-Electrostatic s-Chimney- ISO and Statutory Requirement. Nuclear and Gas Turbine Power Plants	ergy from surized I reactor-L-Open a and associated work combustion manage ors used invarious re	rission fission Heavy iquid rand clo ciated colar The ing pri on and ment san nucle newable.	n and Water metal fa sed cy componermal, nciple firing ystems ar pow	fuel Burn u Reactor-C ast breeder reles-Interce ments inclue Geo Therm Total hou of various t methods in er plant. gy power pl	s Pulverized coal firin house-Forced draft and 9 up-Decay rates and Half as cooled reactor-High reactor-reactor materials cooling - Reheating and 9 ding Turbines. Principle and, Biogas and Fuel Celurs 45 upper of boilers. order to make the fulles and sants.

REFE	RENCES:
1	M. M. El-Wakil, 2002, Power Plant Technology, McGraw-Hill International Editions
2	Black and Veatch, 2005, Power Plant Engineering, CBS Pub and Distributors, New Delhi.
3	G.R. Nagpal, —Power Plant Engineering, Khanna Publishers, 2002.
4	R. K. Rajput, 2005, A Text Book of Power Plant Engineering, Laxmi Publications (P) Ltd.

CO'S	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	3	2	-	-	1	1	-	-	1	1	1	1	3
CO2	3	3	3	2	-	-	1	1	-	-	1	1	1	1	3
CO3	3	3	3	2	-	-	1	1	-	-	1	1	1	1	3
CO4	3	3	3	2	-	-	1	1	-	-	1	1	1	1	3
CO5	3	3	3	2	-	-	1	1	-	-	1	1	1	1	3

Co	ourse code	Course name	Но	urs/W	Credit	Maximum Marks	
2.4	D # F 1 5 1 0 4	Refrigeration and Air	L	T	P	C	100
24	ME15104	Conditioning	3	0	0	3	
O	bjectives	 To understand various concepts an To discuss about the vapor compre To learn the overall attributes of co To describe food freezing and equi To learn the concept of cold chain 	ession cy old stora pment i	cle and ge appl nvolved	its worlications	king principl in food indu zing process.	stries.
	UNIT-I	Introduction to Refrigeration					9
refriger piping	rating effect -Co and different con	refrigeration, refrigeration cycles, Remponents of a Refrigeration system: ntrols- COP - Representation of cycle refrigeration in different food products. Vapour Compression & Absorption	Compre on T-S	ssor, c and p-	ondense	r, Evaporato	r, Expansion valves
Vapour		efrigeration - working principle and			onents	of the plan	
compre	ession refrigeratio	n cycle - Vapor Absorption System - de	scription	n and w	orking o		
	UNIT-III	e of operation Three Fluid absorption system Psychometry	stem, sa	nem rea	uures.		9
Conside	eration of Infiltra	s & Processes- Characterization of S tion - Load concepts of RSHF, GSHF-					
	Calculations. UNIT-IV	Air Conditioning Systems					9
fans and	d blowers. Heat I	ns: Summer and Winter Air conditioning Pump - Heat sources - different heat pune ements of Industrial air conditioning-Au	np circui	ts. App	•	•	
transfer	UNIT-V	Cold Storage and Management					9
in-coole introduce - Impor	ers, and Refrigo ction, Construction rtant Factors to co	insulating materials, air diffusion equiperated container trucks: Freezer Stoon and Working; Cold Storage practice, onsider- logistic supply- Protocols for Ed Moisture monitoring.	rages, l Stackin	Freezer g and h	room andling	Temperature of materials	es, Cooling towers: Supply chain system
				,	Total h	ours :	45
0	Outcomes	 At the end of the course the students Illustrate the fundamental principle Select the properties, applications Describe the utility of different Air Demonstrate the predictive modeli Examine the Industrial application 	es and ap and envi conditi ng for sl	oplication ronmer oning s nelf life	ntal issue ystems f assessn	es of different for different a nent of foods	t refrigerants applications.
TEXT	ВООК	• • • • • • • • • • • • • • • • • • • •	•				
1	Arora, C.P., Re	frigeration and Air Conditioning, McGr	aw Hill,	3rd ed	, New D	elhi, 2010.	
2		"Advances in Food Refrigeration". Leat					
3	James, S.J. and	C. James. "Meat Refrigeration". CRC/	Woodh	ead Pul	liching	2002	

REFE	CRENCES
1	Roy J. Dossat, Principles of Refrigeration, Pearson Education Asia, 4th Edition, 2009.
2	Stoecker, W.F. and Jones J. W., Refrigeration and Air Conditioning, McGraw Hill, New Delhi, 1986.
3	Jones W.P., Air conditioning engineering, Elsevier Butterworth-Heinemann, 5th Edition,2001
4	Refrigeration commissioning guide for commercial and industrial systems, 2013.

CO'S	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	2	2	-	-	-	-	-	-	-	2	1	1	3
CO2	3	3	2	1	-	-	-	-	-	-	-	2	1	1	3
CO3	3	2	2	2	-	-	-	-	-	-	-	2	1	1	3
CO4	3	2	3	3	-	-	-	-	-	-	-	2	1	1	3
CO5	3	3	3	2	-	-	-	-	-	-	-	2	1	1	3

Course	code	Course Name	Но	urs/w		Credit	May	ximum marks
Course	Couc		L	T	P	Credit	IVIA.	amum marks
24ME15	5105	Heating Ventilation and Air Conditioning	3	0	0	3		100
Objective	e(s)	 To inculcate techniques of estimating but To understand the recent Air Condition To provide the knowledge of basic contechniques. To understand the effect of solar radiation To identify trouble shooting of HVAC seems 	ilding eing system incepts of and i	envelop ems of vent	load.	infiltration		_
UNIT		Building Survey						9
Thermal in conditions.	nfiltratio . Heatin	Heating and dehumidifying coils and air washer n, Periodic heat flow through building eleme g and cooling load calculations. Energy-effici HRAE) for building survey.	nts for	weath	er cond	litions all 1	ound	the year, tropical
UNIT-	-II	Introduction to Air Conditioning Systems						9
humidity ra	atio, de conditio	operties of moist air and psychrometric progree of saturation and enthalpy. Classification ning systems. Selection of air conditioning eitioning systems. Thermal storage air conditioning	of air quipme	condition	oning s	ystems –Si	ımmer	, winter and year
UNIT-	·III	Ventilation System						9
system; Ai	ir inlet : /stem; C	amentals of good indoor air quality need for be system, Filtering, heating and cooling equipment beneral exhaust system, local exhaust system as ss.	ent- Far	ıs, Duc	t, Grill	s, Diffuser	s for d	listribution of air.
UNIT-	-IV	Heating System						9
losses through calculation Hot water h	ough stru . Therm heating		solar ra transfe	diation	and in	ternal heat	source	es on heating load
UNIT		Industrial Applications OF HVAC Systems					- 1	
		TITLE D 1.	•		. 11		*1 1*	9
		in HVAC –Real time monitoring-Preventive matricines of system. Trouble shooting of HVAC quence of operation and general trouble shooting	systems	; A gen		_	_	inter-operability-
		ficiency of system. Trouble shooting of HVAC	systems	; A gen	eral gu	_	HVAC	inter-operability-
	tools, se	ficiency of system. Trouble shooting of HVAC	g proce pe able structu ondition provisi eating le	to res with one at a coad cal	n the eratems.	Total hour nvironment riate space.	HVAC	inter-operability- C troubleshooting-
diagnostic	tools, se	On completion of the course, students will Estimate heat transfer through building Illustrate the various methods of Air Co Develop the ventilation and infiltration Estimate the energy requirements for he	g proce pe able structu ondition provisi eating le	to res with one at a coad cal	n the eratems.	Total hour nvironment riate space.	HVAC	inter-operability- C troubleshooting-
Outcome((s)	On completion of the course, students will Estimate heat transfer through building Illustrate the various methods of Air Co Develop the ventilation and infiltration Estimate the energy requirements for he	pe able structu ondition provisi eating le	to res with sing sysons at a coad calency of	n the eratems.	Total hour nvironment riate space.	HVAC	inter-operability- C troubleshooting-
Outcome((s) OOK: Arora C	On completion of the course, students will Estimate heat transfer through building Illustrate the various methods of Air Co Develop the ventilation and infiltration Estimate the energy requirements for he Understand the ways of improvement in	g proce De able structu ondition provisi eating le n efficie	to to system of the control of the c	n the enterms. https://example.com/decompropersisted in the enterms. https://example.com/decompropersisted in the enterms. https://example.com/decompropersisted in the enterms. https://example.com/decompropersisted in the enterms.	Total hour avironment riate space.	HVAC	inter-operability- C troubleshooting-
Outcome((s) OOK: Arora C Manoha	On completion of the course, students will a Estimate heat transfer through building Illustrate the various methods of Air Co Develop the ventilation and infiltration Estimate the energy requirements for he Understand the ways of improvement in P, Refrigeration and Air Conditioning, Tata Mc Prasad, Refrigeration and Air-conditioning, W	g proce De able structu ondition provisi eating le n efficie	to to system of the control of the c	n the enterms. https://example.com/decompropersisted in the enterms. https://example.com/decompropersisted in the enterms. https://example.com/decompropersisted in the enterms. https://example.com/decompropersisted in the enterms.	Total hour avironment riate space.	HVAC	inter-operability- C troubleshooting-

2	HVAC Fundamentals Volume-1 / James E. Brumbou / Audel / 4th Edition.
3	Fundamentals of HVAC Systems / Robert Mcdowall / Academic Press / 2016.
4	Home Heating & Air Conditioning systems / James Kittle / MGH.

co's	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	2	2	1	-	-	-	-	-	-	1	1	1	3
CO2	3	2	2	2	1	-	-	-	-	-	-	1	1	1	3
CO3	3	3	2	2	1	-	-	-	-	-	-	1	1	1	3
CO4	3	3	2	2	1	-	-	-	-	-	-	1	1	1	3
CO5	3	2	2	2	2	-	-	-	-	-	-	1	1	1	3

Course code	Course Name	Credit	Maximum marks			
24ME15106	Computational Fluid Dynamics	L	Т	P	C	100
	0 0 1 1 p 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	3	0	0	3	200
Objective(s)	 To study the fluid flow simulation technique To learn the Discretise 1D and 2D systems u To Formulate diffusion –convection problem To study the flow field for different types of To learn the need for turbulence models and 	sing finns using grids	ite diff finite	erence	and finite v	
UNIT-I	Introduction	ns type	, <u>,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,</u>			9
Basics of Comp Boundary conditi of PDEs on CF	utational Fluid Dynamics – Governing equations & Types– Time-averaged equations for Turb D - Elliptic, Parabolic and Hyperbolic equation ques, Techniques of Discretisation and Numerical	oulent Fons, cor	Flow -	Classif	ication and	nd Energy equations - Mathematical behaviou
UNIT-II	Finite Difference and Finite Volume Method	ds for I	Diffusio	n		9
for steady and tra	te difference equations— General Methods for first insient diffusion 1D and 2D problems — Use of Fin in step-size, Euler, Crank-Nickolson, and pure imp	nite Di	fference	e and F	inite Volun	ne methods, Accuracy of
UNIT-III	Finite Volume Method for Convection Diffu				•	9
	nsional convection and diffusion – Central, up Power-law, QUICK Schemes, Computation of B					
- ,,,	, 1	•	, rajer	,	on reuman	ii stability alialysis.
UNIT-IV	Flow Field Analysis		-			9
UNIT-IV Stream function Pressure and Velo	Flow Field Analysis and vorticity, Representation of the pressure socity corrections – Pressure Correction equation,	gradient	t term,	Stagge	ered grid -	9 - Momentum equations
UNIT-IV Stream function Pressure and Vel-	Flow Field Analysis and vorticity, Representation of the pressure s	gradient	t term,	Stagge	ered grid -	9 - Momentum equations
UNIT-IV Stream function Pressure and Vel- Computation of in UNIT-V Turbulence mode number models,	Flow Field Analysis and vorticity, Representation of the pressure socity corrections – Pressure Correction equation, nternal and external thermal boundary layer.	gradient SIMPI Two e Technic	t term, LE algo	Stagge orithm a	ered grid – and its varia	9 - Momentum equations ants – PISO Algorithms 9 High and low Reynold
UNIT-IV Stream function Pressure and Velo Computation of in UNIT-V Turbulence mode number models, Fredrick Levy nu	Flow Field Analysis and vorticity, Representation of the pressure socity corrections – Pressure Correction equation, internal and external thermal boundary layer. Turbulence Modeling Pl requirement and types, mixing length model, LES, DNS, Mesh Generation and refinement imber, relaxation factor, and grid independence test	gradient SIMPI Two e Technic	t term, LE algo	Stagge orithm a (k-€) ftware	ered grid – and its varia	9 - Momentum equations ants – PISO Algorithms 9 - High and low Reynold solity of solver, Couran
UNIT-IV Stream function Pressure and Velo Computation of in UNIT-V Turbulence mode number models, Fredrick Levy nu	relaxation of the pressure ocity corrections – Pressure Correction equation, nternal and external thermal boundary layer. Turbulence Modeling relarequirement and types, mixing length model, LES, DNS, Mesh Generation and refinement mber, relaxation factor, and grid independence test. On completion of the course, students will be all Apply the fundamentals of CFD, and develoe Discuss finite difference and finite volume be Implement various mathematical schemes ure Solve complex problems in the field of fluit computers. Apply the various discretization methods	Two e Technic st. ble to: p case s ased an id flow	quation ques-so epecific alysis f ite volu	Staggerithm and (k-E) ftware govern steamer me eat trans	models — tools, Stab Total houning equation dy and transithod for consfer with the	9 - Momentum equations ants – PISO Algorithms 9 - High and low Reynold wility of solver, Courant rs 45 - ons. Sient diffusion problems any
UNIT-IV Stream function Pressure and Velo Computation of in UNIT-V Turbulence mode number models, Fredrick Levy nu	requirement and types, mixing length model, LES, DNS, Mesh Generation and refinement mber, relaxation factor, and grid independence test. On completion of the course, students will be all Apply the fundamentals of CFD, and develoe Discuss finite difference and finite volume be Implement various mathematical schemes ure Solve complex problems in the field of flui computers. Apply the various discretization methods modelling.	Two e Technic st. ble to: p case s ased an id flow	quation ques-so epecific alysis f ite volu	Staggerithm and (k-E) ftware govern steamer me eat trans	models — tools, Stab Total houning equation dy and transithod for consfer with the	9 - Momentum equations ants – PISO Algorithms 9 - High and low Reynold wility of solver, Courant rs 45 - ons. Sient diffusion problems any
UNIT-IV Stream function Pressure and Vel- Computation of in UNIT-V Turbulence mode number models, Fredrick Levy nu Outcome(s) TEXT BOOK:	requirement and types, mixing length model, LES, DNS, Mesh Generation and refinement mber, relaxation factor, and grid independence test. On completion of the course, students will be all Apply the fundamentals of CFD, and develoe Discuss finite difference and finite volume be Implement various mathematical schemes ure Solve complex problems in the field of flui computers. Apply the various discretization methods modelling.	Two e Technicst. ble to: p case sased ander find flows, solut	quation ques-so epecific alysis f ite volu and he	Staggerithm a (k-E) ftware governor stead me me taat tran	models — tools, Stab Total hou ning equation dy and transithod for consecret with the end the	Momentum equations ants – PISO Algorithms 9 High and low Reynold will of solver, Courant and solver, Courant and solver
UNIT-IV Stream function Pressure and Velo Computation of in UNIT-V Turbulence mode number models, Fredrick Levy nu Outcome(s) TEXT BOOK: 1 Verstee Method	relaxation factor, and grid independence test On completion of the course, students will be all Apply the fundamentals of CFD, and develo Discuss finite difference and finite volume be Implement various mathematical schemes ur Solve complex problems in the field of fluic computers. Apply the various discretization methods modelling.	Two e Technic st. ble to: p case sased an ader find d flow s, solut	quation quation ques-so specific alysis f ite volu and he	Staggerithm and (k-C) ftware government me me transcocedur	models — tools, Stab Total hou ning equation dy and transithod for consecretion with the end the id Dynamic	Momentum equations ants – PISO Algorithms 9 High and low Reynold willity of solver, Courant and the solver of solver of solver of solver of turbulence solver of turbulence solver.
UNIT-IV Stream function Pressure and Velo Computation of in UNIT-V Turbulence mode number models, Fredrick Levy nu Outcome(s) TEXT BOOK: 1 Verstee Method 2 Ghosho	Flow Field Analysis and vorticity, Representation of the pressure socity corrections – Pressure Correction equation, internal and external thermal boundary layer. Turbulence Modeling el requirement and types, mixing length model, LES, DNS, Mesh Generation and refinement imber, relaxation factor, and grid independence test. On completion of the course, students will be all Apply the fundamentals of CFD, and develoe Discuss finite difference and finite volume be Implement various mathematical schemes une Solve complex problems in the field of fluit computers. Apply the various discretization methods modelling. eg, H.K., and Malalasekera, W., "An Introduction and Pearson Education, 2014. dastidar, P.S., "Computational Fluid Dynamics and discretization and proposed in the field of proposed in the field of fluit computers.	Two e Technic st. ble to: p case sased an ader find d flow s, solut	quation quation ques-so specific alysis f ite volu and he	Staggerithm and (k-C) ftware government me me transcocedur	models — tools, Stab Total hou ning equation dy and transithod for consecretion with the end the id Dynamic	Momentum equations ants – PISO Algorithms 9 High and low Reynold will be solver, Courant and solver, Courant and solver
UNIT-IV Stream function Pressure and Vel- Computation of in UNIT-V Turbulence mode number models, Fredrick Levy nu Outcome(s) TEXT BOOK: 1 Verstee Method 2 Ghosho REFERENCES 1 John. F	and vorticity, Representation of the pressure socity corrections – Pressure Correction equation, internal and external thermal boundary layer. Turbulence Modeling I requirement and types, mixing length model, LES, DNS, Mesh Generation and refinement imber, relaxation factor, and grid independence test. On completion of the course, students will be allowed a Apply the fundamentals of CFD, and develowed Discuss finite difference and finite volume be Implement various mathematical schemes ure Solve complex problems in the field of fluid computers. Apply the various discretization methods modelling. Eg, H.K., and Malalasekera, W., "An Introduction of the course, students will be allowed to the course, students will	Two e Technic st. ble to: p case s ased an ader find flow s, solut to Compatible to C	quation ques-so epecific alysis fite volu and he tion proputation. Transfection", S	Staggerithm and (k-E) ftware governor stead and transported and Fluer", Central Springer	models — tools, Stab Total hou ning equation dy and transit thod for consfer with the e and the id Dynamic ngage Learn r, 2013.	Momentum equations ants – PISO Algorithms 9 High and low Reynold sility of solver, Courar 45 ons. Sient diffusion problems avention diffusion. The support of high speed concept of turbulences: The finite volume
Stream function Pressure and Velo Computation of in UNIT-V Turbulence mode number models, Fredrick Levy nu Outcome(s) TEXT BOOK: 1 Verstee Method 2 Ghosho REFERENCES 1 John. F 2 Suhas	Flow Field Analysis and vorticity, Representation of the pressure socity corrections – Pressure Correction equation, internal and external thermal boundary layer. Turbulence Modeling el requirement and types, mixing length model, LES, DNS, Mesh Generation and refinement imber, relaxation factor, and grid independence test. On completion of the course, students will be all an Apply the fundamentals of CFD, and develoge Discuss finite difference and finite volume be Implement various mathematical schemes une Solve complex problems in the field of fluit computers. Apply the various discretization methods modelling. eg, H.K., and Malalasekera, W., "An Introduction and Pearson Education, 2014. dastidar, P.S., "Computational Fluid Dynamics and Signature and Sig	Two e Technic st. ble to: p case sased an ader find id flow s, solut to Compute to Comp	quation ques-so appecific alysis fite volu and he tion proputation. Transfection., Saylor & S	Staggerithm a (k-C) ftware government me me tran cocedur mal Flucture, Central pringe to France France	models — tools, Stab Total hou ning equation dy and transithod for conser with the end the id Dynamic r, 2013. is, 2009.	Momentum equations ants – PISO Algorithms 9 High and low Reynold sility of solver, Courar rs 45 ons. Sient diffusion problems avention diffusion. The support of high speed concept of turbulence s": The finite volume ting, 2017.

CO'S	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	3	2	2	-	-	1	1	1	-	3	2	3	3
CO2	3	3	3	2	2	-	-	1	1	1	-	3	2	3	3
CO3	3	3	3	2	2	-	-	1	1	1	-	3	2	3	3
CO4	3	3	3	2	3	-	-	1	1	2	-	3	2	3	3
CO5	3	3	3	2	2	-	-	1	1	1	-	3	2	3	3

Course code	Course Name	1	Hours	/week	Credit	Ma	aximum marks
	Design of Jigs, Fixtures and Press	L	Т	P	C		
24ME15201	Tools						100
24WIE 152UI	(Use of PSG Design Data Book is Permitted)	3	0	0	3		100
	To understand the functions and designate the functions and designate the functions are designated as a function of the functions are designated as a function of the functions are designated as a function of the funct	gn prin	ciples o	of jigs, f	fixtures and	press to	ools.
	• To understand the basics of Jigs						
Objective(s)	• To understand the basics of fixtures.	.•					
	To understand bending and drawing o To understand the development of rec	_		of the fi	nol docion		
UNIT-I	• To understand the development of required Introduction	lunea	views	or the m	nai design.		9
	antages of Jigs and fixtures - Basic elemen	ts - pr	inciple	s of loc	ation - Loc	ating m	-
Redundant Locati	on - Principles of clamping - Mechanical acting buttons - Tolerances and materials used.	•	•			_	
UNIT-II	Jigs						9
Design and developost jigs - Indexin	opment of jigs for given component - Types ag jigs.	s of Jig	gs - Po	st, Turn	over, Chan	nel, latc	h, box, pot, angulai
UNIT-III	Fixtures						9
	opment of fixtures for given component-G-Assembly, Inspection and Welding fixture						
UNIT-IV Difference between	Bending and Drawing Dies en bending and drawing - Blank developm	ent fo	r abov	e opera	tions - Typ	es of B	9 ending dies - Press
Difference between capacity - Spring drawing operation	en bending and drawing - Blank developm back - knockouts - direct and indirect - pas - draw die inserts - draw beads - ironing.						eting Metal flow in
Difference between capacity - Spring drawing operation UNIT-V	en bending and drawing - Blank developm back - knockouts - direct and indirect - p as - draw die inserts - draw beads - ironing. Forming Techniques and Evaluation	ressure	e pads	-Ejecto	rs - Variab	les affe	eting Metal flow in
Difference between capacity - Spring drawing operation UNIT-V Bulging, Swaging trends in tool des	en bending and drawing - Blank developm back - knockouts - direct and indirect - pas - draw die inserts - draw beads - ironing.	ressure g, shav	ing and	-Ejecto I sizing, basic i	assembly,	les affec	y nking dies - recent
Difference between capacity - Spring drawing operation UNIT-V Bulging, Swaging trends in tool des	back - knockouts - direct and indirect - pas - draw die inserts - draw beads - ironing. Forming Techniques and Evaluation g, Embossing, coining, curling, hole flanging sign- computer Aids for sheet metal forming	ressure g, shav	ing and	-Ejecto I sizing, basic i	assembly,	fine Bla	y nking dies - recent
Difference between capacity - Spring drawing operation UNIT-V Bulging, Swaging trends in tool des	en bending and drawing - Blank development back - knockouts - direct and indirect - pens - draw die inserts - draw beads - ironing. Forming Techniques and Evaluation g, Embossing, coining, curling, hole flanging sign-computer Aids for sheet metal forming these - setup reduction for work holding - Sing Upon completion of the course, students Summarize the different methods of letter of the course of th	s, shaving Analle min	ing and llysis - ute exc be able g jigs a nt onent ies	-Ejecto I sizing, basic i change o	assembly, ntroduction of dies.	fine Bla - toolii	9 nking dies - recent ng for numerically
Difference between capacity - Spring drawing operation UNIT-V Bulging, Swaging trends in tool descontrolled machin	bending and drawing - Blank development back - knockouts - direct and indirect - properties - draw die inserts - draw beads - ironing. Forming Techniques and Evaluation grammager and Evaluation gra	s, shaving Analle min	ing and llysis - ute exc be able g jigs a nt onent ies	-Ejecto I sizing, basic i change o	assembly, ntroduction of dies.	fine Bla - toolii	9 nking dies - recent ng for numerically
Difference between capacity - Spring drawing operation UNIT-V Bulging, Swaging trends in tool destrontrolled machin Outcome(s)	bending and drawing - Blank development back - knockouts - direct and indirect - properties - draw die inserts - draw beads - ironing. Forming Techniques and Evaluation grammager and Evaluation gra	s, shave ag Analle min shall locating inponent componing disteching technical shall locating in the shall loca	ing and llysis - ute exc be able g jigs a nt onent ies iques	-Ejecto I sizing, basic i change o to: nd fixtu	assembly, assembly, assembly, of dies. Total ares and clar	fine Bla - toolin hours mping p	9 nking dies - recent ng for numerically 45 rinciples
Difference between capacity - Spring drawing operation UNIT-V Bulging, Swaging trends in tool destrontrolled machin Outcome(s) TEXT BOOK 1 Joshi, P.H.	back - knockouts - direct and indirect - pas - draw die inserts - draw beads - ironing. Forming Techniques and Evaluation g, Embossing, coining, curling, hole flanging sign - computer Aids for sheet metal forming res - setup reduction for work holding - Sing Upon completion of the course, students Summarize the different methods of log Design and develop jigs for given completion of the course of Design and develop fixtures for given completion of the course of Design and develop fixtures for given completion of the course of given completion o	s, shave g, shave g Ana le min shall l ocating nponer comp wing d g techn	ing and dlysis - ute exc be able g jigs a nt onent ies iques	-Ejecto I sizing, basic i change o to: nd fixtu	assembly, assembly, ntroduction of dies. Total lares and clar	fine Bla - toolin hours mping p	9 nking dies - recent ng for numerically 45 rinciples
Difference between capacity - Spring drawing operation UNIT-V Bulging, Swaging trends in tool descontrolled machine Outcome(s) TEXT BOOK 1 Joshi, P.H. 2 Joshi P.H."	en bending and drawing - Blank development back - knockouts - direct and indirect - properties - draw die inserts - draw beads - ironing. Forming Techniques and Evaluation graphs and graphs and graphs and graphs and graphs and graphs and develop graphs and develop graphs and draw graphs and develop fixtures for given and develop beautiful evaluation graphs and develop graphs and draw graphs and graphs and graphs and Fixtures", Second Edition, Tata M.	s, shave g Anale min shall le min component comp wing degree technologies. IcGrave hand &	ing and lysis - ute excorpe able g jigs and onent ies iques	-Ejecto I sizing, basic i change o to: nd fixtu	assembly, ntroduction of dies. Total lares and clar	fine Bla - toolin hours mping p	9 nking dies - recent ng for numerically 45 rinciples
Difference between capacity - Spring drawing operation UNIT-V Bulging, Swaging trends in tool destrontrolled machine Outcome(s) TEXT BOOK 1 Joshi, P.H. 2 Joshi P.H. 3 Kempster,	bending and drawing - Blank developments - knockouts - direct and indirect - pass - draw die inserts - draw beads - ironing. Forming Techniques and Evaluation Gramman Evaluation Gramm	s, shave g Anale min shall le min component comp wing destroy technologies and boddes and boddes and boddes and boddes are shared by the shared boddes are shared by the s	ing and lysis - ute excorpe able g jigs and onent ies iques	-Ejecto I sizing, basic i change o to: nd fixtu	assembly, ntroduction of dies. Total lares and claring Co., Ltd. , 1974.	fine Bla - toolin hours mping p	9 nking dies - recent ng for numerically 45 rinciples
Difference between capacity - Spring drawing operation UNIT-V Bulging, Swaging trends in tool descontrolled machine Outcome(s) TEXT BOOK 1 Joshi, P.H. 2 Joshi P.H. 3 Kempster,	en bending and drawing - Blank development back - knockouts - direct and indirect - pass - draw die inserts - draw beads - ironing. Forming Techniques and Evaluation g, Embossing, coining, curling, hole flanging sign-computer Aids for sheet metal forming these - setup reduction for work holding - Sing Upon completion of the course, students Summarize the different methods of leteration and develop jigs for given composition and develop fixed for given composition. Design and develop fixed for given composition and develop bending and draw of the different types of forming types of the different types of form	s, shave g Anale min shall le min component comp wing destroy technologies and boddes and boddes and boddes and boddes are shared by the shared boddes are shared by the s	ing and lysis - ute excorpe able g jigs and onent ies iques	-Ejecto I sizing, basic i change o to: nd fixtu	assembly, ntroduction of dies. Total lares and claring Co., Ltd. , 1974.	fine Bla - toolin hours mping p	9 nking dies - recent ng for numerically 45 rinciples
Difference between capacity - Spring drawing operation UNIT-V Bulging, Swaging trends in tool destrontrolled machine Outcome(s) TEXT BOOK 1 Joshi, P.H. 2 Joshi P.H. 3 Kempster, 4 Donaldson REFERENCE	en bending and drawing - Blank development back - knockouts - direct and indirect - pass - draw die inserts - draw beads - ironing. Forming Techniques and Evaluation g, Embossing, coining, curling, hole flanging sign-computer Aids for sheet metal forming these - setup reduction for work holding - Sing Upon completion of the course, students Summarize the different methods of leteration and develop jigs for given composition and develop fixed for given composition. Design and develop fixed for given composition and develop bending and draw of the different types of forming types of the different types of form	s, shave g Anale min shall le min component comp wing day techn decorated and & coddes a con, Ta	ing and alysis - ute excorpe able g jigs and onent ies iques v Hill Fix Co Litand Stotata McC	-Ejecto I sizing, basic i change o to: nd fixtu	assembly, ntroduction of dies. Total lares and claring Co., Ltd. 1974. 11, 2017.	fine Bla - toolin hours mping p	9 nking dies - recent ng for numerically 45 rinciples
Outcome(s) TEXT BOOK 1 Joshi, P.H. 2 Joshi P.H. 3 Kempster, 4 Donaldson REFERENCE 1 K. Venkata	en bending and drawing - Blank development back - knockouts - direct and indirect - pas - draw die inserts - draw beads - ironing. Forming Techniques and Evaluation gramman Experiment Forming Forming Techniques and Forming Forming and develop forming and develop fixtures for given the Distinguish between bending and drawn Discuss the different types of forming Techniques and Forming Forming Forming Techniques and Forming Techniqu	s, shave g, shave g Ana le min shall le ocating nponer comp wing de g techn lcGrave hand & oddes a on, Ta	ing and alysis - ute excorpe able g jigs and onent ies iques v Hill F & Co Liand Stota McCounter Pu	-Ejecto I sizing, basic i change o to: nd fixtu Publishi td, 2001 oughton Graw Hi	assembly, antroduction of dies. Total lares and clarates and clarates and clarates. 1974. 11, 2017.	fine Bla - toolin hours mping p	9 nking dies - recent ng for numerically 45 rinciples
Outcome(s) TEXT BOOK 1 Joshi, P.H. 2 Joshi P.H. 3 Kempster, 4 Donaldson, REFERENCE 1 K. Venkata 2 "ASTME -	en bending and drawing - Blank development back - knockouts - direct and indirect - properties - draw die inserts - draw beads - ironing. Forming Techniques and Evaluation Gramman Technique	s, shave ag Anale min shall le min component comp wing day techn decodes a con, Table 1 of In	ing and lysis - ute excorpt able g jigs and onent ies iques v Hill Fand Stota McCorpt and Stota McCorpt able g jigs and stota mcCorpt and	-Ejecto I sizing, basic i change o to: nd fixtu Publishi td, 2001 oughton Graw Hi ablication	assembly, assembly, assembly, antroduction of dies. Total lares and clarates and clarates and clarates and clarates. 1974. ans, 2015. ew Delhi 19	fine Bla - toolin hours mping p	9 nking dies - recent ng for numerically 45 rinciples

CO'S	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	2	2	2	1	-	-	-	1	-	1	2	3	-
CO2	3	3	2	2	3	1	-	-	-	1	-	1	2	3	-
CO3	3	3	2	2	3	1	-	-	-	1	-	1	2	3	-
CO4	3	2	2	1	2	1	-	-	-	1	-	1	2	3	-
CO5	3	2	2	1	2	1	-	-	-	1	-	1	2	3	-

Course	code	Course Name	Но	ours/w	eek	Credit	Ma	ximum marks
) / N / I To 1	15202	Dungage Dionwing and Cont Estimation	L	Т	P	C		100
24ME 1	13202	Process Planning and Cost Estimation	3	0	0	3		100
Objectiv	ve(s)	 To provide the necessary knowledge for the products. To know the different steps involved in products. To Estimate costs for new products. To understand the machining time calculation. 	cess pla	anning.				
UNI	T-I	Introduction to Process Planning						9
		res- methods of process planning-drawing interprelection-production equipment and tooling selecti		-dimen	sional to	olerances in	manu	facturing process-
UNI	Γ-II	Process Planning Steps						9
	election	ss plan – selection of production processes, tool of inspection devices and tools-documenting the						uter-aided process
UNIT	Γ-III	Introduction to Cost Estimation						9
		osting and estimation-methods of costing-elem- tion labor cost, material cost-allocation of overhead						
UNIT	Γ-IV	Production Cost Estimation						9
Estimatio	n of diff	erent types of jobs– estimation of forging shop, w	elding	shop, f	oundry	shop.		
UNI	Γ-V	Machining Time Calculation						9
		chining time—importance of machine time calculating, planning and grinding.	ılation-	calcula	tion of	machining	time	for lathe, drilling
-						Total hou	rs	45
Outcom	e(s)	 Upon completion of the course, students shall be Describe the process planning techniques in describe the process planning activity chart. Compute the direct and indirect product costines. Find the production cost for manufacturing presented the machining time for machining or 	ifferen ng. ocesses	t indust s.	rial pro	cesses.		
TEXT B	OOK:	, i						
1	Peter sc	alon, "Process planning, Design/Manufacture Int	erface"	, Elsev	ier scie	nce technol	ogy Bo	ooks, Dec 2002.
2	Sinha B	P, "Mechanical Estimating and Costing", Tata-N	/IcGrav	v Hill p	ublishii	ng co, 1995		
3	Gideon	Halevi, "Process and operation planning", Kluwe	er acade	emic Pu	ıblisher	s (Printede	-book)	, 2003.
REFER	ENCES	:			_			
1	Chitale	A.V. and Gupta R.C., "Product Design and Manu	ıfacturi	ng", 2r	d Editi	on, PHI, 20	11.	
2		al P.F. and Munez J., "Manufacturing Processes a					Viley,	1998.
4	Mikell	R.S and Tailor B.W, "Operations Management", P. Groover, "Automation, Production, System on 2001.					Ianufa	cturing", Pearson
5		in & L.N. Aggarwal, "Production Planning Co	ontrol	and Inc	lustrial	Manageme	ent", K	Channa Publisher

CO'S	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	2	2	3	2	-	-	-	1	-	3	2	3	-
CO2	3	3	2	2	3	2	-	-	-	1	-	3	2	3	-
CO3	3	3	2	2	3	2	-	-	-	2	-	3	2	3	-
CO4	3	3	2	2	3	2	-	-	-	2	-	3	2	3	-
CO5	3	3	2	2	3	2	-	-	-	2	-	3	2	3	-

Course code	Course Name	Но	ours/w	eek	Credit	N	Iaximum marks
24ME15203	Geometric Dimension, Tolerance and	L	Т	P	C		100
Objective(s) UNIT-I Overview of the Tolerances – Typ	Modeling To understand the concepts on steps To get idea of drawing standards, fit To gain knowledge on integration of To obtain basic concepts on geomet systems. To gain practical experience in handesign tool. Examinatio Introduction to design, Limits, Fits and design process - Selection of materials dependence of the process of fits - Allocation of fits for different Geometric Modeling and Methods	ts and to f design tric mod dling 2 on Patto Tolera pendent lata she	olerand n tool i deling D sket ern: T nnce t on m	ces in don composite the compo	esign and di uters to obta ls for design ad 3D solid cal Mode	ain 2D n and d model ristics	and 3D modeling. rafting in mechanica ing using appropriate 9 - Preferred numbers
GEOMETRIC M	ODELLING- Curves representation - Herr techniques – surface patch- Coons and bic						rves-rational curves
teeninques es e	Examination	n Patte	rn: Pr	actical	Mode		
UNIT-III	Geometric Graphics and Representation	n					9
hidden surface retransformations h UNIT-IV Preparation of	design –CAD system architecture- Computermoval, reflection, shading and generation omogeneous coordinates. Part Modeling of Engineering Componer part drawings from the given detailed	ents views	haracte (ortho	ers. Tra	nsformation	n in g	raphics -2D and 3E 9 k clamp, Bracket
UNIT-V	Pump housing, Stop valve body, Pistor Assembly and Cross Sections	1 Head	l, hydi	aulic f	ittings, jou	ırnal E	Bearing. 9
Preparation of as	sembly drawings and cross sections from box, Steam stop valve, Hydraulic cylinder	_			views (ortho	ograph	
					Total ho	ours	45
Outcome(s) TEXT BOOKS:	 At the end of the course student will be all Describe the various steps involved Apply the drawing standards, fits an Comprehend the concept of compute Develop 2D models using modeling Develop part, assembly modeling at 	in the I d tolera er aideo softwa	ances i d desig are.	n desigi n and g	n and draftin eometric mo	odeling	
	Zeid "Theory and Practice" Tata McGraw-H	[i]] Puh	lishino	Co 2 ^r	nd Edition 20	009	
	akrishan, S. Subramanyan, V. Raju, "CAD/O						ublishers, 4 th Edition
	V, "Introduction To Machine Design", 2 nd	Edition	ı, Tata	McGra	w- HillBoo	kCo, 2	013.
REFERENCES:							
MET EREICES.							

2. Foley, Wan Dam, Feiner and Hughes - "Computer graphics principles & practice", 2nd Edition, Pearson Education -2007.

SOFTWARE:

1. High-end Integrated Modeling CAD software – 30 Users.

CO'S	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	3	2	2	-	-	-	2	1	-	2	3	2	-
CO2	3	2	3	2	2	-	-	-	2	1	-	2	3	2	-
CO3	3	2	3	2	3	-	-	-	2	1	-	2	3	2	-
CO4	2	2	2	1	3	-	-	-	2	2	-	2	3	2	-
CO5	3	2	3	2	3	-	-	-	2	2	-	2	3	2	-

Course code	Course Name	Но	urs/w	Maximum marks		
24ME15204	Value Engineering	L 3	T	P 0	C 3	100
Objective(s)	 To study the value engineering process a To determine the appropriate value en appropriate training to centralized and de To learn various decision-making pro appropriately in the product developmen To explore in-depth understanding of vanuaufacturing and marketing. To demonstrate to implement value engineering 	nd able to agineering ecentralize ocesses and t life-cycle arious val	identif metho d mode d cost e. ue engi	y its fur dology es. evalua	for a givention mode	en project and propose els and apply them in ons in human resources,
UNIT-I	Value Engineering Basics					9
Management - V Types of Value	engineering - Meaning of value engineering - alue Analysis Versus Value Engineering - Valunction - Basic and Secondary functions - cos, advantages and limitations of Value analysis. Value Engineering Job Plan And Process	lue Analy ncept of c	sis ver	sus Tra	ditional co	st reduction techniques -
Seven phases of	ob plan - FAST Diagramming as Value Engine	eering Too		avioral	and organi	
UNIT-III	n principles of Value analysis - Benefits of Val Value Engineering Techniques	ue Engine	ering.			9
or Buy decisions Analysis - Life c						e (FAST) - Break Even
UNIT-IV	Worksheets and Guidelines					9
Meaningful costs guidelines for wi Case studies and		- Feasibil	ity ranl	king - I	nvestigator	phase, study summary - ral presentation - Audit -
UNIT-V	Versatility of Value Engineering					9
	g operation in maintenance and repair activitie g programme Introduction - training plan - care			or value	engineeri	ng specialties.
					Total hou	rs 45
Outcome(s)	 Upon completion of the course, students sha Estimate a product cost based on value of worthiness. Discuss the product and articulate it in value of Discuss and select appropriate methods, propose appropriate training Apply querying theory and FAST to prefore the Develop various case studies related to value of the product of the	engineerin arious pha standards ect a valu	g princes ses of vand appearance engine	value en ply then	ngineering m on value project imp	engineering project and plementation.
TEXT BOOK	•	aruc ciigii	iccinig	project	mpicinen	tutiOII.
	S., "Value Engineering", New Age Internation	al (P) Lim	ited, 9t	h Editio	on, 2009 31	Ed", , 2009.
2 Anil I	Kumar. and Mukhopadhyaya., "Value Enginations, 1st Edition, 2003.					
REFERENCE						
1 Del L.	Younker., "Value Engineering: analysis and m					
	nce D. Miles., "Techniques of Value Analysis ition, 2015.	and Eng	ineering	g", Law	vrence D.	Miles Value Foundation,

CO'S	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	3	2	2	-	-	-	-	-	-	3	3	2	-
CO2	3	2	3	2	2	-	-	-	-	-	-	3	3	2	-
CO3	3	2	3	2	3	-	-	-	-	-	-	3	3	2	-
CO4	3	2	3	2	3	-	-	-	-	-	-	3	3	2	-
CO5	3	2	3	2	3	-	-	-	-	-	-	3	3	2	-

	code	Course Name	Ho	Ma	ximum marks			
24ME15	205 Ac	lditive Manufacturing and Wireframe	L	T	P	С		100
24 1V1E13	203	Modeling	2	0	4	3		100
Objective((s) •	To understand the principles and processes To familiarize with wireframe modeling tec To apply modeling techniques for preparin To enable hands-on experience with slicing To develop skills in transforming wirefram	chnique g desig g, print	es for 3 gns suita ing, and	D objeable for post-p	ct represent additive me processing	tation. nanufac in AM.	
UNIT-	I F	undamentals of Additive Manufacturing					•	9
Photopolym Application	nerization s: Prototyp	nufacturing Processes - Classification of (SLA), Powder Bed Fusion (SLS, SLM) bing, Medical, Aerospace, Automotive Limita	- Mate	erials f nd Futu	or AM	(Polymer		tals, Composites)
UNIT-		ntroduction to Wireframe Modeling and Its						9
	lines), Co	amentals - Wireframe Modeling: Concepts an ordinate systems - Models - Application		•				•
		List of Experiments						27
7. Mat 8. 3D 9. Pos	terial Setup Printing of t-Processin	eration and Mesh Checking apport Generation o and Print Bed Calibration f a Wireframe-based Solid Model ag of Printed Components Component from Concept to Product						
7. Mat 8. 3D 9. Pos	terial Setup Printing of t-Processin	apport Generation o and Print Bed Calibration f a Wireframe-based Solid Model				Total hou	ırs	45
7. Mat 8. 3D 9. Pos 10. Proj	terial Setup Printing of t-Processin ject: AM (apport Generation o and Print Bed Calibration f a Wireframe-based Solid Model ng of Printed Components	nodelin lid mo cute F	ng for A dels us DM pri	ve man M file ing CA nting t	nufacturing preparation D tools. asks.	proces	sses.
7. Mat 8. 3D 9. Pos 10. Proj	terial Setup Printing of t-Processin ject: AM (and Print Bed Calibration f a Wireframe-based Solid Model ng of Printed Components Component from Concept to Product Understand the principles and classificate Apply CAD techniques and wireframe in Construct accurate 3D wireframe and so Prepare STL files, slice models, and exe Demonstrate complete workflow from in 	nodelir lid mo cute F nodelir	ng for A dels us DM pri ng to po	ve mand M file ing CA nting to st-produce to the contract of t	nufacturing preparation D tools. asks. cessing of p	g proces	sses.
7. Mat 8. 3D 9. Pos 10. Pro Outcome(s	Printing of t-Processin ject: AM (S	 and Print Bed Calibration a Wireframe-based Solid Model ag of Printed Components Component from Concept to Product Understand the principles and classificate Apply CAD techniques and wireframe in Construct accurate 3D wireframe and so Prepare STL files, slice models, and execute 	nodelir lid mo cute F nodelir	ng for A dels us DM pri ng to po	ve mand M file ing CA nting to st-produce to the contract of t	nufacturing preparation D tools. asks. cessing of p	g proces	sses.
7. Mat 8. 3D 9. Pos 10. Pro Outcome(s) TEXT BO 1 Z	Printing of t-Processin ject: AM (S	 and Print Bed Calibration f a Wireframe-based Solid Model ng of Printed Components Component from Concept to Product Understand the principles and classificate Apply CAD techniques and wireframe in Construct accurate 3D wireframe and so Prepare STL files, slice models, and exe Demonstrate complete workflow from in 	nodelir lid mo cute F nodelir	ng for A dels us DM pri ng to po	ve mand M file ing CA nting to st-produce to the contract of t	nufacturing preparation D tools. asks. cessing of p	g proces	sses.
7. Mat 8. 3D 9. Pos 10. Proj Cutcome(s) TEXT BO 1 Z REFEREN 1 G at	Printing of t-Processin ject: AM (S) OK: eid, Ibrahi NCES: eibson, I., I	 and Print Bed Calibration f a Wireframe-based Solid Model ng of Printed Components Component from Concept to Product Understand the principles and classificate Apply CAD techniques and wireframe in Construct accurate 3D wireframe and so Prepare STL files, slice models, and exe Demonstrate complete workflow from in 	nodelin lid mo cute F nodelin raw-Hi	ng for A dels us DM pri ng to po	ve man AM file ing CA nting to est-production, 2	nufacturing e preparation AD tools. asks. cessing of personal properties of personal personal properties of personal p	printed	sses. parts.
7. Mat 8. 3D 9. Pos 10. Pro TEXT BO 1 Z REFEREN 1 G au 2 C Pt	Printing of t-Processing ject: AM (Control of the Processing ject: AM (Control of the Printing ject: AM (Control of the Printi	 and Print Bed Calibration a Wireframe-based Solid Model ng of Printed Components Component from Concept to Product Understand the principles and classificate Apply CAD techniques and wireframe in Construct accurate 3D wireframe and so Prepare STL files, slice models, and exe Demonstrate complete workflow from in m - *CAD/CAM Theory and Practice*, McG Rosen, D. W., & Stucker, B Additive Manual Digital Manufacturing, Springer, 2nd Edition, in, Leong, K. F., & Lim, C. S Rapid Prof 5th Edition, 2019. 	nodelin lid mo cute F nodelin raw-Hi facturi 2015.	ng for Adels us DM pring to po Il Educe Ing Tec g: Pring	ve man AM file ing CA nting to sst-production, 2 ciples	preparation of prepar	printed n, 2008 nting, F	sses. parts. Rapid Prototyping , World Scientifi
7. Mat 8. 3D 9. Pos 10. Proj Cutcome(s) TEXT BO 1 Z REFEREN 1 G au 2 C Proj 3 A	Printing of t-Processin ject: AM (S) POK: eid, Ibrahi NCES: dibson, I., Ind Direct If thua, C. K ublishing, undreas Go	 and Print Bed Calibration a Wireframe-based Solid Model ng of Printed Components Component from Concept to Product Understand the principles and classificate Apply CAD techniques and wireframe in Construct accurate 3D wireframe and so Prepare STL files, slice models, and exe Demonstrate complete workflow from in m - *CAD/CAM Theory and Practice*, McG Rosen, D. W., & Stucker, B Additive Manual Digital Manufacturing, Springer, 2nd Edition, I., Leong, K. F., & Lim, C. S Rapid Product 	nodelin lid mo cute F nodelin raw-Hi facturi 2015.	ng for Adels us DM pring to po Il Educe Ing Tec g: Pring	ve man AM file ing CA nting to sst-production, 2 ciples	preparation of prepar	printed n, 2008 nting, F	sses. parts. Rapid Prototyping , World Scientific

CO'S	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	2	2	2	-	-	-	2	1	1	2	2	3	-
CO2	3	2	3	2	3	-	-	-	2	1	1	2	3	3	-
CO3	2	2	3	2	3	-	-	-	2	2	1	2	3	3	-
CO4	2	2	3	2	3	-	-	-	2	2	2	2	3	3	-
CO5	2	2	3	2	3	-	-	-	3	2	2	2	3	3	-

Course	e code	Course Name	Но	urs/w	eek	Credit	Ma	aximum marks
24ME	15206	Computational Solid Mechanics	L	T	P	С		100
	10100	Companies Sona Necessaries	3	0	0	3		100
Objectiv	ve(s)	 To study the definition and basics on theory To learn finite element method and procedur To study the Non Linear and History depend To study time dependent and dynamic proble To study Structural Elements & Interfaces an 	e for sta proble ems of S	atic line ms Small a	nd larg	ge strain vis	•	ticity
UNI	T-I	Basic on Theory of Elasticity			<u> </u>			9
Stress -	strain rela oility equa	ons and sign conventions for stress and strain, Entions, Lame's constant –cubical dilation, Conations for stresses and strains, Principal stress	pressib	oility of	f mater	rial, bulk n	nodulu	s, Shear modulus,
UNI	T-II	Finite Element Method for Static Linear Ela	asticity					9
element p	orocedure	plementation of a basic 2D FE code with trials for linear elasticity: interpolation and numeric cting variational forms; mixed methods. Accura	al integ	ration i	in 1D,	2D and 3D	. Deri	
UNIT	Γ-III	Non Linear and History Depend Problems						9
Small stra	ain hypo-	elastic materials - Small strain visco-plasticity -	Large s	train ela	asticity	-Large stra	ain vis	co-plasticity.
UNIT	Γ-IV	Time Dependent And Dynamic Problems						9
	•	s - the diffusion equation - Explicit time integral modal time integration.	tion – 1	he Nev	vmark	method - In	mplici	t time integration -
UNI	T-V	Structural Elements & Interfaces and Conta	act					9
		 Shells – Cohesive Zones - Enforcing constr in two dimensions) 	aints u	sing pe	nalty r	nethods and	d Lagı	ange Multipliers -
						Total hou	ırs	45
Outcom	e(s)	 Upon completion of the course, students shall be Discuss the definition and basics on theory Derive the finite element method for static le Discuss the Non Linear and History dependence Discuss time dependent and dynamic problete Discuss Structural Elements & Interfaces are 	of elast inear el proble ems sol	icity lasticity ms, Sol ve prob	ve pro lems.	blems.		
TEXT B	BOOK:							
1	L.S.Srina	ath, Advanced Mechanics Of Solids, 3 rd Edition	2008					
2	J.N.Redo	dy, Introduction To Finite Element Method, 4th E	Edition	2020.				
3	S.Timos	henko, Theory of Elasticity, McGraw-Hill Educa	ation (I	ndia) P	vt Limi	ited, 2010.		
REFER	ENCES:							
1		chanics of Solids and Structures - Hierarchical Md Solid Mechanics) by Miguel Luiz Bucalem and						

CO'S	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	3	2	3	3	2	2	-	-	-	3	3	2	3
CO2	3	3	3	3	3	3	2	2	-	-	-	3	3	2	3
CO3	3	3	3	3	3	3	2	2	-	-	-	3	3	2	3
CO4	3	3	3	3	3	3	2	2	-	-	-	3	3	2	3
CO5	3	3	3	3	3	3	2	2	-	-	-	3	3	2	3

Course code	Course I	Name	Ho	urs/w	eek	Credit	Maximum marks
0 AB #E1 # F	Composite	e Materials,	L	T	P	C	100
24ME15.	Processing an	nd Application	3	0	0	3	100
	processes. To understand the position of the process of the	ymer, metal, and properties and uses ed composites like the testing and choosites assification—based	of diffe ke carb naracteri	rent corpon—car zation o	x commposite bon common based	e materials. composites posites.	and their aerospace 9 ure – Advantages and
UNIT-II	Polymer matrix com	posites					9
	r matrix materials – PMC proent winding – Auto clave base PMC's.			_		_	
UNIT-III	Metal matrix compos						9
processes – In-situ	processes. Properties and app	lications of MMC's	_	of MMO	C – Lio	quid state p	
UNIT-IV	Ceramic matrix com	<u>-</u>	+ - mi m -	Hot me		Infiltmotic	9
In-situ chemical re	terials – properties – processi action techniques – sol-gel po Properties and Applications of	olymer pyrolysis –	_	_	_		-
UNIT-V	Advance in composit						9
carbon fibre performance	oon matrix – limitations of om. Properties and application composite materials – Mecha	s of Carbon–carbo	n comp	osites.	Compo		
						otal hour	s 45
Outcome(s)	 Identify and classify Explain the processes Describe the propertion Recognize the advant Understand how to te 	used to make poly es and applications ages and limitation	mer, me of various of adv	etal, and ous com vanced o	d ceran posite: compos	s.	composites.
TEXT BOOK							
1 Chaw	a K.K., Composite materials,	2/e, Springer – Ve	rlag, 19	98.			
2 Danie 2003	Gay, Suong V. Hoa & Steph	en W. Tsai – Analy	ysis and	Perforr	nance	of Fiber Co	imposites, 2nd edition
1	Shukla (Editor) — Mechanics on 2022	of Composite Mater	rials and	Structi	ures: W	Vith Person	al Computers, 2nd
REFERENCES	•						

2.	A.B. Strong, Fundamentals of Composite Manufacturing, SME, 1989.
3.	S.C. Sharma, Composite materials, Narosa Publications, 2000.
4.	Maureen Mitton, Hand Book of Bioplastics & Bio-composites for Engineering applications, John Wiley publications, 2011

CO'S	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	-	-	-	-	2	-	-	-	-	-	3	2	-
CO2	3	3	2	-	-	-	-	-	-	-	-	-	3	3	-
CO3	3	2	-	-	-	2	3	-	-	-	-	-	3	2	-
CO4	3	2	-	-	-	-	2	-	-	-	-	-	3	2	-
CO5	3	3	2	2	-	-	-	-	-	-	-	-	3	2	2

Course code	Course Name	Но	ours/w	eek	Credit	Maximum marks
24ME15302	Computer Integrated Manufacturing	L	T	P	C	100
24WIE133U2	Computer integrated Manufacturing	3	0	0	3	100
Objective(s)	 To study the overview of evolution of autom To study the various Automation tools, inclu To understand the group technology and FM To understand the computer aided process pl 	de vari S. anning	ous mat	terials l ufactur	nandling sys	
UNIT-I	• To understand the basics of data transaction, Introduction	ШОШ	ation ii	negran	on and cont	9
manufacturing – T	hree step process for implementation of CIM The future automated factory – Management of CI		•		•	ances in CIM
UNIT-II	Automated Manufacturing Systems					9
assembly system - of material handli handling. Convey Types &applicatio - storage location and Carousel stor	ction line – system configurations, work part tra-System configuration, Part delivery at workstating equipments – Consideration in material handlor systems – Types of conveyors – Operations at ons – Vehicle guidance technology – Vehicle mastrategies – Conventional storage methods and age system Deadlocks in Automated manufacturice – smart manufacturing – Industry 4.0 - Digita Group Technology And FMS	ions — ling systand feat anagem equipm aring sy	Design stem de tures. A ent and nents – vstems	for aut sign – Automa safety Autom – Petri	omated asse The 10 printed Guided . Storage synated storage net models	embly – Overvie nciples of Materi Vehicle system estem performance/Retrieval syste – Applications
	1 00					
	sual – Parts classification and coding – Production stering method – Benefits of GT – Case studies.					

machine concept – Quantitative analysis of FMS – Bottleneck model – Simple and complicated problems – Extended Bottleneck model - sizing the FMS - FMS applications, Benefits.

UNIT-IV Process Planning

Process planning - Activities in process planning, Informations required. From design to process planning classification of manufacturing processes – Selection of primary manufacturing processes – Sequencing of operations according to Anteriorities – various examples – forming of Matrix of Anteriorities – case study. Typical process sheet - case studies in Manual process planning. Computer Aided Process Planning - Process planning module and data base – Variant process planning – Two stages in VPP – Generative process planning – Flow chart showing various activities in generative PP - Semi generative process planning- Comparison of CAPP and Manual PP.

UNIT-V Process Control and Data Analysis 9

Introduction to process model formulation – linear feedback control systems – Optimal control – Adaptive control – Sequence control and PLC& SCADA. Computer process control – Computer process interface – Interface hardware – Computer process monitoring - Direct digital control and Supervisory computer control - Overview of Automatic identification methods - Bar code technology - Automatic data capture technologies. - Quality management (SPC) and automated inspection

Total hours 45

Outcome(s)

Upon completion of this course, the Learners will be able to:

- Discuss the basics of computer aided engineering.
- Choose appropriate automotive tools and material handling systems.
- Discuss the overview of group technology, FMS and automation identification methods.

	Design using computer aided process planning for manufacturing of various components
	Explain computer process control techniques.
TEXT 1	BOOK:
1	Shivanand H K, Benal M M and Koti V, Flexible Manufacturing System, New Age, 2016.
2	Mikell P. Groover, Automation, Production system and Computer integrated Manufacturing, Prentice Hall
	of India Pvt. Ltd., 4 th Edition, 2014.
REFER	RENCES:
1	Alavudeen and Venkateshwaran, Computer Integrated Manufacturing, PHI Learning Pvt. Ltd., New Delhi,
	2013.
2	Radhakrishnan P, Subramanian S and Raju V, CAD/CAM/CIM, New Age International Publishers, 3 rd
	Edition 2008

CO'S	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	2	2	2	1	-	-	-	1	-	2	2	2	-
CO2	3	2	3	2	2	1	-	-	-	1	-	2	2	3	-
CO3	3	2	3	2	2	1	-	-	-	1	-	2	2	3	-
CO4	3	3	3	3	3	1	-	-	-	2	-	3	3	3	-
CO5	3	3	3	3	3	1	-	-	-	2	-	3	3	3	-

Course code	e Course Name	Ho	urs/w	eek	Credit	Max	Maximum marks		
24ME15303	Engineering Economics and Cost Analysis	L 3	T 0	P 0	C 3		100		
Objective(s)	 To understand the cost estimation of composition To evaluate value engineering and time valuation To study the decision and risk analysis To analyze replacement and maintenance To analyze depreciation and evaluation of 	lue of mo	·	res					
UNIT-I	Introduction to Economics	posite dir					9		
Engineering eff Revenue, Sunl selection for pr	Economics - Flow in an economy, Law of surficiency, Economic efficiency, Scope of engineering k cost, Opportunity cost, Break-even analysis oduct Design selection for a product, Process plant	ng econo	mics -	Elemei	nt of costs, l	Margina	al cost, Marginal lysis - Material		
UNIT-II	Value Engineering						9		
applications - T payment series recovery factor		ımount fa	ctor, S	ingle p	ayment pres	sent wo	rth factor, Equal nt series capital		
UNIT-III	Decision and Risk Analysis						9		
	oject risk - Introduction to probability concepts for aparing mutually exclusive risky alternatives - C								
UNIT-IV	Replacement and Maintenance Analysis						9		
UNIT-IV Replacement a economic life challenger and	Replacement and Maintenance Analysis Ind Maintenance analysis - Types of maintenator and asset, Replacement of an asset with a nedefender, Simple probabilistic model for items who	ance, typ	es of	replace	ment probl	lem, d	9 etermination of		
UNIT-IV Replacement a economic life challenger and UNIT-V	Replacement and Maintenance Analysis Ind Maintenance analysis - Types of maintenator of an asset, Replacement of an asset with a nedefender, Simple probabilistic model for items where Depreciation	ance, typ w asset iich fail c	es of - cap omplet	replace ital rec ely.	ement probl overy with	lem, d	9 etermination of and concept of		
UNIT-IV Replacement a economic life challenger and UNIT-V Depreciation - years digits me method of dep	Replacement and Maintenance Analysis Ind Maintenance analysis - Types of maintenator of an asset, Replacement of an asset with a nedefender, Simple probabilistic model for items who Depreciation Introduction, Straight line method of depreciation thod of depreciation, sinking fund method of depreciation - Evaluation of public alternatives -	ance, typew asset ich fail con, declin	es of - cap: omplet ing bal	replace ital receity.	ement proble overy with method of depression	em, contraction	etermination of and concept of tion Sum of the n, service output		
UNIT-IV Replacement a economic life challenger and UNIT-V Depreciation - years digits me	Replacement and Maintenance Analysis Ind Maintenance analysis - Types of maintenator of an asset, Replacement of an asset with a nedefender, Simple probabilistic model for items who Depreciation Introduction, Straight line method of depreciation thod of depreciation, sinking fund method of depreciation - Evaluation of public alternatives -	ance, typew asset ich fail con, declin	es of - cap: omplet ing bal	replace ital receity.	ement proble overy with method of depression	eprecia reciation	etermination of and concept of tion Sum of the n, service output		
UNIT-IV Replacement a economic life challenger and UNIT-V Depreciation - years digits me method of deprocedure to ad Outcome(s)	Replacement and Maintenance Analysis Ind Maintenance analysis - Types of maintenator of an asset, Replacement of an asset with a needlefender, Simple probabilistic model for items who Depreciation Introduction, Straight line method of depreciation thod of depreciation, sinking fund method of depreciation - Evaluation of public alternatives - Ijust inflation. Upon completion of this course, the Learners who Describe the basic terminologies and control of the process of the proces	ance, typew asset wich fail con, declin reciation/introduction.	es of - cap complet ing ba Annu tion, I	replace ital receity. lance receity met Example	ement proble overy with overy with method of depres, Inflatio Total has generally gen	eprecia reciation adjustations.	etermination of and concept of tion Sum of the and service output sted decisions -		
UNIT-IV Replacement a economic life challenger and UNIT-V Depreciation - years digits me method of deprocedure to ad Outcome(s)	Replacement and Maintenance Analysis Ind Maintenance analysis - Types of maintenator of an asset, Replacement of an asset with a need defender, Simple probabilistic model for items who Depreciation Introduction, Straight line method of depreciation thou of depreciation, sinking fund method of depreciation - Evaluation of public alternatives - ligust inflation. Upon completion of this course, the Learners who Describe the basic terminologies and control of the process of the process of the concepts for investment described by the Depreciation methods for Introductions.	ance, typew asset wich fail con, declin reciation/introductions and Tiecisions et.	es of - cap complet ing bal Annuation, I	replace ital receity. lance ration metality metality metaline of I	ement proble overy with overy with the method of depres, Inflation Total has generated by the method of depres, Inflation Total has generated by the method of depression of the method of the method of depression of the method	em, de return eprecia reciation adjust s.	etermination of and concept of tion Sum of the and service output sted decisions -		
UNIT-IV Replacement a economic life challenger and UNIT-V Depreciation - years digits me method of deprocedure to add Outcome(s)	Replacement and Maintenance Analysis Ind Maintenance analysis - Types of maintenator of an asset, Replacement of an asset with a needlefender, Simple probabilistic model for items who Depreciation Introduction, Straight line method of depreciation thod of depreciation, sinking fund method of depreciation - Evaluation of public alternatives - Ijust inflation. Upon completion of this course, the Learners who Describe the basic terminologies and control of the process of the proces	ance, typew asset wich fail con, declin reciation/introductions and Tiecisions et.	es of - cap complet ing bal Annuation, I	replace ital receity. lance ration metality metality metaline of I	ement proble overy with overy with the method of depres, Inflation Total has generated by the method of depres, Inflation Total has generated by the method of depression of the method of the method of depression of the method	em, de return eprecia reciation adjust s.	etermination of and concept of tion Sum of the and service output sted decisions -		
UNIT-IV Replacement a economic life challenger and UNIT-V Depreciation - years digits me method of deprocedure to ad Outcome(s) TEXT BOOF 1 Pann	Replacement and Maintenance Analysis Ind Maintenance analysis - Types of maintenator of an asset, Replacement of an asset with a need defender, Simple probabilistic model for items who Depreciation Introduction, Straight line method of depreciation thou of depreciation, sinking fund method of depreciation - Evaluation of public alternatives - ligust inflation. Upon completion of this course, the Learners who Describe the basic terminologies and control of the process of the process of the concepts for investment described by the Depreciation methods for Introductions.	ance, type w asset tich fail con, declin reciation/introduce will be absoncepts on and Tiecisions et.	es of - cap complet ing bal Annuation, I	replace ital receity. lance ration metality metality metaline of I	ement proble overy with overy with the method of depres, Inflation Total has generated by the method of depres, Inflation Total has generated by the method of depression of the method of the method of depression of the method	em, de return eprecia reciation adjust s.	etermination of and concept of tion Sum of the and service output sted decisions -		
UNIT-IV Replacement a economic life challenger and UNIT-V Depreciation - years digits me method of deprocedure to ad Outcome(s) TEXT BOOF 1 Pann 2 Smit 3 Jame	Replacement and Maintenance Analysis Ind Maintenance analysis - Types of maintenator of an asset, Replacement of an asset with a needlefender, Simple probabilistic model for items who Depreciation Introduction, Straight line method of depreciation though of depreciation, sinking fund method of depreciation - Evaluation of public alternatives - Ligust inflation. Upon completion of this course, the Learners who Describe the basic terminologies and control of the process of the concepts for investment deconomical process. Apply the techniques Value Engineering Determine the economical life of an asset of the Apply the Depreciation methods for Inflation. K: L Riggs, David D. Bedworth, "Engineering Economy", Lowa State Preses L Riggs, David D. Bedworth, "Engineering Economy Econo	ance, type we asset the concepts of the concep	es of - cap: omplet ing ba Annuition, I	replace ital receity. Iance receity met Example neering lue of I	ement proble overy with overy with method of depres, Inflatio Total has geconomics Money.	eprecia reciation adjustatives.	etermination of and concept of tion Sum of the and service output sted decisions		
UNIT-IV Replacement a economic life challenger and UNIT-V Depreciation - years digits me method of deprocedure to add Outcome(s) TEXT BOOK 1 Pann 2 Smit 3 Jame 4 Prasa	Replacement and Maintenance Analysis Ind Maintenance analysis - Types of maintenator of an asset, Replacement of an asset with a need defender, Simple probabilistic model for items who Depreciation Introduction, Straight line method of depreciation thou of depreciation, sinking fund method of depreciation - Evaluation of public alternatives - ligust inflation. Upon completion of this course, the Learners vortice in the depreciation of the depreciation of the depreciation of public alternatives - ligust inflation. Upon completion of this course, the Learners vortice in the depreciation of the dep	ance, type we asset the concepts of the concep	es of - cap: omplet ing ba Annuition, I	replace ital receity. Iance receity met Example neering lue of I	ement proble overy with overy with method of depres, Inflatio Total has geconomics Money.	eprecia reciation adjustatives.	etermination of and concept of tion Sum of the steed decisions		
UNIT-IV Replacement a economic life challenger and UNIT-V Depreciation - years digits me method of deprocedure to ad Outcome(s) TEXT BOOF 1 Pann 2 Smit 3 Jame	Replacement and Maintenance Analysis Ind Maintenance analysis - Types of maintenator of an asset, Replacement of an asset with a need defender, Simple probabilistic model for items who Depreciation Introduction, Straight line method of depreciation thou of depreciation, sinking fund method of depreciation - Evaluation of public alternatives - ligust inflation. Upon completion of this course, the Learners vortice in the depreciation of the depreciation of the depreciation of public alternatives - ligust inflation. Upon completion of this course, the Learners vortice in the depreciation of the dep	ance, type we asset the concepts of the concep	es of - cap: omplet ing ba Annuition, I	replace ital receity. Iance receity met Example neering lue of I	ement proble overy with overy with method of depres, Inflatio Total has geconomics Money.	eprecia reciation adjustatives.	etermination of and concept of tion Sum of the and service output sted decisions		
UNIT-IV Replacement a economic life challenger and UNIT-V Depreciation - years digits me method of deprocedure to address of the procedure to	Replacement and Maintenance Analysis Ind Maintenance analysis - Types of maintenator of an asset, Replacement of an asset with a need defender, Simple probabilistic model for items who Depreciation Introduction, Straight line method of depreciation thou of depreciation, sinking fund method of depreciation - Evaluation of public alternatives - ligust inflation. Upon completion of this course, the Learners vortice in the depreciation of the depreciation of the depreciation of public alternatives - ligust inflation. Upon completion of this course, the Learners vortice in the depreciation of the dep	ance, typew asset wich fail con, declin reciation/ introductions and Tiecisions et. Hall of Inc. ss, 1987. nomics", Prentice H	es of - cap: complet ing ba: Annuition, I le to: of Engi me Va Industr dia Ltd	replace related receity. Iance related receity met Example received receiv	ment proble overy with overy with method of depres, Inflation Total has general Economics Money. Delhi, 2012 Hill, 1998.	eprecia reciation adjustatives.	etermination of and concept of and concept of the steel decisions 45		

3	Samuelson P A and Nordhaus W D, "Economics", Tata McGraw Hill, 2010.
4	Patel Bhavesh. M, "Project Management, Strategic Financial Planning Evaluation and Control", Vikas Publishing
	House, New Delhi, 2010.

co's	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	2	2	1	2	1	-	-	-	-	2	2	2	-
CO2	3	2	2	2	2	2	1	-	-	-	-	2	2	2	-
CO3	3	3	3	3	2	2	1	-	-	-	-	3	2	2	-
CO4	3	3	3	3	2	2	1	-	-	-	-	3	2	2	-
CO5	3	3	3	3	2	2	1	-	-	-	-	3	2	2	-

Course code	Course Name	Н	ours/w	eek	Credit	Maximum marks				
24ME15304	Smart Materials And Applications	L	T	P	C	100				
 To introduce the fundamentals and biological interactions of intelligent and bio-companient materials. To classify and understand the behavior of various active and passive smart materials. To explore the principles, characteristics, and applications of electro-rheological and piezoele materials. To study the properties, mechanisms, and applications of shape memory alloys and polymers. 										
	To examine the real-world applications industrial domains.	of sma	art mat	erials a	cross engi	neering, biomedical, and				
UNIT-I	Introduction					9				
bio-compatible m response: swellin	rt materials – Functional materials – Poly function naterials. – Intelligent biological materials – Bion g and leaching, corrosion and dissolution, deform cess – coagulation and hemolysis – in vitro and in	mimeti nation a	cs – W and fail	olff's lure, frie	Law – Bio	ocompatibility - Material				
UNIT-II	Classification of Smart Materials					9				
materials Magn	art materials – passive smart materials-Piezoele eto-rheological materialsPhotoactive materials passive smart materials.									
UNIT-III	Electro-Rheological and Piezoelectric Mater	rials				9				
materials – active body model – pri electro- rheologic Principles and in	redients of smart materials —micro-sensors- hybride, passive reactive actuator based smart structure incipal characteristics of electro-rheological fluids and fluid domain — fluid actuators- design parameteristic and application of Magneto-rheolism, properties and application. Introduction to electro-shape Memory Materials	es- susp - char neter – ological	ensions ge mig applica fluids	2nd el ation n tion of — Pies	ectro-rheo nechanism Electo-rhe zoelectric	logical fluids – Bingham for the dispersed phase – eological fluids – Basics, materials: polymers and				
	ım alloy (Nitinol) – Materials characteristics	of Nit	inol –	marte	nsitic trans	sformations – austenitic				
applications of SI plant, etc. – micr	thermoelastic martensitic transformations— class MA—continuum applications of SMA fasteners—o robot actuated by SMA—SMA memorization ints to applications of SMA—Shape memory poly	SMA f process	ibers – (Satell	reaction	n vessels, r enna Appli	nuclear reactors, chemical ications) SMA blood clot				
	$\frac{1}{1}$ into the applications of SWA – Shape memory pory $\frac{1}{1}$ ing – types and applications.	incis–	meenai	115111 01	snape men	nory-rimary mounting –				
UNIT-V	Applications					9				
product health or Monitoring-self-r	tors-sensor-Micro Electro Mechanical Systems (National Systems) lifetime monitoring, cure monitoring, intelligent epair - artificial organs, novel indicating deviced nedical Applications-Reducing Waste-Reducing Formula (National Systems).	process Field of	ing, ac Defen	tive and se and	l passive c Space-Nuc	ontrols, Structural Health clear Industries-Structural lation.				
					Total Hot	113 73				
Outcome(s)	 Upon completion of this course, the Learners will be able to: Illustrate the fundamental concepts and biological responses related to intelligent and bio-compatible materials. Classify and explain the properties of various active and passive smart materials. Analyze the working principles and applications of electro-rheological and piezoelectric materials. Evaluate the behavior, transformation mechanisms, and uses of shape memory alloys and polymers. Apply smart materials in advanced engineering, biomedical, and industrial applications. 									

TEXT B	OOK:
1	Sujata V., Bhat., "Biomaterials", Narosa Publication House, New Delhi, 2002.
2	M. V. Gandhi and B. S. Thompson, "Smart Materials and Structures", Chapman and Hall ,London, First Edition, 1992.
3	Inderjit Chopra and Jayant Sirohi, Smart Structures Theory, Cambridge University Press, 2014
REFER	ENCES:
1	Melton, K. N, Stockel, D. and Wayman, C.M., "Engineering aspects of Shapememory Alloys", Butterworth – Heinemann, 1990.
2	Rogers, C. A., Smart Materials, "Structures and Mathematical issues", Technomic Publishing Co., U.S.A, 1989.
3	Mohsen Shahinpoor and Hans-Jo"rg Schneider "Intelligent Materials", RSC Publishing, 2008
4	Mel Schwartz (Ed), Encyclopaedia of Smart Materials" Volume –I and II, John Wiley & Sons, Inc.2002

CO'S	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	2	2	2	2	2	1	1	1	1	2	2	2	2
CO2	3	2	2	2	2	1	1	1	1	1	1	2	2	2	2
CO3	3	3	3	3	3	2	2	1	1	1	1	3	2	2	2
CO4	3	3	3	3	3	2	2	1	1	1	1	3	2	2	2
CO5	3	3	3	3	3	2	3	2	2	2	2	3	3	2	3

Course cod	Course Name	Но	urs/w	eek	Credit	Maximum marks
24ME1530	Non-Destructive Testing	L	T	P	C	100
211/12/1000	Tion Desirative Testing	3				
Objective(s)	 To understand different surface NDE tecl To acquire familiarity with Liquid Penetr To understand the basic principles underl To know the advantages and limitations of the products 	ate Testi ying each of each te	h NDT chniqu	es and	equipment	
UNIT-I	Visual Testing					9
Fundamentals	f and introduction to destructive and non-dest thods, Different visual examination aids-compute		_	•		itations of NDT, Visual
UNIT-II	Liquid Penetrant Testing					9
Preparation of	es and properties of liquid penetrants – develor est materials – Application of penetrants to parts, penetrant process variables – selection of penetra	removal	of exc	ess pen	etrants, po	st cleaning - Control and
UNIT-III	Magnetic Particle Testing and Equipments	3				9
factors – Mag castings and we	etism – ferromagnetic, paramagnetic materials – etic Bharkhausen Noise Analysis (MBN) – adv ding – Dry continuous method and wet residual n	antages				tic particle inspection of
UNIT-IV	Radiography and Ultrasonic testing					9
techniques, ap	na-Ray radiography, Their principles, methods o lications, limitations- Basic principles of sound their advantages and limitations, Piezoelectric by UT and Thickness determination by ultrason	d propag Material	gation, , Vario	types	of sound	waves, Principle of UT
UNIT-V	Leak and pressure testing and Eddy curre	nt testin	g			9
	ak and types, Principle, Various methods of pre Principle, instrument, techniques, sensitivity, app			-		•
_					Total hou	irs 45
Outcome(s)	 Upon completion of this course, the Learners w Discuss the surface NDE techniques and w Discuss the methods of liquid penetrant test Differentiate various defect types and selec Discuss the radiography techniques with ap Discuss the testing and evaluation of the rest 	ith the exing meth t the appopulation	stablish nods ropriate s	e NDT	methods fo	or better evaluation.
TEXT BOOK	·					
	v Raj, T. Jayakumar and M. Thavasimuthu, Practed, 3rd edition, 2002.	ical Non	Destru	ictive [Testing, Al	pha Science International
2 J. Pr	sad and C. G. K. Nair, Non-Destructive Test and n, 2011.	Evaluatio	on of M	Iaterial	s, Tata Mc	GrawHill Education, 2nd
	Prakash, "Non-Destructive Testing Techniques"	, 1st rev	rised ed	dition,	New Age	International Publishers

REFER	REFERENCES:									
1	Chuck Hellier, "Handbook of Nondestructive Evaluation", Mc Graw Hill, 2012.									
2	ASM Metals Handbook, V-17, "Nondestructive Evaluation and Quality Control", American Society of Metals, USA, 2001.									

co's	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	2	2	2	1	2	-	-	-	-	2	2	3	-
CO2	3	3	2	2	2	1	2	-	-	-	-	2	2	3	-
CO3	3	3	3	2	3	1	2	-	-	-	-	2	2	3	-
CO4	3	2	2	2	2	1	2	-	-	-	-	2	2	3	-
CO5	3	3	3	2	2	1	2	-	-	-	-	2	2	3	-

Course code	Course Name	Но	ours/wo	eek	Credit	Maximum marks
		L	T	P	C	
24ME15306	Supply Chain Management	3	0	0	3	100
Objective(s)	 Understand the basics of Supply C Learn about Supply Chain Network Understand Supply Chain Plannin Technology Learn application of Supply Chair Understand Location and Transpo 	ork Desi ng, imple n Planni	gn and ementat ng and	Demar ion and Strateg	d order processes.	
UNIT-I	Introduction to SCM				FF-7	9
Focus areas in SCM	e, Overview, Objective, Process Overview, , Change Drivers, Evolution of SCM, Type SCMs. Case studies on SCM. Supply Chain Network Design and Der	pes of C	Cargoes	. Cross		
	Network design, Integrated SCM Planning,				of Logistic	
Demand Management customer service. De	network design decisions, Major Locations, Relationship between customer servicement management process, The Role of forecasting, collaborative planning.	ce and	deman	d man	agement, I	Performance measures for
UNIT-III	Supply Chain Planning, implementation	on and o	order p	rocess	ing with IT	9
•	replenishment cycles, Order processing The warehouse management system, The t Supply Chain Planning and Strategies	transpor		_		
	111				. ~	
it, Supply chain s management, Supply	ies, Strategy classification, Corporate strateries, Supply chain strategy framew chain integration, Push, Pull and Push Pull arategy versus decentralized control strategy	vork, S l system	upply	chain	relationship	os, Customer relationshi
UNIT-V	Location and Transportation Strategy	in Sup	ply Cha	in		9
facility versus multi chain, Traffic and tra Transportation econd	ange planning, Major locational determin facility location, Methods of evaluating lansportation strategy, Carrier selection decomics and pricing costing of transportation Management System (TMS).	nants, H ocation cision, I	istorica alterna ntermo	l persp tives. ' del tra	The role of nsportation.	transportation in a supply Transport documentation
					Total h	ours 45
Outcome(s)						
	 Students will be able to: Describe the basics of Supply Chain N Discuss and apply the Supply Chain N Demonstrate Supply Chain Planning, Technology Apply the Supply Chain Planning and 	Network implement	Design entatior ies	and o	rder process	_
DEVE DOOK	 Describe the basics of Supply Chain M Discuss and apply the Supply Chain M Demonstrate Supply Chain Planning, Technology 	Network implement	Design entatior ies	and o	rder process	_
TEXT BOOK: 1 K. Shridhara	 Describe the basics of Supply Chain N Discuss and apply the Supply Chain N Demonstrate Supply Chain Planning, Technology Apply the Supply Chain Planning and 	Vetwork implemon Strategy	Design entation ies in Sup	and o	rder process	_

Sunil Chopra, Peter Meindl, Dharam Vir Kalra, Supply Chain Management, Strategy, Planning and Operation Pearson

REFERENCES:

- Sarika Kulkarni, Ashok Sharma ,Supply Chain Management, Creating Linkages for Faster Business Turnaround, Tata McGraw-Hill Publishing Company Ltd
- James B. Ayers, Supply Chain Project Management, A Structured Collaborative and Measurable Approach, CRC Press

co's	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2	1	1	2	2	-	-	-	-	-	2	1	3	-
CO2	3	3	2	2	3	2	-	-	-	-	-	3	2	3	-
CO3	3	3	2	2	3	1	-	-	-	-	-	3	2	3	-
CO4	3	3	2	2	3	2	-	-	-	-	-	3	2	3	-
CO5	3	3	2	2	3	2	-	-	-	-	-	3	2	3	-

Course code	Course code Course Name Hours/week Credit M												
24ME15401	Maintenance Engineering	L 3	T	P	C 3		100						
Objective(s)	 To understand the fundamental porganization. To identify and compare different cand TPM. To explore condition monitoring teasystems. To examine failure modes and devinachinery. To apply suitable repair methods and 	principl ategorie chnique	es and res and a	object method association	etives of soft maintage ted tools upgical and	tenance is used in m	ncluding preventive nodern maintenance al fault detection in						
UNIT-I	UNIT-I Principles and Practices of Maintenance Planning												
- Benefits of sound	maintenance planning - Objectives and print Maintenance systems - Reliability and magaintenance organization – Maintenance econ	chine a				•	V 1						
UNIT-II	Maintenance Policies – Preventive Main	ntenanc	e				9						
	ories – Comparative merits of each categorial methods of lubrication – TPM.	ry – Pr	eventiv	e main	tenance, n	naintenan	ce schedules, repair						
UNIT-III	Condition Monitoring						9						
	ring – Cost comparison with and without I – Temperature sensitive tapes – Pistol ther				•		ing – Methods and						
UNIT-IV	Repair Methods for Basic Machine Ele		218 – WE	ai-ueo	iis anaiysi	S	9						
	or beds, slide ways, spindles, gears, lead s gical fault location methods – Sequential fau			rings -	- Failure a	analysis -	- Failures and their						
UNIT-V	Repair Methods for Material Handling						9						
Repair methods f	or Material handling equipment - Equip	ment r	ecords	–Job	order syst	tems -Us	e of computers in						
maintenance.													
					Total	hours	45						
 Explain the objectives, types, and economic principles of maintenance systems and their impa on equipment availability. Differentiate among various maintenance strategies and evaluate preventive and TP techniques. Apply condition monitoring methods using appropriate tools and interpret test results f maintenance planning. Analyze common mechanical failures and develop logical procedures for fault diagnosis. Demonstrate repair procedures for industrial equipment and utilize computerized systems f maintenance management. 													
TEXT BOOK:			- D		3.6		1000						
Edition, 2						ent, S. Cl	nand & Co, 2nd						
2 Venkatara	aman, "Maintenance Engineering & Manage	ement",	PHI Le	arning,	2009.								
3 B. S. Dhil	lon, Engineering Maintenance: A Modern A	pproac	h, CRC	Press,	2019								

REFE	RENCES:
1	B. S. Dhillon Maintainability, Maintenance, and Reliability for Engineers, CRC Press, 2006
2	Garg M.R., "Industrial Maintenance", S. Chand & Co., 3rd edition 2012.

co's	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	2	2	2	2	2	-	-	-	-	2	2	3	-
CO2	3	3	2	2	2	2	2	-	-	-	-	2	2	3	-
CO3	3	3	3	3	3	1	1	-	-	-	-	3	2	3	-
CO4	3	3	3	3	3	1	1	-	-	-	-	2	2	3	-
CO5	3	3	3	2	3	1	1	-	-	-	-	3	2	3	-

Course code	Course Name	Но	ours/w	eek	Credit	Ma	aximum marks
		L	T	P	C		
24ME15402	Digital Manufacturing and IOT	3	0	0	3		100
Objective(s)	 To study the various aspects of digital To inculcate the importance of DI Management To formulate of smart manufacturing To interpret IoT to support the digital To elaborate the significance of digital 	M in l system manuf	Product ns in the	Lifec			***
UNIT-I	Introduction						9
UNIT-II Collaborative Product nd Product reuse —	Digital Life Cycle & Supply Chain Mar ct Development, Mapping Requirements to Engineering Change Management, Bill of ent – Virtual testing and collateral. Overview	nageme o speci Materi	e nt fication	ıs – Pa	rt Number	ing, En	9 Igineering Vaulting
SC - Effective Digita	l Transformation - Future Practices in SCM					•	
UNIT-III	Smart Factory						9
•	els of Smart Factories – Benefits – Techno Factory – Creating a Smart Factory – Smar	_			•	Smart 1	Factory in IoT- Ke
UNIT-IV ntroduction — Induservices — Intelligent	Factory – Creating a Smart Factory – Smar Industry 4.0 try 4.0 –Internet of Things – Industrial Innetworks of manufacturing – Cloud compu	rt Facto	ories and	d Cybe	r security Framework:	Conne	9 ectivity devices an
UNIT-IV Introduction – Industrices – Intelligent Machine communica	Factory – Creating a Smart Factory – Smar Industry 4.0 try 4.0 –Internet of Things – Industrial Innetworks of manufacturing – Cloud compution – Case Studies.	rt Facto	ories and	d Cybe	r security Framework:	Conne	9 ectivity devices an
UNIT-IV Introduction – Industrices – Intelligent Machine communica UNIT-V Basic Concepts – Fe	Factory – Creating a Smart Factory – Smar Industry 4.0 try 4.0 –Internet of Things – Industrial Innetworks of manufacturing – Cloud compu	nternet ting – l	of Thir Data an	ngs – I alytics	Framework: -Cyber phy	Conne ysical s	9 ectivity devices anystems –Machine of 9 Building Blocks
UNIT-IV Introduction – Industrices – Intelligent Machine communica UNIT-V Basic Concepts – Fe	Factory – Creating a Smart Factory – Smar Industry 4.0 try 4.0 –Internet of Things – Industrial Innetworks of manufacturing – Cloud compution – Case Studies. Study of Digital Twin eatures and Implementation – Digital Twir	nternet ting – l	of Thir Data an	ngs – I alytics	Framework: -Cyber phy	Conne ysical s hadow- ire of D	9 ectivity devices an ystems –Machine t 9 • Building Blocks
UNIT-IV Introduction – Industrices – Intelligent Machine communica UNIT-V Basic Concepts – Fe	Factory – Creating a Smart Factory – Smar Industry 4.0 try 4.0 –Internet of Things – Industrial Innetworks of manufacturing – Cloud compution – Case Studies. Study of Digital Twin eatures and Implementation – Digital Twir	nternet ting – l n: Digir fits, Im gital ma digital ent. ing praen ind its re	of Thir Data an tal Thre apact & anufactu produc ctical woole in de	ngs – Ings – Ing	r security Framework: —Cyber phy d Digital S nges — Futu Total h opment life rough digita nanufacturii	hadow- re of D cycle p	9 ectivity devices anystems –Machine of 9 Building Blocks Digital Twins 45 process and supply ation in Factories.
UNIT-IV Introduction — Industry Introduction — Industry Interligent Machine communica UNIT-V Basic Concepts — For Types — Characterist	Industry 4.0 Itry 4.0 —Internet of Things — Industrial Innetworks of manufacturing — Cloud compution — Case Studies. Study of Digital Twin eatures and Implementation — Digital Twir ics of a Good Digital Twin Platform — Benefic Differentiate the concepts involved in chain management in digital environment of Select the proper procedure of validation — Implementation the concepts of IoT are	nternet ting – l n: Digir fits, Im gital ma digital ent. ing praen ind its re	of Thir Data an tal Thre apact & anufactu produc ctical woole in de	ngs – Ings – Ing	r security Framework: —Cyber phy d Digital S nges — Futu Total h opment life rough digita nanufacturii	hadow- re of D cycle p	9 ectivity devices arystems –Machine 9 Building Blocks Digital Twins 45 process and supply

REFERENCES:

- Lihui Wang and Andrew YehChing Nee, Collaborative Design and Planning for Digital Manufacturing, SpringerVerlag London Limited, 2009.
- Andrew Yeh Chris Nee, Fei Tao, and Meng Zhang, "Digital Twin Driven Smart Manufacturing", Elsevier Science., United States, 2019.
- Alp Ustundag and Emre Cevikcan, "Industry 4.0: Managing The Digital Transformation", Springer Series in Advanced Manufacturing., Switzerland, 2017

CO'S	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	2	2	3	-	-	-	-	-	-	2	2	3	-
CO2	3	2	3	2	3	-	-	-	-	-	-	2	2	3	-
CO3	3	3	3	3	3	-	-	-	-	-	-	2	2	3	-
CO4	3	2	3	2	3	-	-	-	-	-	-	3	2	3	-
CO5	3	3	3	3	3	-	-	-	-	-	-	3	2	3	-

Course code	Course Name	Н	ours/w	eek	Credit	Ma	aximum marks
	Manufacturing Information	L	T	P	C		
24ME15403	Systems	3	0	0	3		100
Objective(s)	 To introduce the role and componen To provide an understanding of data To explain ERP and MES systems u To expose students to decision supp To develop skills in applying MIS component 	base de sed in p ort tool	esign an olanning s and er	d mana g, exec nergin	agement for ution, and r g digital tec	r manuf monitor chnolog	acturing operations. ing. ies.
UNIT-I	Introduction to Manufacturing Inform	ation S	systems				9
Hardware, Software,	nufacturing, Types of manufacturing sys Procedures, People, Data, Introduction to inportance of information in decision makin	System	Develo				•
UNIT-II	Database Management for Manufactur	ring					9
design: normalization	ntabases, Entity Relationship (ER) modeling and schema development, Manufacturication and inventory control	0.					•
UNIT-III	ERP and MES Systems						9
MRP-II vs ERP, Be	(Enterprise Resource Planning), ERP mo enefits and challenges of ERP in manufa of ERP and MES with shop-floor control						
UNIT-IV	Decision Support and Monitoring Tool	s					9
Decision Support Sy uptime, Basic forec	Decision Support and Monitoring Tool vestems (DSS) and their use in manufacture asting techniques: moving averages, ex DA and sensors, Role of dashboards and KE	iring, F	ial smo	othing	g, Real-tim		ad time, cycle time
Decision Support Sy uptime, Basic forec	vstems (DSS) and their use in manufacturasting techniques: moving averages, ex	aring, Faponent	ial smo	othing	g, Real-tim		ad time, cycle time
Decision Support Sy uptime, Basic forecontroduction to SCAI UNIT-V Industry 4.0 and the manufacturing, Basic	easting techniques: moving averages, ex DA and sensors, Role of dashboards and KF	pring, Faponent PIs in prince of the prince	ial smo	oothing on man digital	Real-tim agement twins, Int	ternet	ad time, cycle time itoring and control 9 of Things (IoT) in
Decision Support Sy uptime, Basic forecontroduction to SCAI UNIT-V Industry 4.0 and the manufacturing, Basic	extems (DSS) and their use in manufacturesting techniques: moving averages, ex DA and sensors, Role of dashboards and KE Smart Manufacturing and Emerging To the role of information systems, Smart fires of cloud computing and cyber security	pring, Faponent PIs in prince of the prince	ial smo	oothing on man digital	Real-tim agement twins, Int	ternet o	ad time, cycle time itoring and control 9 of Things (IoT) in
Decision Support Sy uptime, Basic forecontroduction to SCAI UNIT-V Industry 4.0 and the manufacturing, Basic	extems (DSS) and their use in manufacturesting techniques: moving averages, ex DA and sensors, Role of dashboards and KE Smart Manufacturing and Emerging To the role of information systems, Smart fires of cloud computing and cyber security	ring, Faponent PIs in programmer of Manufactorians of Manufactoria	s and studies IIS in a studies and the ce mone	oothing on man digital s on E manuf related eir inte	twins, Interpretation of the control	ternet ooT in r	ad time, cycle time itoring and control 9 of Things (IoT) in real-world factories,
Decision Support Sy uptime, Basic forec Introduction to SCAI UNIT-V Industry 4.0 and th manufacturing, Basic Future trends: AI in re	stems (DSS) and their use in manufacture asting techniques: moving averages, ex DA and sensors, Role of dashboards and KE Smart Manufacturing and Emerging To the role of information systems, Smart files of cloud computing and cyber security manufacturing, data analytics, sustainable Messer Students will be able to: Describe the components and function to Design simple databases to manage in Explain and compare ERP and MES Apply basic decision support and per	ring, Faponent PIs in programmer of Manufactorians of Manufactoria	s and studies IIS in a studies and the ce mone	oothing on man digital s on E manuf related eir inte	twins, Interpretation of the control	ternet ooT in r	ad time, cycle time itoring and control 9 of Things (IoT) in real-world factories,
Decision Support Sy uptime, Basic forecontroduction to SCAI UNIT-V Industry 4.0 and the manufacturing, Basic Future trends: AI in reference to the control of the control	stems (DSS) and their use in manufacture asting techniques: moving averages, ex DA and sensors, Role of dashboards and KE Smart Manufacturing and Emerging To the role of information systems, Smart files of cloud computing and cyber security manufacturing, data analytics, sustainable Messer Students will be able to: Describe the components and function to Design simple databases to manage in Explain and compare ERP and MES Apply basic decision support and per	ring, Faponent PIs in programmer of Manufactorians of Manufactoria	s and studies IIS in a studies and the ce mone	oothing on man digital s on E manuf related eir inte	twins, Interpretation of the control	ternet ooT in r	ad time, cycle time itoring and control 9 of Things (IoT) in real-world factories,
Decision Support Sy uptime, Basic forecontroduction to SCAI UNIT-V Industry 4.0 and the manufacturing, Basic Future trends: AI in reference to the control of the control	stems (DSS) and their use in manufacture asting techniques: moving averages, ex DA and sensors, Role of dashboards and KE Smart Manufacturing and Emerging To the role of information systems, Smart first of cloud computing and cyber security manufacturing, data analytics, sustainable Messer Students will be able to: Describe the components and function to Design simple databases to manage in Explain and compare ERP and MES. Apply basic decision support and per Understand and evaluate the impact of the province of the components of the province of the components and function to the province of the components and function of the province of the components and function of the province of the pro	PIs in properties of Manufactorians of Manufactorians of Indus	roductions and studies and the studies and the studies and the studies are the studies and the studies are the	oothing on man digital s on E manuf related eir intestoring on MIS	twins, Interpretation of the control	ternet ooT in r	ad time, cycle time itoring and contro 9 of Things (IoT) in eal-world factories,
Decision Support Sy uptime, Basic forecontroduction to SCAI UNIT-V Industry 4.0 and the manufacturing, Basic Future trends: AI in respect to the control of the control o	stems (DSS) and their use in manufacture asting techniques: moving averages, ex DA and sensors, Role of dashboards and KE Smart Manufacturing and Emerging To the role of information systems, Smart files of cloud computing and cyber security manufacturing, data analytics, sustainable Messer Students will be able to: Describe the components and function to Design simple databases to manage in Explain and compare ERP and MES. Apply basic decision support and per Understand and evaluate the impact of mufacturing Information and Systems.	PIs in properties of Manufactorians of Manufactorians of Indus	roductions and studies and the studies and the studies and the studies are the studies and the studies are the	oothing on man digital s on E manuf related eir intestoring on MIS	twins, Interpretation of the control	ternet ooT in r	ad time, cycle time itoring and contro 9 of Things (IoT) in eal-world factories,
Decision Support Syuptime, Basic forecontroduction to SCAI UNIT-V Industry 4.0 and the manufacturing, Basic Future trends: AI in respect to the property of	stems (DSS) and their use in manufacture asting techniques: moving averages, ex DA and sensors, Role of dashboards and KE Smart Manufacturing and Emerging To the role of information systems, Smart files of cloud computing and cyber security manufacturing, data analytics, sustainable Messer Students will be able to: Describe the components and function to Design simple databases to manage in Explain and compare ERP and MES. Apply basic decision support and per Understand and evaluate the impact of mufacturing Information and Systems.	PIs in properties of the prope	IIS in a studies and the ce month of try 4.0	manuf manuf related eir inte itoring on MIS	twins, Interpretation of the control	ternet coor in r	9 of Things (IoT) in eal-world factories,

CO'S	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	2	2	3	-	-	1	-	-	1	2	2	3	-
CO2	3	3	3	2	3	-	-	1	-	-	1	2	2	3	-
CO3	3	2	3	2	3	-	-	1	-	-	1	2	2	3	-
CO4	2	3	3	3	3	-	-	1	-	-	1	2	2	3	-
CO5	2	2	2	2	3	-	-	2	-	-	2	3	2	3	-

Course code	Course Name	Н	ours/w	eek	Credit	Maximum marks
24ME15404	Industrial Safety	L	T	P	С	100
Objective(s)	 To study the fundamental concept and prince To study the principles of maintenance engine To analyzing the wear and its reduction. To study the faults in various tools, equipmed To study the periodic maintenance procedure 	neering.	machir	nes.		
UNIT-I	Introduction					9
Evolution of r Exposure.	nodern safety concepts - Fire prevention - Med	chanical	hazard	s - Bo	ilers, Pres	sure vessels, Electric
UNIT-II	Chemical Hazards					9
Chemical expo Toxicology.	sure - Toxic materials - Ionizing Radiation and I	Non-ioni	zing R	adiatior	ı - Industri	al Hygiene - Industri
UNIT-III	Environmental Control					9
	th Hazards - Environmental Control - Industrial Isonal Protection.	Noise -	Noise r	neasuri	ng instrum	ents, Control of Nois
UNIT-IV	Hazard Analysis					9
System Safety analysis and Ri	Analysis - Techniques - Fault Tree Analysis (FTAsk Assessment), Failur	e Mode	s and E	Effects Ana	lysis (FMEA), HAZO
UNIT-V	Safety Regulations					9
•	isaster management - catastrophe control, hazardons Product safety.	control	, Safety	educa	tion and ti	raining - Factories Ac
					Total h	ours 45
Outcome(s)	 Explain the evolution of safety concepts Analyze chemical hazards and evaluate Assess industrial environmental hazard methods. Apply hazard analysis techniques such a Interpret safety regulations and develop 	industria s and ap as FTA, l	al toxico oply app FMEA,	ology ai propria HAZO	nd hygiene te control a P, and risk	practices. and personal protection assessment.
TEXT BOOK	X :					·
	n and Sunil S.Rao , Industrial Safety , Health and lelhi 2006.	Environ	ment M	anagen	nent Syster	ms, Khanna publishers
2. John V	Grimaldi, Safety Management, AITB S Publishers	, 2003.				
3. Safety	Manual, EDEL Engineering Consultancy, 2000.					
/1	L.Goetsch, Occupational Safety and Health for Teca Education Ltd., 2005.	hnologis	sts, 5th	Edition	, Engineers	and Managers,
REFERENC	ES:					
	Handbook of Occupational Safety and Health, Joh					
	Lees - Loss of prevention in Process Industries, V					
3. 2012.	Lees, "Lees' Loss Prevention in the Process Industr				ion, Assess	ment and Control",
4. Ralph V	W. King and J. Majid, "Industrial Hazard and Safet	y Handb	ook", 1	979.		

CO'S	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	2	2	2	3	3	2	1	1	1	2	2	2	2
CO2	3	3	2	3	2	3	3	2	1	1	1	2	2	2	2
CO3	3	3	2	3	2	3	3	2	1	1	1	2	2	2	2
CO4	3	3	3	3	3	3	3	2	1	1	1	3	3	3	2
CO5	2	2	3	2	2	3	2	3	2	2	2	3	2	2	2

Course co	ode Course Name	Н	ours/w	eek	Credit	N	Iaximum n	narks
24ME154	05 Plant Layout and Material Handling	L	T	P	С		100	
241111111111111111111111111111111111111	Thank Dayout and Material Handing	3	0	0	3		100	
	To study the various types of plant lay	youts.						
Objective(s								
	To understand the importantance of m			_		oduct	ion cost	
	To understand the bottlenecks in materials. The state of the sta		_	•				
UNIT-I	• To understand various safety measure Introduction	s to be	taken	n mate	riai nandiin	g syste	ems.	<u> </u>
		.4 1	4a T a.	مل عددد	.:			
	n of Layout, Advantages and Limitations of differencess layout & Product layout: Selection, specification	•			~ .			•
and process	•	OII. IIII _j	picincii	tation	and Tonow	up. C	zomparison c	n product
UNIT-II	Heuristics for Plant Layout						9)
	for Plant layout - ALDEP. CORELAP, CRA	FT (Group	Lavou	t Fixed r	ositio	n lavout- (Quadratic
	model. Branch and bound method.		эгоир	Layou	i, Tinea j	OBILIO	n layout	Quadratic
UNIT-III	Introduction to Material Handling systems						9)
Introduction	, Material Handling systems. Material hand	lling	princir	oles. (Classificatio	n of	Material	Handling
	Relationship of material handling to plant layout.	0	r · r					
UNIT-IV	Basic Material Handling systems:						9)
Basic Mater	ial Handling systems: Selection, Material Handli	ng me	thod-	path, E	Equipment,	functi	on oriented	systems.
UNIT-V	Analysis of Material Handling						9)
Methods to	minimize cost of material handling- Maintenan	ce of	Materi	al Han	dling Equi	pment	's, Safety i	n handlin
Ergonomics	of Material Handling equipment. Design, Miscelland	eous ec	quipme	nt's.				
	Total hours					45		
	Upon completion of this course, the Learners wi	ill he al	hle to :					
	 Discuss the various types of plant layouts. 		oic to.					
	Explain the Plant Layouts for various types		dustrie	S.				
Outcome(s)								
Outcome(s)	Estimate the bottlenecks in material handle.	ing sys	stems.					
	Discuss the ergonomics of material handli	•						
TEXT BO	- The state of the							
<u> </u>		mla Ia	he Wil	ov. 6- C	on a			
	ant Layout and Material Handling, by- James M. Ap					T 11		
	acility Layout and Location: An Analytical Approach				cis, Pearsoi	1 India		
3. Pl	ant Layout and Material Handling, by- B. K. Aggary	val, Jai	in Brotl	ners.				

CO'S	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	2	2	2	-	-	1	-	1	1	2	2	3	-
CO2	3	2	3	2	2	-	-	1	-	1	1	2	2	3	-
CO3	3	3	3	3	3	-	-	1	-	1	1	2	2	3	-
CO4	3	3	3	3	3	-	-	1	-	1	1	2	2	3	-
CO5	3	2	2	2	2	-	-	1	-	1	1	2	2	3	-

Course co	le Course Name	Но	ours/w	eek	Credit	Maximum marks
24ME1540	Industrial Engineering and Management	L	T	P	С	100
Objective(s	 To understand the technique and procedures To understand the plant layout and materials To study the motivation theories To study the planning procedures Human e To understand the methods of wage payment 	s handl ffective	ing sys		3	
UNIT-I	Work Measurement and Work Study					9
study, Techn	rement, Techniques- Production study, Time study, iques- Human factors- Work study and productivity Motion economy principles- SIMO chart-Ergonomics'	-meth	od stud	y, Tec	hniques an	1 0
UNIT-II	Plant Layout and Material Handling					9
layout, proce line balancing	s, site selection- Plant layout types, need, factors influess chart, flow diagram, string diagram, Template and Material Handling, scope and importance- Types of thods of material handling.	l Scale	model	s- Layo	out Plannin	g procedure- Assembly
UNIT-III	Motivation Theories and Leadership					9
Mayo's Haw Leadership: I UNIT-IV Need for Pro-	leaning and Types of Motivation – Theories of Motivation – Experiment- Herzberg two factor theory of Definition, Meaning, Features and Types of Leadership Productivity Planning And Implementation ductivity Planning – Short term and long term product Productivity Improvement techniques – Technology 1	of mot	ivation	, Masl	ow's hiera	9 nprovement approaches,
techniques –	Managerial aspects of Productivity Implementation sc				_	ontrol
UNIT-V	Wages and Incentives					9
of wage payr	lary administration- Meaning principles- Techniques nent. Incentive scheme, Types, Advantages and disacincentive scheme.			ductivi	ty base inc	entives, Case Example-
					Total hou	urs 45
Outcome(s)	 Discuss the principles and techniques of work productivity. Apply plant layout tools and material handling Analyze various motivation theories and leader Evaluate different productivity improvement te Design wage and incentive schemes using jumotivation. 	methooship st	ds to de yles to es and	esign ef improv develoj	ficient mar e employed p implemer	nufacturing systems. e performance. ntation plans.
TEXT BOO	OK:					
1 Kh	anna O. P., Industrial Engineering and Management, I	Khanna	publis	hers, N	ew Delhi,	1999
	C.Jain & L.N. Aggarwal, "Production Planning Con 90) reprint 2002	trol ar	nd Indu	strial N	Managemei	nt", Khanna Publishers,
REFEREN						
	rtand Telsang, "Industrial Engineering and Production, 2006.	tion M	lanager	nent",	S. Chand	and Company, Second

co's	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	2	3	2	2	2	2	1	1	1	3	2	3	-
CO2	3	3	3	3	3	1	1	2	1	1	1	3	2	3	-
CO3	3	3	2	3	2	3	3	3	2	2	1	3	1	2	-
CO4	3	3	3	3	3	2	2	2	1	1	1	3	2	3	-
CO5	3	3	3	3	3	2	2	2	1	1	1	3	2	3	-

Course code	Course Name	Н	ours/we	eek	Credit	Maximum ma	rks
		L	Т	P	С		
24ME15501	Automobile Engineering	3	0	0	3	100	
Objective (s)	 To make wider the understanding components. To understand the concepts modifications in automobiles. To study the Constructional and To understand the concepts of value Structural Systems of Automobiles. To know the safety, security in Automobiles. 	of enginal of theoretic vehicle suites.	ne, igr cal cond b syste	nition cepts of ms like	and fuel f transmissi e Steering,	supply system an on systems. Braking, Suspensio	nd its
UNIT-I	Introduction To Vehicle Structure, E	ngine Co	ompon	ents			9
Cylinder arrangem Piston pin - Conne - Types - Water pu	on - Chassis and body - Specifications ent - Construction details - Cylinder bloc ecting rod - Crankshaft - Valves. Lubricat emps - Radiators - Electronic Engine Man	k - Cylin tion syste nagemen	der hea m - Ty t Syster	d - Cyl pes - C	linder liner	s - Piston – piston r	rings - ystem
UNIT-II	Ignition, Fuel Supply and Emission C	ontrol S	ystem				9
- Fuel pumps - Fu Injection system (I and environment Recirculation (EG UNIT-III Clutches - Functio - Sliding - Const Hydromatic transr	Coil and Magneto - Spark plug - Distributed injection systems - Mono point and MEFI) - GDI, MPFI, DTSI-Automobile Errocontrol techniques - Engine Emission R). Transmission System n - Types - Single plate, Multiple plate arant - Synchromesh - Overdrive - Automission - Continuously variable transmission axle assembly - Types of Differential - D Steering, Suspension, Braking System	fulti poin missions n Control and Diaphi omatic t sion - Ur ifferentia	t – Uni – Sourd l by 3– ragm C ransmis niversal	t inject ce of fo -Way (lutch – ssion - joint - - Four	or – Nozzlormation – Catalytic C Fluid coup Torque co	e types - Electronic Effects on human I ontroller – Exhaus ling - Gearbox - M onverter - Epicylic shaft - Hotchkiss d	e Fuel health t Gas 9 Ianual c and
	ng - Steering Geometry and wheel align				ges –Powe	r steering - front :	
Suspension system - Wheel sand Tire -Drum and Disc	a - Independent and Solid axle – coil, leaf s - Construction - Types and specification Mechanical system- Hydraulic and pneu ypes of Wheels -Wheel Balancing. Types	f spring a ns - Tire v matic - V	nd air s wear an √acuun	suspens d cause n assist	sions - torsi es - Brakes ed –Retard	on bar - shock abso - Needs —Classific ers — Anti-lock Br	orbers ations aking
	Automotive Electrical Systems, Instru- ectrical circuits-Dash board instrumentation, and Air Conditioning) - Seat belts	tion - Pa	assenge	r comf	ort – Safet	y and security - H	
(Heating, Ventilat Unit (ECU) - Van	ectrical circuits-Dash board instrumentation, and Air Conditioning) - Seat belts riable Valve Timing (VVT) - Active Suic Stability Program(ESP) Traction Con	ttion - Pa - Air bag uspensior trol Syst	nssenge gs - Au n Syste em (TO	r comf tomoti m (AS	ort – Safet ve Electror S) - Electr	y and security - H nics - Electronic Co conic Brake Distrib tioning System (G	IVAC ontrol oution
(Heating, Ventilat Unit (ECU) - Van (EBD) - Electron	ectrical circuits-Dash board instrumentation, and Air Conditioning) - Seat belts riable Valve Timing (VVT) - Active Suic Stability Program(ESP) Traction Con	ation - Pa - Air bag aspensior	nssenge gs - Au n Syste em (TO	r comf tomoti m (AS	ort – Safet ve Electror S) - Electr	y and security - H nics - Electronic Co onic Brake Distrib	IVAC ontrol oution
(Heating, Ventilat Unit (ECU) - Van (EBD) - Electron	ectrical circuits-Dash board instrumentation, and Air Conditioning) - Seat belts riable Valve Timing (VVT) - Active Suic Stability Program(ESP) Traction Con	tion - Pa - Air bag uspension trol Syst Total honents and systems,	assenge gs - Au n Syste em (TO	r comf tomoti m (AS CS) - C	ort – Safet ve Electron S) - Electr Global Posi of vehicle	y and security - Horics - Electronic Coronic Brake Distributioning System (G	IVAC ontrol oution BPS) -

	• Explain automotive electrical systems, instrumentation, and recent advancements in vehicle electronics and safety features.
TEX	Γ BOOKS:
1	Devaradjane. Dr. G., Dr. M. Kumaresan, "Automobile Engineering", AMK Publishers, 2013.
2	Kirpal Singh Vol. I & II "Automobile Engineering", Standard Publishers, New Delhi, 2011.
3	Srinivasan.S, — Automotive Mechanics, 2nd edition, Tata McGraw-Hill, 2003.
REFI	ERENCES:
1	Srinivasan S, "Automotive Mechanics" Tata McGraw-Hill Publications, 2011.
2	Kapil Dev, "Automobile Engineering Theory ", Asian Books Pvt. Ltd, 2001.
3	Joseph Heitner, "Automotive Mechanics: Principles and Practices" East - West Press publications, 2001.
4	William H., Crouse & Donald L Anglin, "Automotive mechanics",10 th Edition Tata McGraw Hill Publishing Company Ltd., 2007.

CO'S	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	3	2	1	1	2	1	1	-	-	2	3	2	2
CO2	3	2	3	2	2	2	2	1	1	-	-	2	3	3	2
CO3	3	3	3	2	2	1	3	2	2	-	-	2	3	2	2
CO4	3	2	3	2	3	2	3	2	2	-	-	2	3	3	2
CO5	3	3	3	2	2	1	3	3	2	-	-	2	3	3	3

Course code	Course Name	ours/w	eek	Maximum marks		
24ME15502	Conventional and Futuristic Vehicle	L	T	P	C	100
241111111111111111111111111111111111111	Technology	3	0	0	3	100
	To study the advanced engine technologies					
	• To understand various advanced combustion		_			
Objective(s)	• To understand the methods of using low carb			_	ficance	
	To understand the hybrid and electric vehicle	•	-			
	To study the application of fuel cell technological t	gy in a	utomo	tives		
UNIT-I	Advanced Engine Technology					9
	njection, Common Rail Direct Injection, Variab VT, Intelligent Cylinder De-activation, After T					
UNIT-II	Combustion Technology					9
Spark Ignition co	mbustion, Compression Ignition Combustion, Co	onventi	ional D	Oual Fu	el Combust	tion. Low Temperatur
Combustion Con Compression Igni	cepts— Controlled Auto Ignition, Homogeneous ition, Partially Premixed Compression Ignition, Compression Ignition.	us Cha	arge C	Compres	sion Igniti	ion, Premixed Charg
UNIT-III	Low Carbon Fuel Technology					9
	Ammonia Fuel and Combustion, Methan			5,		,, 8
Technology, Ch	Hybrid And Electric Vehicle					9
UNIT-IV Conventional Hyl		ybrids	(RCCI	/GDCI	Engine +	
UNIT-IV Conventional Hyl	Hybrid And Electric Vehicle brids (Conventional ICE + Battery), Modern Hy	ybrids	(RCCI	/GDCI	Engine +	
UNIT-IV Conventional Hylvehicle Technolo UNIT-V Fuel cells for auto Liquid hydrogen a	Hybrid And Electric Vehicle brids (Conventional ICE + Battery), Modern H gy - Challenges and Way forward	Tuel cel	l vehic	le syste	ms - Onbo	Battery), Pure Electri 9 ard hydrogen storage
UNIT-IV Conventional Hylvehicle Technolo UNIT-V Fuel cells for auto Liquid hydrogen a	Hybrid And Electric Vehicle brids (Conventional ICE + Battery), Modern Hygy - Challenges and Way forward Fuel Cell Technology comotive applications - Technology advances in f	Tuel cel	l vehic	le syste	ms - Onbo	Battery), Pure Electri 9 ard hydrogen storage fuel cell - Road map to
UNIT-IV Conventional Hyl Vehicle Technolo UNIT-V Fuel cells for auto	Hybrid And Electric Vehicle brids (Conventional ICE + Battery), Modern Hygy - Challenges and Way forward Fuel Cell Technology comotive applications - Technology advances in fand compressed hydrogen - Metal hydrides, Fuel	uel cel cell co	l vehic	le syste	ms - Onbo - Alkaline f	Battery), Pure Electri 9 ard hydrogen storage fuel cell - Road map t
UNIT-IV Conventional Hylvehicle Technolo UNIT-V Fuel cells for auto Liquid hydrogen a	Hybrid And Electric Vehicle brids (Conventional ICE + Battery), Modern Hygy - Challenges and Way forward Fuel Cell Technology comotive applications - Technology advances in fand compressed hydrogen - Metal hydrides, Fuel Upon completion of this course, the Learners will	Tuel cel cell co	l vehic	le syste	ms - Onbo - Alkaline f	Battery), Pure Electri 9 ard hydrogen storage fuel cell - Road map t
UNIT-IV Conventional Hylvehicle Technolo UNIT-V Fuel cells for auto Liquid hydrogen a	Hybrid And Electric Vehicle brids (Conventional ICE + Battery), Modern Hygy - Challenges and Way forward Fuel Cell Technology comotive applications - Technology advances in found compressed hydrogen - Metal hydrides, Fuel Upon completion of this course, the Learners will • Discuss the latest trends in engine technology	Tuel cell colling	l vehice ontrol state of the leto:	le syste system	ms - Onbo - Alkaline t	Battery), Pure Electri 9 Pard hydrogen storage fuel cell - Road map t 118 45
UNIT-IV Conventional Hyl Vehicle Technolo UNIT-V Fuel cells for auto Liquid hydrogen a market.	Hybrid And Electric Vehicle brids (Conventional ICE + Battery), Modern Hygy - Challenges and Way forward Fuel Cell Technology comotive applications - Technology advances in fand compressed hydrogen - Metal hydrides, Fuel Upon completion of this course, the Learners will Discuss the latest trends in engine technolog Discuss the need of advanced combustion	Tuel cell colling	l vehice ontrol state of the leto:	le syste system	ms - Onbo - Alkaline t	Battery), Pure Electri 9 Pard hydrogen storage fuel cell - Road map t 118 45
UNIT-IV Conventional Hyl Vehicle Technolo UNIT-V Fuel cells for auto Liquid hydrogen a market.	Hybrid And Electric Vehicle brids (Conventional ICE + Battery), Modern Hygy - Challenges and Way forward Fuel Cell Technology comotive applications - Technology advances in for and compressed hydrogen - Metal hydrides, Fuel Upon completion of this course, the Learners will Discuss the latest trends in engine technolog Discuss the need of advanced combustion print on the environment. Analyzing the basic characteristics of low of achieving sustainable development goals.	uel cel cell co ll be ab gy techno	l vehice ontrol so le to:	le system system and its	Total hou	Battery), Pure Electri 9 eard hydrogen storage fuel cell - Road map tell 11 45 reducing carbon foot inventional fuels and in
UNIT-IV Conventional Hyl Vehicle Technolo UNIT-V Fuel cells for auto Liquid hydrogen a market.	Hybrid And Electric Vehicle brids (Conventional ICE + Battery), Modern Hygy - Challenges and Way forward Fuel Cell Technology comotive applications - Technology advances in formation and compressed hydrogen - Metal hydrides, Fuel Upon completion of this course, the Learners will Discuss the latest trends in engine technolog Discuss the need of advanced combustion print on the environment. Analyzing the basic characteristics of low of	uel cel cell co ll be ab gy techno	l vehice ontrol so le to : logies fuels, i	le system system and its	Total hou	Battery), Pure Electri 9 eard hydrogen storage fuel cell - Road map tell 11 45 reducing carbon foot inventional fuels and in
UNIT-IV Conventional Hyl Vehicle Technolo UNIT-V Fuel cells for auto Liquid hydrogen a market. Outcome(s)	Hybrid And Electric Vehicle brids (Conventional ICE + Battery), Modern Hygy - Challenges and Way forward Fuel Cell Technology comotive applications - Technology advances in for and compressed hydrogen - Metal hydrides, Fuel Upon completion of this course, the Learners will Discuss the latest trends in engine technolog Discuss the need of advanced combustion print on the environment. Analyzing the basic characteristics of low of achieving sustainable development goals. Discuss the working and energy flow in var Analyzing the need for fuel cell technology	uel cell cell cell cell cell cell cell c	l vehice ontrol so le to : logies fuels, in the brid and	and its	ms - Onbo - Alkaline f Total hou impact on act over con ric configu	Battery), Pure Electri 9 eard hydrogen storage fuel cell - Road map t 11 45 reducing carbon foot enventional fuels and in
UNIT-IV Conventional Hyl Vehicle Technolo UNIT-V Fuel cells for auto Liquid hydrogen a market.	Hybrid And Electric Vehicle brids (Conventional ICE + Battery), Modern Hygy - Challenges and Way forward Fuel Cell Technology comotive applications - Technology advances in for and compressed hydrogen - Metal hydrides, Fuel Upon completion of this course, the Learners will Discuss the latest trends in engine technolog Discuss the need of advanced combustion print on the environment. Analyzing the basic characteristics of low of achieving sustainable development goals. Discuss the working and energy flow in var Analyzing the need for fuel cell technology	uel cell cell cell cell cell cell cell c	l vehice ontrol so le to : logies fuels, in the brid and	and its	ms - Onbo - Alkaline f Total hou impact on act over con ric configu	Battery), Pure Electri 9 eard hydrogen storage fuel cell - Road map t 11 45 reducing carbon foot any enventional fuels and in
UNIT-IV Conventional Hyl Vehicle Technolo UNIT-V Fuel cells for auto Liquid hydrogen a market. Outcome(s) TEXT BOOK:	Hybrid And Electric Vehicle brids (Conventional ICE + Battery), Modern Hygy - Challenges and Way forward Fuel Cell Technology comotive applications - Technology advances in for and compressed hydrogen - Metal hydrides, Fuel Upon completion of this course, the Learners will Discuss the latest trends in engine technolog Discuss the need of advanced combustion print on the environment. Analyzing the basic characteristics of low of achieving sustainable development goals. Discuss the working and energy flow in var Analyzing the need for fuel cell technology	ll be abgy technolious hy in auto	l vehice ontrol so le to: logies fuels, i omotive Modern	and its impa	ms - Onbo - Alkaline f Total hou impact on ct over con ric configurations.	Battery), Pure Electri 9 Pard hydrogen storage fuel cell - Road map to the storage fuel cell - Road m
UNIT-IV Conventional Hyl Vehicle Technolo UNIT-V Fuel cells for auto Liquid hydrogen a market. Outcome(s) TEXT BOOK: 1 Mehrda Vehicle 2 Rakesh	Hybrid And Electric Vehicle brids (Conventional ICE + Battery), Modern Hygy - Challenges and Way forward Fuel Cell Technology comotive applications - Technology advances in for and compressed hydrogen - Metal hydrides, Fuel Upon completion of this course, the Learners will Discuss the latest trends in engine technolog Discuss the need of advanced combustion print on the environment. Analyzing the basic characteristics of low of achieving sustainable development goals. Discuss the working and energy flow in var Analyzing the need for fuel cell technology	uel cell cell cell cell cell cell cell c	l vehice ontrol so the le to: logies fuels, in the comotive of the learn of the lea	and its impaind electric applic	ms - Onbo - Alkaline to Total house impact on act over contric configurations. c, Hybrid	Battery), Pure Electri 9 Pard hydrogen storage fuel cell - Road map to the storage fuel cell cell cell cell cell cell cell c
UNIT-IV Conventional Hyl Vehicle Technolo UNIT-V Fuel cells for auto Liquid hydrogen a market. Outcome(s) TEXT BOOK: 1 Mehrda Vehicle 2 Rakesh	Hybrid And Electric Vehicle brids (Conventional ICE + Battery), Modern Hygy - Challenges and Way forward Fuel Cell Technology comotive applications - Technology advances in found compressed hydrogen - Metal hydrides, Fuel Upon completion of this course, the Learners with Discuss the latest trends in engine technology Discuss the need of advanced combustion print on the environment. Analyzing the basic characteristics of low of achieving sustainable development goals. Discuss the working and energy flow in varies and Ehsani, Yimi Gao, Sebastian E. Gay, Ali Eners: Fundamentals, Theory and Design, CRC Press Kumar Maurya, Characteristics and Control of 507-6, SPRINGER	uel cell cell cell cell cell cell cell c	l vehice ontrol so the le to: logies fuels, in the comotive of the learn of the lea	and its impaind electric applic	ms - Onbo - Alkaline to Total house impact on act over contric configurations. c, Hybrid	Battery), Pure Electri 9 Pard hydrogen storage fuel cell - Road map to the storage fuel cell cell cell cell cell cell cell c
UNIT-IV Conventional Hylvehicle Technolo UNIT-V Fuel cells for auto Liquid hydrogen amarket. Outcome(s) TEXT BOOK: 1 Mehrda Vehicle 2 Rakesh 319-683 REFERENCES	Hybrid And Electric Vehicle brids (Conventional ICE + Battery), Modern Hygy - Challenges and Way forward Fuel Cell Technology comotive applications - Technology advances in found compressed hydrogen - Metal hydrides, Fuel Upon completion of this course, the Learners with Discuss the latest trends in engine technology Discuss the need of advanced combustion print on the environment. Analyzing the basic characteristics of low of achieving sustainable development goals. Discuss the working and energy flow in varies and Ehsani, Yimi Gao, Sebastian E. Gay, Ali Eners: Fundamentals, Theory and Design, CRC Press Kumar Maurya, Characteristics and Control of 507-6, SPRINGER	uel cell cell cell cell cell cell cell c	l vehicontrol sole to: logies fuels, interpretation	and its impaind electricature C	ms - Onbo - Alkaline f Total hou impact on ct over con ric configurations. c, Hybrid ombustion	Battery), Pure Electric 9 pard hydrogen storage fuel cell - Road map to 45 reducing carbon foot inventional fuels and intrations. Electric and Fuel Ce

CO'S	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	3	2	2	1	3	1	1	-	-	2	3	2	2
CO2	3	2	3	2	3	2	3	2	2	-	-	2	3	3	2
CO3	3	2	2	3	3	3	3	2	2	-	-	2	3	3	3
CO4	3	3	3	2	2	1	2	3	2	-	-	2	3	3	3
CO5	3	2	2	3	2	2	3	2	1	-	-	2	3	3	3

Course co	ode	Course Name	Н	ours/w	eek	Credit	Maximum marks
24ME155	503	Renewable Powered Off Highway Vehicles and Emission Control Technology	L 3	T	P 0	C 3	100
Objective (s	s)	 To study the low and zero carbon fuels suitability To understand the green energy production mategories. To understand the various fuel cell types and its suarchine. To understand the impact of in-cylinder technologies. To study the existing after-treatment technologies. 	and methodo	ethods of the control	of use if and it finds from the first term of th	n off-road s use in c way vehicle hissions con	off-road vehicle s applications trol.
UNIT-		Low and Zero Carbon Fuels Powered Off-Highw			Sirvay	veniere app	9
		l, Butanol, Biodiesel, CNG, LNG, DME, Polyoxymet			hvl Et	her (PODE	
		uitability, methods, and technologies for powering off-r	•				,,
UNIT-I	Ι	Green Energy Powered Off-Highway Vehicles					9
		for Green Electricity, Green Electricity for Hydrogen		tion, H	ydroge	n Smart Gr	id Technologies.
		powered vehicles, Hydrogen to Fuel Cell Powered Veh	icles.				1
UNIT-I		Fuel Cell Powered Off-Highway Vehicles					9
	Den	s, Applications, Fuel Cell Requirement, Sizing nerits, Pathway to overcome the limitations. Scions.					
UNIT-I		In-Cylinder Treatment Technologies					9
	activit s.	Combustion Modes - Homogeneous Charge Comprety Controlled Compression Ignition, Gasoline Direct l After Treatment Technologies		_			•
Diesel Oxida	tion (Catalyst, Diesel Particulate Filter, Selective Catalytic R pues, Waste Heat Recovery and Organic Rankine Cycle		on, Am	monia	slip / clean	
uosorption te	Cilling	acs, waste frem recovery and organic rankine cycle	•			Total hou	rs 45
Outcome(s))	 Upon completion of this course, the Learners will be able Evaluate the availability, suitability, and its role carbon footprint on the environment. Discuss the various green energy production method off-road vehicle applications. Develop the working of fuel cell, various fuel of applications. Discuss the various in-cylinder low temperature controlling the engine-out emissions. Explain the working of various existing after tree emissions. 	in offords and cell type comb	l its impes, an	pact on d its o	categories meeting endesign for logies and	in reducing the nergy demand of off-road vehicle its key role in
TEXT BOO	OK :						
1	John	Twidell, and Tony Weir. Renewable Energy Sources –	3rd E	dition 2	015,		
2	Rake	sh Kumar Maurya, Characteristics and Control of Low	Tempe	erature	Combi	ıstion Engii	nes.
REFEREN	CES	:					
	Engi	el J Holt. Fuel Cell Powered Vehicles: Automotive Toneers, 2001 - Technology & Engineering,					
2	Towa 2011	ard Zero Carbon: The Chicago Central Area DeCarbo	nizatio	n Plan	by Ad	rian Smith	and Gordon Gill

CO'S	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	3	3	2	3	3	-	-	-	2	2	-	-	3
CO2	3	2	2	2	2	3	3	-	-	-	2	2	-	-	3
CO3	3	3	3	2	3	2	3	-	-	-	2	2	-	-	3
CO4	3	3	2	3	2	2	3	-	-	-	2	2	-	-	3
CO5	3	3	2	2	2	2	3	-	-	-	2	2	-	-	3

Cour	rse code	Course Name Hours/week Credit										
	=1==01	Vehicle Health Monitoring Maintenance	L	Т	P	С	400					
24M)	E15504	and Safety	3	0	0	3	100					
Objectiv	ve(s)	 To understand the principles, functions and vehicles. To study the powertrain maintenance, fault die To develop vehicle system maintenance and see To study the concepts of vehicle safety and refer to study and understand the simulation of safety. 	iagnos service egulati	is, mair e of clut ons.	itenanc	e of Batteri						
UN	NIT-I	Introduction	icty co	псерь			9					
Need for I systems – Computer	Maintenance power pack rized engine	e – importance, classification of maintenance work, tyres, safety systems. Scheduled maintenance seanalyzer study and practice- OBD and scan tools;	ervices				tenance of vehicle					
UN	IT-II	Powertrain Maintenance					9					
diagnosis System, C	- OBD-III at Charging Sys	t of petrol and diesel engine; - Electronic fuel nd scan tool, identifying DTC and servicing emistem and Body Electrical -Fault Diagnosis Using S	ission	control			Batteries, Starting					
UN	IT-III	Vehicle System Maintenance					9					
rotation,	Computerize	ance and Service of McPherson strut, coil springed wheel balancing & wheel alignment, Mainte										
rotation, column, R UN Concepts bags, electoristics control systemsing w	Computerize Rack and pin IT-IV of vehicle setronic syste ystem, Moderipers.	ed wheel balancing & wheel alignment, Maintaion steering Vehicle Safety safety -Seat belt, regulations, automatic seat belt em for activating air bags, bumper design for safern electronic features in vehicles like tyre presented.	tighte	ner sys	tem, co	of steering ollapsible st - ABS, EB	eering column, air D, CSC, Traction adlamp ON, Rain					
rotation, column, F UN Concepts bags, electorized systemsing w UN	Computerize Rack and pin IT-IV of vehicle setronic syste ystem, Moderipers. IIT-V	ed wheel balancing & wheel alignment, Maintaion steering Vehicle Safety safety -Seat belt, regulations, automatic seat belt om for activating air bags, bumper design for safern electronic features in vehicles like tyre president Simulation of Safety Concepts	tighte afety, A	ner sys Active monitor	tem, co Safety ing, Au	of steering ollapsible st - ABS, EB utomatic he	eering column, air D, CSC, Traction adlamp ON, Rain					
rotation, column, F UN Concepts bags, electoristics with the control systems with the control system with the control systems with the control systems with the control system with the control systems with the control system with the control systems with the control system with the control system with the control systems with the control system with the control system with the control systems	Computerize Rack and pin IT-IV of vehicle setronic syste ystem, Moderipers. IIT-V fety: driving afety, deform Collision was	ed wheel balancing & wheel alignment, Maintaion steering Vehicle Safety safety -Seat belt, regulations, automatic seat belt om for activating air bags, bumper design for safetn electronic features in vehicles like tyre present safety, conditional safety, perceptibility safety nation behavior of vehicle body, speed and accelering system, causes of rear end collision, from	tighte afety, assure r	ner sys Active monitor	tem, co Safety ing, Au	of steering ollapsible st - ABS, EB utomatic he assive safet of passeng	g linkage, steering geering column, air D, CSC, Traction adlamp ON, Rain gery: exterior safety, er compartment on					
rotation, column, F UN Concepts bags, electoristics with the control systems with the control system with the control systems with the control systems with the control system with the control systems with the control system with the control systems with the control system with the control system with the control systems with the control system with the control system with the control systems	Computerize Rack and pin IT-IV of vehicle setronic syste ystem, Moderipers. IIT-V fety: driving afety, deform Collision was	ed wheel balancing & wheel alignment, Maintaion steering Vehicle Safety safety -Seat belt, regulations, automatic seat belt em for activating air bags, bumper design for safetn electronic features in vehicles like tyre present safety, conditional safety, perceptibility safety nation behavior of vehicle body, speed and acceleration.	tighte afety, assure r	ner sys Active monitor	tem, co Safety ing, Au	of steering ollapsible st - ABS, EB utomatic he assive safet of passeng	eering column, air D, CSC, Traction adlamp ON, Rain 9 ey: exterior safety, er compartment on e object detection					
rotation, column, F UN Concepts bags, electoristics with the control systems with the control system with the control systems with the control systems with the control system with the control systems with the control system with the control systems with the control system with the control system with the control systems with the control system with the control system with the control systems	Computerize Rack and pin IT-IV of vehicle setronic syste ystem, Moderipers. IIT-V fety: driving afety, deform Collision was bject detection	ed wheel balancing & wheel alignment, Maintaion steering Vehicle Safety safety -Seat belt, regulations, automatic seat belt om for activating air bags, bumper design for safetn electronic features in vehicles like tyre present safety, conditional safety, perceptibility safety nation behavior of vehicle body, speed and accelering system, causes of rear end collision, from	tighte afety, assure ration tal obj	ner sys Active monitor ating si charact ect det	tem, co Safety ing, Au	of steering ollapsible st - ABS, EB utomatic he assive safet of passeng rear vehicl	eering column, air D, CSC, Traction adlamp ON, Rain 9 ey: exterior safety, er compartment on e object detection					
rotation, column, R UN Concepts bags, electoric control systemsing w UN Active satinterior	Computerize Rack and pin IT-IV of vehicle setronic syste ystem, Moderipers. IIT-V fety: driving afety, deform Collision was bject detection	wheel balancing & wheel alignment, Maintaion steering Vehicle Safety safety -Seat belt, regulations, automatic seat belt and for activating air bags, bumper design for safety electronic features in vehicles like tyre preserved. Simulation of Safety Concepts g safety, conditional safety, perceptibility safety nation behavior of vehicle body, speed and acceleration system, causes of rear end collision, from on system with braking system Interactions. Upon completion of this course, the Learners will Discuss the vehicle health monitoring, maintained. Explain the maintenance of power train. Discuss the maintenance of Vehicle system. Explain and awareness of vehicle safety.	tighte afety, assure ration tal obj	ner sys Active monitor ating si charact ect det	tem, co Safety ing, Au	of steering ollapsible st - ABS, EB utomatic he assive safet of passeng rear vehicl	eering column, ain D, CSC, Traction adlamp ON, Rain 9 ey: exterior safety er compartment on e object detection					
rotation, column, R UN Concepts bags, electoric control systemsing w UN Active satinterior	Computerize Rack and pin IT-IV of vehicle setronic syste ystem, Moderipers. IIT-V fety: driving afety, deform Collision was bject detection	wheel balancing & wheel alignment, Maintaion steering Vehicle Safety safety -Seat belt, regulations, automatic seat belt and for activating air bags, bumper design for safety electronic features in vehicles like tyre preserved. Simulation of Safety Concepts g safety, conditional safety, perceptibility safety nation behavior of vehicle body, speed and acceleration system, causes of rear end collision, from on system with braking system Interactions. Upon completion of this course, the Learners will Discuss the vehicle health monitoring, maintained. Explain the maintenance of power train. Discuss the maintenance of Vehicle system. Explain and awareness of vehicle safety.	tighte afety, assure ration tal obj	ner sys Active monitor ating si charact ect det	tem, co Safety ing, Au afety p eristics ection,	of steering ollapsible st - ABS, EE utomatic he assive safet of passeng rear vehicl	eering column, air PD, CSC, Traction adlamp ON, Rair PS, exterior safety er compartment or e object detection at the column of t					
rotation, column, R UN Concepts bags, electron control systemsing w UN Active satinterior sating control system, of the control system contro	Computerize Rack and pin IT-IV of vehicle setronic system, Moderipers. IIT-V fety: driving afety, deform collision was bject detection. EOOK: Ed May, "A	wheel balancing & wheel alignment, Maintaion steering Vehicle Safety safety -Seat belt, regulations, automatic seat belt and for activating air bags, bumper design for safety electronic features in vehicles like tyre preserved. Simulation of Safety Concepts g safety, conditional safety, perceptibility safety nation behavior of vehicle body, speed and acceleration system, causes of rear end collision, from on system with braking system Interactions. Upon completion of this course, the Learners will Discuss the vehicle health monitoring, mainto Explain the maintenance of power train. Discuss the maintenance of Vehicle system. Explain and awareness of vehicle safety. Explain the simulation of safety concepts.	tighte afety, assure ration tal obj	ner sys Active monitor ating si charact ect det	tem, co Safety ing, Au afety p eristics ection,	of steering ollapsible st - ABS, EB utomatic he assive safet of passeng rear vehicl Total hou	eering column, ain PD, CSC, Traction adlamp ON, Rain PD, exterior safety er compartment or e object detection e object detection 45					
rotation, column, R UN Concepts bags, electoric control systemsing w UN Active satinterior	Computerize Rack and pin IT-IV of vehicle setronic syste ystem, Moderipers. IIT-V fety: driving afety, deform Collision wan bject detection Ed May, " Jack Erjave	wheel balancing & wheel alignment, Maintaion steering Vehicle Safety safety -Seat belt, regulations, automatic seat belt and for activating air bags, bumper design for safety en electronic features in vehicles like tyre preserved safety, conditional safety, perceptibility safety nation behavior of vehicle body, speed and acceleration system, causes of rear end collision, from on system with braking system Interactions. Upon completion of this course, the Learners will Discuss the vehicle health monitoring, maint Explain the maintenance of power train. Discuss the maintenance of Vehicle system. Explain and awareness of vehicle safety. Explain the simulation of safety concepts.	tighte afety, assure ration tal obj	ner sys Active monitor ating si charact ect det	tem, co Safety ing, Au afety p eristics ection,	of steering ollapsible st - ABS, EB utomatic he assive safet of passeng rear vehicl Total hou	eering column, ain PD, CSC, Traction adlamp ON, Rain PD, exterior safety er compartment on e object detection e object detection 45					
rotation, column, R UN Concepts bags, electoric control systemsing w UN Active satinterior satinpact. Cosystem, of TEXT B 1 2	Computerize Rack and pin IT-IV of vehicle setronic syste ystem, Moderipers. IIT-V fety: driving afety, deform Collision was bject detection Ed May, "A Jack Erjave ENCES:	wheel balancing & wheel alignment, Maintaion steering Vehicle Safety safety -Seat belt, regulations, automatic seat belt and for activating air bags, bumper design for safety en electronic features in vehicles like tyre preserved safety, conditional safety, perceptibility safety nation behavior of vehicle body, speed and acceleration system, causes of rear end collision, from on system with braking system Interactions. Upon completion of this course, the Learners will Discuss the vehicle health monitoring, maint Explain the maintenance of power train. Discuss the maintenance of Vehicle system. Explain and awareness of vehicle safety. Explain the simulation of safety concepts.	tighte afety, Assure ration tal obj	ner sys Active monitor ating si charact ect det	tem, co Safety ing, Au afety peristics ection, afety.	of steering ollapsible st - ABS, EB utomatic he assive safet of passeng rear vehicl Total hou tions, Tenth ing, 5th Edi	eering column, ain D, CSC, Traction adlamp ON, Rain Py: exterior safety, er compartment on e object detection rs 45 1 edition, 2018 tion, 2012					

co's	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	2	2	1	2	2	2	2	1	1	2	3	2	2
CO2	3	3	3	2	1	2	2	2	2	1	1	2	3	3	2
CO3	3	3	3	2	1	2	2	2	2	1	1	2	3	3	2
CO4	3	2	2	3	2	2	3	2	3	2	2	3	3	3	3
CO5	3	3	3	2	2	2	2	3	3	1	1	2	3	3	3

Course code	Course Name	Но	ours/w	eek	Credit	Maximum marks
24ME15505	CAE and CFD Approach in Future	L	T	P	C	100
24MIE13303	Mobility	3	0	0	3	100
Objective(s)	 To study the use of computer in mobility sof To study the concepts computer aided design To understand the basic concepts of the finit To understand basics and fundamental of the 	and rate elements	pid pro ents me itationa	totypir thods. 1 fluid	dynamics	
UNIT-I	To understand the Turbulence Modeling and Introduction to CAE /CFD	variou	s simui	ation te	echniques.	9
Introduction to urole of compute modeling and sir	se of computer in Mobility Product Life Cycle, S rs in the design process, use of modern compu- nulation. CFD as a design and research tool, Appl	tational	tools	used f	or design a	on to design process and analysis, Concept of neering
UNIT-II	CAD and Rapid Prototyping					9
curves and surfa representation (E Formats: Types	aces: Geometric modeling curves and surfaces, Woces, Solid modeling: Fundamentals of solid modeling: Fundamentals of solid modeling, Constructive solid geometry (CSG). Mechange file formats & their exchange, Graphics standard Solid modeling for RP, Surface modeling, Stace formats	eling, l anism lards. (Differen design CAD D	nt solic and as ata and	d representa sembly. CA d Programn	ntion schemes, Boundary AD/CAM Data Exchange ning Techniques for RP:
UNIT-III	Introduction to FEA					9
Governing differ Discretization – Stiffness matrice of mechanical co	Finite Element Method, Ritz and Rayleigh Ritz rential equations of one- and two dimensional Linear and Higher order Elements – Interpolations and force vectors-Assembly of Matrices - Solumponents using 2D and 3D elements	problen and sl	ns, One	Dime	ensional Se s, Derivation	cond Order Equations – n of Shape functions and studies in stress analysis
UNIT-IV	Introduction to CFD					9
steps in CFD cor Source panel me	nentation; continuity, navier-stokes and energy enputation Various simplifications, Dimensionless whod, and Vortex panel method. Conservation for and space marching. 3-D structured and unstructured and unstruct	equation orm of	ns and the equ	param ations	eters, Incon , shock fitti	npressible inviscid flows, ing and shock capturing,
UNIT-V	Problem Solving Using CFD					9
and boundary lagand on-road sin	eling, different turbulent modeling scheme. Incomper flows. Eddy viscosity and non-eddy viscosity aulation of vehicles; Simulation of Ahmed and action in climatic and acoustic wind tunnels; velocity	model Wind	ls; Veh	icle Ae lies; V	erodynamic orticity ba	Simulation Wind tunnel sed grid-free simulation mulation
					1 otai nou	rs 45
Outcome(s)	 Upon completion of this course, the Learners w Discuss the basic concept of the CAE /CFD Develop the computer aided design and rap Discuss the basic concept of Finite Element Discuss the concepts of computational fluid Discuss the simulation using computational 	id proto metho dynan	otyping ds. nics	•		
TEXT BOOK		11414	. <i>y</i> 11411111			
1	er, M. P., CAD/CAM: Computer-Aided Design ar	d Man	ufacturi	ng, Pe	arson Educa	ation, 2008
2 Tirupa	thiR.Chandrupatla and Ashok D.Belegundu, ational Edition, Pearson Education Limited, 2014.					

3	Applied Computational Fluid Dynamics by S. C. Gupta
REFER	ENCES:
1	Dhanaraj. R and Prabhakaran Nair. K, "Finite Element Analysis", Oxford Publications, 2015.
2	Versteeg, H.K., and Malalasekera, W.,"An Introduction to Computational Fluid Dynamics": The finite volume
	Method, Pearson Education, 2014

co's	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	2	1	1	1	1	3	2	-	-	-	3	2	2
CO2	3	3	3	2	2	2	1	3	3	-	-	-	3	2	3
CO3	3	3	2	1	1	1	1	2	2	-	-	-	3	2	2
CO4	3	2	2	1	1	1	1	3	2	-	-	-	3	2	3
CO5	3	3	3	2	2	2	1	3	3	-	-	-	3	3	3

Course	code	Course Name	Ho	ours/w	eek	Credit	Ma	nximum marks
24ME1	5506	Hybrid and Electric Vehicle Technology	L	T	P	С		100
27 1V1121	.5500	Trybrid and Electric venicie recinology	3	0	0	3		100
Objective	e(s)	 To introduce the concept of hybrid and electr To elaborate on the types and utilisation of hy To expose on different types of AC and DC d To learn and utilise different types of energy To introduce concept of energy management 	ybrid a Irives f storage	nd elector electors	tric dri tric vel ns	nicles.		
UNIT	Г-І	Introduction						9
	ehicles, s	performance, vehicle power source characterizate ocial and environmental importance of hybrid						•
UNIT	-II	Hybrid Electric Drive Trains						9
train topol	logies, fı	ybrid traction, introduction to various hybrid dri uel efficiency analysis. Electric Drive-trains: Ba topologies, power flow control in electric drive-t	asic co	ncept o	of elec	tric traction	n, intro	duction to various
UNIT	-III	Control of AC & DC Drives				•		9
Induction	Motor dr	ectric components used in hybrid and electric vives, Permanent Magnet Motor drive, and Switch			_			
T IN ITEM	TT7	TE CL						
UNIT		Energy Storage						9
Introduction	on to En	Energy Storage ergy Storage Requirements in Hybrid and Electure and Super Capacitor based, Hybridization of			_	•		
Introduction based, Fue	on to Enel Cell ba	ergy Storage Requirements in Hybrid and Electused, and Super Capacitor based, Hybridization of Drive Sizing and Energy Management Strate	f differ	ent ene	ergy sto	orage devic	es.	analysis - Battery
Introduction based, Fue UNIT Sizing the motor, siz Introduction	on to Energy C-V drive sying the point of energy control of the point of energy control of the Energy control	ergy Storage Requirements in Hybrid and Elecused, and Super Capacitor based, Hybridization or	f differ egies nternal gy stor	combu	ergy sto	engine (IC	es. E), Siz Mana	analysis - Battery 9 ing the propulsion gement Strategies:
Introduction based, Fue UNIT Sizing the motor, siz Introduction	on to Energy C-V drive sying the point of energy control of the point of energy control of the Energy control	ergy Storage Requirements in Hybrid and Electronical Action of the Sizing and Energy Management Strate system: Matching the electric machine and the income electronics, selection of appropriate energy management strategies used in hybrid and electric machine and the income ergy management strategies used in hybrid and electric machine and the income ergy management strategies used in hybrid and electric machine and the income action of appropriate energy management strategies used in hybrid and electric machine and the income action of appropriate energy management strategies used in hybrid and electric machine and the income action of appropriate energy management strategies used in hybrid and electric machine action of appropriate energy management strategies used in hybrid and electric machine action of appropriate energy management strategies used in hybrid and electric machine action of appropriate energy management strategies used in hybrid and electronic machine action of appropriate energy management strategies used in hybrid and electronic machine action of appropriate energy management strategies used in hybrid and electronic machine action of appropriate energy management strategies used in hybrid and electronic machine action of appropriate energy management strategies used in hybrid and electronic machine action of appropriate energy management strategies used in hybrid and electronic machine action of appropriate energy management strategies used in hybrid and electronic machine action of appropriate energy machine action of	f differ egies nternal gy stor	combu	ergy sto	engine (IC	E), Siz Mana and cor	analysis - Battery 9 ing the propulsion gement Strategies:
Introduction based, Fue UNIT Sizing the motor, siz Introduction management of the Unit of	on to En ball Cell ball ce	ergy Storage Requirements in Hybrid and Electronical Action of the Sizing and Energy Management Strate system: Matching the electric machine and the income electronics, selection of appropriate energy management strategies used in hybrid and electric machine and the income ergy management strategies used in hybrid and electric machine and the income ergy management strategies used in hybrid and electric machine and the income action of appropriate energy management strategies used in hybrid and electric machine and the income action of appropriate energy management strategies used in hybrid and electric machine and the income action of appropriate energy management strategies used in hybrid and electric machine action of appropriate energy management strategies used in hybrid and electric machine action of appropriate energy management strategies used in hybrid and electric machine action of appropriate energy management strategies used in hybrid and electronic machine action of appropriate energy management strategies used in hybrid and electronic machine action of appropriate energy management strategies used in hybrid and electronic machine action of appropriate energy management strategies used in hybrid and electronic machine action of appropriate energy management strategies used in hybrid and electronic machine action of appropriate energy management strategies used in hybrid and electronic machine action of appropriate energy management strategies used in hybrid and electronic machine action of appropriate energy machine action of	f differ egies nternal gy stori lectric Il be al rivetra ctric d es for e	comburage tecevehicle ble to: ins requirive tra lectric or a hy	uiremeins in vehicl	engine (IC gy, Energy sification, a ent for a vea a vehicle es. electric ve	E), Siz Mana and cor hicle	analysis - Battery 9 ing the propulsion gement Strategies: nparison of energy
Introduction based, Fue UNIT Sizing the motor, siz Introduction management of the Unit of the International Court of the Internat	on to En ball Cell ball ce	ergy Storage Requirements in Hybrid and Electric ased, and Super Capacitor based, Hybridization of Drive Sizing and Energy Management Strate system: Matching the electric machine and the incover electronics, selection of appropriate energy management strategies used in hybrid and elegies, Implementation issues. Upon completion of this course, the Learners will Discuss Characterise and configure hybrid delegies and apply appropriate hybrid and elegies Design and install suitable AC and DC drives Discuss arrive at a suitable energy storage synapply energy management strategies to ensure the property of the property	egies nternal gy stor lectric Il be al rivetra ctric d es for e ystem f are bett	comburage tecevehicle ble to: ins require tra lectric for a hy ter econ	uireme ins in vehicle brid / nomy a	engine (IC gy, Energy sification, a rotal house a vehicle es. electric vehicle end efficient efficient efficient efficient efficient efficient end end efficient end efficient end efficient end efficient end	E), Size Mana and corurs hicle	analysis - Battery 9 ing the propulsion gement Strategies: nparison of energy
Introduction based, Fue UNIT Sizing the motor, siz Introduction management of the Unit of the motor of the mo	on to En ball Cell ball ce	ergy Storage Requirements in Hybrid and Elected and Super Capacitor based, Hybridization of Drive Sizing and Energy Management Strate system: Matching the electric machine and the interpower electronics, selection of appropriate energy management strategies used in hybrid and elegies, Implementation issues. Upon completion of this course, the Learners will be Discuss Characterise and configure hybrid delegies and apply appropriate hybrid and elegies Design and install suitable AC and DC drive Discuss arrive at a suitable energy storage syllar Apply energy management strategies to ensure as Discuss arrive and Hybrid Vehicles: Design Functions and Hybrid Vehicles: Design Functions and State Sta	f differ egies nternal gy stor lectric Il be al rivetra ctric d es for e ystem f are bett ndame	comburage tecevehicle ble to: ins require tra lectric for a hyter econ	uiremedins in vehicle brid / homy a	engine (IC gy, Energy sification, a Total horest for a very a vehicle es. electric very and efficient Edition, 202	E), Size Mana and corurs hicle	analysis - Battery 9 ing the propulsion gement Strategies nparison of energy
Introduction based, Fued UNIT Sizing the motor, siz Introduction management of the size of	con to En tel Cell back of C-V drive sy ing the point of energy on to energy on the strate of Cell (S). COOK: Iqbal Hu James La	ergy Storage Requirements in Hybrid and Elected and Super Capacitor based, Hybridization of Drive Sizing and Energy Management Strate system: Matching the electric machine and the incover electronics, selection of appropriate energy management strategies used in hybrid and elegies, Implementation issues. Upon completion of this course, the Learners with Discuss Characterise and configure hybrid defined and apply appropriate hybrid and elegies and install suitable AC and DC drives. Discuss arrive at a suitable energy storage system Apply energy management strategies to ensure as a suitable and Design Full arminie, John Lowry, Electric Vehicle Technological arminie armin	f differ egies nternal gy stor lectric Il be al rivetra ctric d es for e ystem f are bett ndame	comburage tecevehicle ble to: ins require tra lectric for a hyter econ	uiremedins in vehicle brid / homy a	engine (IC gy, Energy sification, a Total horest for a very a vehicle es. electric very and efficient Edition, 202	E), Size Mana and corurs hicle	analysis - Battery 9 ing the propulsior gement Strategies in parison of energy
Introduction based, Fued UNIT Sizing the motor, siz Introduction management of the size of	on to En el Cell ba C-V drive sy ing the pon to ene ent strate C(s) OOK: Iqbal Hu James La ENCES:	ergy Storage Requirements in Hybrid and Elected and Super Capacitor based, Hybridization of Drive Sizing and Energy Management Strate system: Matching the electric machine and the incover electronics, selection of appropriate energy management strategies used in hybrid and elegies, Implementation issues. Upon completion of this course, the Learners with Discuss Characterise and configure hybrid defended apply appropriate hybrid and elegies and install suitable AC and DC drive Discuss arrive at a suitable energy storage system. Apply energy management strategies to ensure as Apply energy management strategies to ensure arminie, John Lowry, Electric Vehicle Technologies. It Ehsani, Yimi Gao, Sebastian E. Gay, Ali English Electric Vehicle Technologies.	f differ egies nternal gy stor lectric Il be al rivetra ctric d es for e eystem f ure bett ndame gy Exp	comburage tecevehicle ble to: ins requirive tra lectric for a hyter econ ntals#,	uiremeins in vehicle brid / homy a	engine (IC gy, Energy sification, a rotal house the for a very a vehicle es. electric very electric	E), Siz Mana and corurs hicle	analysis - Battery 9 ing the propulsior gement Strategies: nparison of energy 45
Introduction based, Fued UNIT Sizing the motor, siz Introduction management of the size of	con to En to El Cell back of Ce	ergy Storage Requirements in Hybrid and Elected and Super Capacitor based, Hybridization of the second seed, and Super Capacitor based, Hybridization of the second seed and Energy Management Strates and the interpretation of the second seed in hybrid and elegies, Implementation issues. Upon completion of this course, the Learners with Discuss Characterise and configure hybrid defined and apply appropriate hybrid and elegies and install suitable AC and DC drivers. Discuss arrive at a suitable energy storage synthesis and the second seed and the second seed armining the second seed and Hybrid Vehicles: Design Functional Seed armining the second seed armining the second seed and Hybrid Vehicles: Design Functions armining the second seed and Hybrid Vehicles: Design Functions armining the second seed and the second seed armining the second seed and the second seed armining the second seed and the second seed armining the second second seed armining the second second second seed armining the second seco	f differegies nternal gy storilectric Il be al rivetra cetric des for e ystem f nre bett madi, 1 2004.	comburage tecevehicles ble to: ins require trace lectric for a hyter econ ntals, fained, Modern	uiremeins in vehicle brid / homy a	engine (IC gy, Energy sification, a rotal house of the ent for a very a vehicle es. electric very el	E), Size Mana corrurs hicle	analysis - Battery 9 ing the propulsior gement Strategies nparison of energy 45

CO'S	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	2	1	2	1	-	2	2	-	-	-	3	3	3
CO2	3	3	3	2	3	2	-	2	3	-	-	-	3	3	3
CO3	3	2	3	2	3	2	-	3	3	-	-	-	3	3	3
CO4	3	3	2	1	2	2	-	2	3	-	-	-	3	3	3
CO5	3	3	3	2	3	2	-	3	3	-	-	-	3	3	3

Cours	se code	e Course Name Hours/week Credit M					Maximum marks	
24MF	E15601	Industrial Robotics	L	T	P	С	100	
24 1V112	213001	industrial Robotics	3	0	0	3	100	
Objectiv	ve(s)	 Mention the need and knowledge of Describe the importance's of kinema Identify the select the suitable type of Discuss the importance of machine v 	tics and f grippir ision and	dynam ng mech d the v	ics in re hanism arious t	obotic and driving ypes of sen		
TIN	IT-I	• Identify the various application of rol Introduction	ootics an	id robo	t econo	mics	9	
		ad scope of industrial robots- Coordinate Syste	me Clas	sificati	on of F	Pohot- Roh		
		tomation & robotics, Future Prospects, Machi						
		& Inspectors, comparison of Electric, Hydraul					8 ·F	
	IT-II	Robot Kinematics					9	
End Effe	ecters - ty	rpes, Mechanical & other grippers, Tool as en	nd effect	ter Co	ordinate	Frames, I	Rotations, Homogeneou	
		y, Yaw, Roll, Joint Notations, Speed of Motion CV, Inverse Kinematics of Planer Robot, Four A	•			quation of	Planer Robot, Four axis	
UNI	T-III	Robot Drives and Control					9	
drives -	Linear a	bot motion – Position and velocity sensing dev nd rotary actuators and control valves – D.	C. Serve	_		•	•	
	_	effectors – Vacuum, magnetic and air operated g	grippers					
UNI' Introduct	T-IV tion, Low	Machine Vision and control & sensors level & High level vision, Sensing & Digitize	zing, Im					
UNI' Introduct detection Segregati Sensor, I	T-IV tion, Low n, Object tion. Poka LVDT, Re	Machine Vision and control & sensors level & High level vision, Sensing & Digitic description recognition, Interpretation, N yoke., Principles and Applications of the followsolvers, Optical Encoders, pneumatic Position	zing, Im oises ir lowing t	Imag	ge, App sensor	olication of s-Position	sis, Segmentation, Edge f imaging for Productions sensors - Piezo Electric	
UNI' Introduct detection Segregati Sensor, I UNI	T-IV tion, Low n, Object tion. Poka LVDT, Re IT-V	Machine Vision and control & sensors level & High level vision, Sensing & Digitic description & recognition, Interpretation, N yoke., Principles and Applications of the followsolvers, Optical Encoders, pneumatic Position & Implementation and Robot Economics	zing, Im oises ir lowing ty Sensors,	n Imag ypes of Range	se, App Sensor Sensor	plication of rs- Position s	sis, Segmentation, Edge f imaging for Produc sensors - Piezo Electric	
UNI' Introduct detection Segregati Sensor, I UNI Impleme	T-IV tion, Low n, Object tion. Poka LVDT, Re IT-V entation of	Machine Vision and control & sensors level & High level vision, Sensing & Digitic description recognition, Interpretation, N yoke., Principles and Applications of the follosolvers, Optical Encoders, pneumatic Position Implementation and Robot Economics Robots in Industries –Safety Considerations for	zing, Im oises ir lowing ty Sensors,	n Imag ypes of Range	se, App Sensor Sensor	plication of rs- Position s	sis, Segmentation, Edge f imaging for Produc sensors - Piezo Electric	
UNI' Introduct detection Segregati Sensor, I UNI Impleme	T-IV tion, Low n, Object tion. Poka LVDT, Re IT-V entation of	Machine Vision and control & sensors level & High level vision, Sensing & Digitic description & recognition, Interpretation, N yoke., Principles and Applications of the followsolvers, Optical Encoders, pneumatic Position & Implementation and Robot Economics	zing, Im oises ir lowing ty Sensors,	n Imag ypes of Range	se, App Sensor Sensor tions; I	plication of rs- Position s	sis, Segmentation, Edge f imaging for Product sensors - Piezo Electric 9 Analysis of Robots - Pay	
UNI' Introduct detection Segregati Sensor, I UNI Impleme	T-IV tion, Low n, Object ion. Poka LVDT, Re IT-V entation of thod, EUA	Machine Vision and control & sensors level & High level vision, Sensing & Digitic description recognition, Interpretation, N yoke., Principles and Applications of the follosolvers, Optical Encoders, pneumatic Position Implementation and Robot Economics Robots in Industries – Safety Considerations for AC Method, Rate of Return Method. Upon completion of this course, the Learners of Interpret the various degrees of freedom	zing, Im oises ir lowing ty Sensors, or Robot will be a	n Imagypes of Range t Operation of the control of	e, App Sensor Sensor tions; I	Dication of Services Position of Seconomic A	sis, Segmentation, Edge f imaging for Product sensors - Piezo Electric 9 Analysis of Robots - Payors 45	
UNI' Introduct detection Segregati Sensor, I UNI Impleme back Met	tion, Lown, Object ion. Poka LVDT, Restation of thod, EUA	Machine Vision and control & sensors level & High level vision, Sensing & Digitic description & recognition, Interpretation, N yoke., Principles and Applications of the follosolvers, Optical Encoders, pneumatic Position & Implementation and Robot Economics Robots in Industries – Safety Considerations for C Method, Rate of Return Method. Upon completion of this course, the Learners of Interpret the various degrees of freedom • Design appropriate end effectors for various configurations	zing, Im oises ir lowing ty Sensors, or Robot will be a n of mot s applicat	n Imagypes of Range t Operation of rations an	se, App sensor Sensor tions; I	Economic A Total hou	sis, Segmentation, Edge f imaging for Product sensors - Piezo Electric 9 Analysis of Robots - Payors 45	
UNI' Introduct detection Segregati Sensor, I UNI Impleme back Met	tion, Lown, Object ion. Poka LVDT, Restation of thod, EUA	Machine Vision and control & sensors level & High level vision, Sensing & Digitic description recognition, Interpretation, N yoke., Principles and Applications of the followsolvers, Optical Encoders, pneumatic Position Implementation and Robot Economics Robots in Industries – Safety Considerations for Completion of this course, the Learners of the Interpret the various degrees of freedom Interpret the various degrees of freedom Design appropriate end effectors for various configurations Select the suitable sensors and drive for readers.	zing, Im oises ir lowing t Sensors, or Robot will be a n of mot s applicat	n Imagypes of Range t Opera ble to: ion of itions an	se, App sensor Sensor tions; I	Economic A Total hou	sis, Segmentation, Edge f imaging for Product sensors - Piezo Electric 9 Analysis of Robots - Payors 45	
UNI' Introduct detection Segregati Sensor, I UNI Impleme back Met	tion, Lown, Object ion. Poka LVDT, Restation of thod, EUA	Machine Vision and control & sensors level & High level vision, Sensing & Digitic description & recognition, Interpretation, N yoke., Principles and Applications of the follosolvers, Optical Encoders, pneumatic Position & Implementation and Robot Economics Robots in Industries – Safety Considerations for AC Method, Rate of Return Method. Upon completion of this course, the Learners of the Interpret the various degrees of freedom Interpret the various degrees of freedom Design appropriate end effectors for various configurations Select the suitable sensors and drive for real compute required trajectory planning & drive for real computer required trajectory p	zing, Im oises ir lowing ty Sensors, or Robot will be a n of mot s applicat d time wo	n Imagypes of Range t Operated to Specific to Specifi	se, App sensor Sensor tions; I	Economic A Total hou	sis, Segmentation, Edge f imaging for Product sensors - Piezo Electric 9 Analysis of Robots - Pagers 45	
UNI' Introduct detection Segregati Sensor, I UNI Impleme	tion, Lown, Object ion. Poka LVDT, Restration of thod, EUA	Machine Vision and control & sensors level & High level vision, Sensing & Digitic description recognition, Interpretation, N yoke., Principles and Applications of the followsolvers, Optical Encoders, pneumatic Position Implementation and Robot Economics Robots in Industries – Safety Considerations for Completion of this course, the Learners of the Interpret the various degrees of freedom Interpret the various degrees of freedom Design appropriate end effectors for various configurations Select the suitable sensors and drive for readers.	zing, Im oises ir lowing ty Sensors, or Robot will be a n of mot s applicat d time wo	n Imagypes of Range t Operated to Specific to Specifi	se, App sensor Sensor tions; I	Economic A Total hou	sis, Segmentation, Edge f imaging for Product sensors - Piezo Electric 9 Analysis of Robots - Payors 45	
UNI' Introduct detection Segregati Sensor, I UNI Impleme back Met Outcom	tion, Lown, Object ion. Poka LVDT, Reservation of thod, EUA	Machine Vision and control & sensors level & High level vision, Sensing & Digitic description recognition, Interpretation, No yoke., Principles and Applications of the following solvers, Optical Encoders, pneumatic Position of Implementation and Robot Economics Robots in Industries – Safety Considerations for AC Method, Rate of Return Method. Upon completion of this course, the Learners of the Interpret the various degrees of freedom Design appropriate end effectors for various configurations Select the suitable sensors and drive for read Compute required trajectory planning & drive specify various types of Robots for industriance.	zing, Imoises ir lowing to Sensors, or Robotowill be a nof motos applicated time we lives for the land application of the land	t Operations an orking one giver ations	ee, App Sensor Sensor tions; I	Economic A Total house kinematics ootic arm.	sis, Segmentation, Edge f imaging for Product sensors - Piezo Electric 9 Analysis of Robots - Payors 45 s of various manipulator	
UNI' Introduct detection Segregati Sensor, I UNI Impleme back Met	tion, Lown, Object ion. Poka LVDT, Reserved in the transfer of tra	Machine Vision and control & sensors level & High level vision, Sensing & Digitic description & recognition, Interpretation, New yoke., Principles and Applications of the followsolvers, Optical Encoders, pneumatic Position & Implementation and Robot Economics Robots in Industries – Safety Considerations for AC Method, Rate of Return Method. Upon completion of this course, the Learners of the Interpret the various degrees of freedom of the Design appropriate end effectors for various configurations Select the suitable sensors and drive for read of the Compute required trajectory planning & drawn of the Specify various types of Robots for industrice. P.Groover, Mitchell Weis, Roger N.Nagel	zing, Im oises ir lowing ty Sensors, or Robot will be a n of mot s applicat litime wo ives for th ial applic	t Operations an orking one giver ations	ee, App Sensor Sensor tions; I	Economic A Total house kinematics ootic arm.	sis, Segmentation, Edge f imaging for Product sensors - Piezo Electric 9 Analysis of Robots - Payors 45 s of various manipulator	
UNI' Introduct detection Segregati Sensor, I UNI Impleme back Met	tion, Lown, Object ion. Poka LVDT, Re IT-V entation of thod, EUA mikell, Program D. Rich	Machine Vision and control & sensors level & High level vision, Sensing & Digitic description recognition, Interpretation, No yoke., Principles and Applications of the following solvers, Optical Encoders, pneumatic Position of Implementation and Robot Economics Robots in Industries – Safety Considerations for AC Method, Rate of Return Method. Upon completion of this course, the Learners of the Interpret the various degrees of freedom Design appropriate end effectors for various configurations Select the suitable sensors and drive for read Compute required trajectory planning & drive specify various types of Robots for industriance.	zing, Im oises ir lowing ty Sensors, or Robot will be a n of mot s applicat ditime wo ives for th ial applic	h Imagypes of Range t Opera ble to: ion of itions an orking of the given ations class Colors	se, App sensor Sensor tions; I robots d analyz f the rob	Economic A Total hou e kinematics ootic arm.	sis, Segmentation, Edge of imaging for Product sensors - Piezo Electric sensors - Piezo Electric sensors of Robots - Pay Trs	
UNI Introduct detection Segregati Sensor, I UNI Impleme back Met Outcom TEXT I	tion, Lown, Object ion. Poka LVDT, Re IT-V entation of thod, EUA entation of the IT-V entation of IT-V entation of the IT-V entation of IT-V entation entat	Machine Vision and control & sensors level & High level vision, Sensing & Digitic description & recognition, Interpretation, N yoke., Principles and Applications of the following solvers, Optical Encoders, pneumatic Position & Implementation and Robot Economics Robots in Industries —Safety Considerations for AC Method, Rate of Return Method. Upon completion of this course, the Learners of Interpret the various degrees of freedom Design appropriate end effectors for various configurations Select the suitable sensors and drive for read Compute required trajectory planning & drive of the Specify various types of Robots for industrical Computer (Mitchell Weis, Roger N.Nagel Laming and Applications", McGraw Hill, Int., 19 ard, Klafter, A. Thomas, Chmielewski and	zing, Imfoises ir lowing types. Sensors, or Robot will be a nof mot s applicate time woives for thial applic. Nicho 86 Michael	ble to: ion of rations an orking one giver ations Negir	se, App sensor Sensor tions; I robots d analyz f the rob task	Economic A Total hou e kinematics ootic arm.	sis, Segmentation, Edge f imaging for Product sensors - Piezo Electric 9 Analysis of Robots - Payors 45 s of various manipulator Robotics Technology	
UNI Introduct detection Segregati Sensor, I UNI Impleme back Met TEXT I 1 2	tion, Lown, Object ion. Poka LVDT, Restroy entation of thod, EUA Mikell, Program D. Rich Approacy	Machine Vision and control & sensors level & High level vision, Sensing & Digitic description & recognition, Interpretation, New yoke., Principles and Applications of the followsolvers, Optical Encoders, pneumatic Position & Implementation and Robot Economics Robots in Industries – Safety Considerations for AC Method, Rate of Return Method. Upon completion of this course, the Learners of the Interpret the various degrees of freedom of the Design appropriate end effectors for various configurations Select the suitable sensors and drive for read of the Compute required trajectory planning & drawn of the Specify various types of Robots for industrications. C. Groover, Mitchell Weis, Roger N. Nagel and Applications, McGraw Hill, Int., 19 and, Klafter, A. Thomas, Chmielewski and the Prentice Hall of India, New Delhi, 2001	zing, Im oises ir lowing ty Sensors, or Robot will be a n of mot s applicat litime wo ives for th ial applic , Nicho 86 Michael Book Co	ble to: ion of rations and orking one giver ations Negir	se, App sensor Sensor tions; I robots d analyz f the rob task	Economic A Total house kinematics ootic arm. 'Industrial otics Engin	sis, Segmentation, Edge f imaging for Product sensors - Piezo Electric 9 Analysis of Robots - Payors 45 s of various manipulator Robotics Technology	
UNI Introduct detection Segregati Sensor, I UNI Impleme back Met TEXT I 1 2 3 4	tion, Lown, Object ion. Poka LVDT, Restroy entation of thod, EUA Mikell, Program D. Rich Approacy	Machine Vision and control & sensors level & High level vision, Sensing & Digitic description recognition, Interpretation, Nyoke., Principles and Applications of the following solvers, Optical Encoders, pneumatic Position Implementation and Robot Economics Robots in Industries —Safety Considerations for Mc Method, Rate of Return Method. Upon completion of this course, the Learners of Interpret the various degrees of freedom Design appropriate end effectors for various configurations Select the suitable sensors and drive for read Compute required trajectory planning & dr. Specify various types of Robots for industrical Computer of India, New Delhi, 2001 Koren, "Robotics for Engineers", McGraw-Hill man.P.A., "Robotics and Image Processing", Temporary of the Samuel Computer of Samuel Computers of Samuel Compute	zing, Im oises ir lowing ty Sensors, or Robot will be a n of mot s applicat litime wo ives for th ial applic , Nicho 86 Michael Book Co	ble to: ion of rations and orking one giver ations Negir	se, App sensor Sensor tions; I robots d analyz f the rob task	Economic A Total house kinematics ootic arm. 'Industrial otics Engin	sis, Segmentation, Edge of imaging for Product sensors - Piezo Electric sensors - Piezo Electric sensors of Robots - Pay Trs	

2	Introduction to Robotics: Mechanica and Control, Craig, J. J., 2nd :J?:dition, Addison-Welsey, 1989
3	Fu.K.S. Gonzalz.R.C., and Lee C.S.G., "Robotics Control, Sensing, Vision and Intelligence", McGraw-Hill Book Co., 2008
4	Yoram Koren, "Robotics for Engineers", McGraw-Hill Book Co., 2001

co's	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	2	1	1	-	-	1	2	-	-	-	3	2	2
CO2	3	3	3	2	2	-	-	1	2	-	-	-	3	2	3
CO3	3	2	3	2	2	-	-	2	2	-	-	-	3	3	3
CO4	3	3	3	2	3	-	-	2	3	-	-	-	3	3	3
CO5	3	2	2	1	2	-	-	1	2	-	-	-	3	2	2

	Course Name	Н	ours/w	eek	Credit	Maximum marks		
248/15/22	Hydraulics and Pneumatics	L	T	P	C		00	
24ME15602	Systems	3	0	0	3	J	100	
	 To understand the basics of hydraulic To study the hydraulic pumps and co 	•			· ·			
Objective(s)	 To understand the utilization of cy electronic control components. To understand the fluid power circuit 		accum	ulators	valves and	d variouselec	trical and	
	To study the fluid power condition r	nonitori	ng, mai	ntenan	ce and troub	leshooting.		
UNIT-I	Introduction to fluid power						9	
•	eumatics, Pascal's Law, Bernoulli's endard hydraulic fluids, Basic principles ats.	•						
UNIT-II	Fluid Power drives						9	
	upply-Types, construction and selection onstruction and selection of Compressor nover.							
UNIT-III	Fluid Power Control Components						9	
	direction and flow control valves, propertuators-Linear and rotary.	ortional	l and	servo	valves, Acc	umulators, F	ilter Regulato	
UNIT-IV	Basic Fluid Power Circuits ,Electronic	and E	lectric	al Cont	role		9	
Fail safe circuits, R Counter balance circulars, proximity se	egenerative circuits, Meter in and Meter ocuit, Multi cylinder sequencing circuits, Elnsors, Programmable Logic Controllers, La	out circu lectro pr adder di	its, Ac neumati agram,	cumula c & El Timers	tor circuits, ectro hydra and Count	ulic compone ers.	ensifier circuit ents- solenoids	
Fail safe circuits, R Counter balance circulars, proximity se	cuit, Multi cylinder sequencing circuits, El	out circu lectro pr adder di	its, Ac neumati agram,	cumula c & El Timers	tor circuits, ectro hydra and Count	ulic compone ers.	ensifier circui	
Fail safe circuits, R Counter balance circulars, proximity se UNIT-V Travel step diagran	cuit, Multi cylinder sequencing circuits, Elasors, Programmable Logic Controllers, La Fluid Power Circuit Design, Application	out circu lectro pradder di ons ,ma method,	nits, Ac neumati agram, intenai	cumula ic & El Timers nce and	tor circuits, ectro hydra and Count I troublesh Packaging	ulic componeers. ooting Industry, M	ensifier circuit ents- solenoids 9 aterial handlin	
Fail safe circuits, R Counter balance circulars, proximity se UNIT-V Travel step diagran	ruit, Multi cylinder sequencing circuits, El nsors, Programmable Logic Controllers, La Fluid Power Circuit Design, Application of fluid power systems n, cascade and Karnaugh – Veitch map	out circu lectro pradder di ons ,ma method,	nits, Ac neumati agram, intenai	cumula ic & El Timers nce and	tor circuits, ectro hydra and Count I troublesh Packaging ing of fluid	ulic componeers. ooting Industry, M	ensifier circuit ents- solenoids 9 aterial handlin	
Fail safe circuits, R Counter balance circulars, proximity se UNIT-V Travel step diagran	ruit, Multi cylinder sequencing circuits, El nsors, Programmable Logic Controllers, La Fluid Power Circuit Design, Application of fluid power systems n, cascade and Karnaugh – Veitch map	but circulectro pradder di ons ,ma method, onitoring	nits, Ac neumati agram, intenar Bottling, troub	cumula ic & El Timers nce and ng and leshoo	tor circuits, ectro hydra and Count I troublesh Packaging ing of fluid Tota	ulic compone ers. ooting Industry, M	ensifier circuints- solenoids 9 aterial handlin	
Fail safe circuits, R Counter balance circulars, proximity se UNIT-V Travel step diagran	cuit, Multi cylinder sequencing circuits, Elasors, Programmable Logic Controllers, La Fluid Power Circuit Design, Application of fluid power systems a, cascade and Karnaugh – Veitch map reations and maintenance and condition more sequences. Upon successful completion of the coupse of the sequences.	but circulectro pradder di ons ,ma method, onitoring urse the omponer	nits, Ac neumati agram, intenar Bottlii g, troub	cumula ic & El Timers nce and ng and leshoot	tor circuits, ectro hydra and Count I troublesh Packaging ing of fluid Tota	ulic compone ers. ooting Industry, M	ensifier circuints- solenoids 9 aterial handlin	
Fail safe circuits, R Counter balance circuits, proximity se UNIT-V Travel step diagran and assembly applice	Cuit, Multi cylinder sequencing circuits, El nsors, Programmable Logic Controllers, La Fluid Power Circuit Design, Application of fluid power systems a, cascade and Karnaugh – Veitch map reations and maintenance and condition more second of the country of the	but circulectro produced on section on section of fluoring on the component of fluoring of fluoring on the component of fluoring of fluoring on the component of fluoring of fl	nits, Ac neumati agram, intenar Bottlii g, troub student nts	cumula ic & El Timers nce and ng and leshood	tor circuits, ectro hydra and Count I troublesh Packaging ing of fluid Tota e able to	ulic componeers. poting Industry, M powersyster I hours 45	ensifier circui ents- solenoide 9 aterial handlir	
Fail safe circuits, R Counter balance circulars, proximity se UNIT-V Travel step diagran	Cuit, Multi cylinder sequencing circuits, Elmsors, Programmable Logic Controllers, Lansors, Lans	method, onitoring arse the omponer of flusystem f	agram, intenal Bottli g, troub student ats aid pow for vari	cumulate & El Timers nce and ng and leshoot s will b	tor circuits, ectro hydra and Count I troublesh Packaging ing of fluid Tota e able to	ulic componeers. poting Industry, M powersyster I hours 45	ensifier circui ents- solenoid 9 aterial handlir	
Fail safe circuits, R Counter balance circuits, proximity se UNIT-V Travel step diagran and assembly applic	Cuit, Multi cylinder sequencing circuits, El nsors, Programmable Logic Controllers, La Fluid Power Circuit Design, Application of fluid power systems a, cascade and Karnaugh – Veitch map reations and maintenance and condition more electrons. Upon successful completion of the country of the country of the country of the country of the function and operation of the function and operation of the country of th	method, onitoring on of flu system factoring	its, Acheumatiagram, intenar Bottliig, troub student ats aid pow for vari tuation	cumulatic & El Timers nce and ng and leshoods will be er system ous pur circuits	tor circuits, ectro hydra and Count I troublesh Packaging ing of fluid Tota e able to	ulic components. poting Industry, M powersyster I hours 45 ustry.	ensifier circuints- solenoid 9 aterial handlings.	
Fail safe circuits, R Counter balance circuits, proximity se UNIT-V Travel step diagran and assembly application Outcome(s)	Cuit, Multi cylinder sequencing circuits, Elmsors, Programmable Logic Controllers, Lansors, Lans	method, onitoring on of flu system factoring	its, Acheumatiagram, intenar Bottliig, troub student ats aid pow for vari tuation	cumulatic & El Timers nce and ng and leshoods will be er system ous pur circuits	tor circuits, ectro hydra and Count I troublesh Packaging ing of fluid Tota e able to	ulic components. poting Industry, M powersyster I hours 45 ustry.	ensifier circui ents- solenoid 9 aterial handlinns.	
Fail safe circuits, R Counter balance circuits, proximity se UNIT-V Travel step diagram and assembly application Outcome(s)	Cuit, Multi cylinder sequencing circuits, Elasors, Programmable Logic Controllers, Lasors, Programmable Logic Controllers, Las	method, onitoring one of flusystem familia acronents a	nits, Acheumatiagram, intenal Bottlii g, troub student ats aid pow for vari tuation and acc	cumulatic & El Timers nce and ng and leshoods will be er system ous pur circuits essorie	tor circuits, ectro hydra and Count I troublesh Packaging ing of fluid Tota e able to ems poses in income sused in fluid	ulic components. poting Industry, M powersyster I hours 45 ustry.	ensifier circui ents- solenoid 9 aterial handlinns.	
Fail safe circuits, R Counter balance circuits, proximity se UNIT-V Travel step diagram and assembly application Outcome(s) TEXT BOOK: 1 Anthony	Cuit, Multi cylinder sequencing circuits, Elmsors, Programmable Logic Controllers, Lansors, Lansors, Programmable Logic Controllers, Lansors, Lansors, Programmable Logic Controllers, Lansors,	method, onitoring multi according to the multiple to the	agram, intenar Bottli g, troub student nts nid pow for vari tuation and accumational	cumulate & El Timers nce and ng and leshoot s will be er system ous pur circuits essorie edition	tor circuits, ectro hydra and Count I troublesh Packaging ing of fluid Tota e able to ems poses in income s used in fluid, 2013.	ulic components. poting Industry, Management of the powersystem I hours 45 ustry. uid powersys	ensifier circui ents- solenoide 9 aterial handlinas.	
Fail safe circuits, R Counter balance circuits, proximity se UNIT-V Travel step diagran and assembly application Outcome(s) TEXT BOOK: 1 Anthony 2 James R.I.	Cuit, Multi cylinder sequencing circuits, Elasors, Programmable Logic Controllers, Lasors, Programmable Logic Controllers, Las	method, onitoring multi according to the multiple to the	agram, intenar Bottli g, troub student nts nid pow for vari tuation and accumational	cumulate & El Timers nce and ng and leshoot s will be er system ous pur circuits essorie edition	tor circuits, ectro hydra and Count I troublesh Packaging ing of fluid Tota e able to ems poses in income s used in fluid, 2013.	ulic components. poting Industry, Management of the powersystem I hours 45 ustry. uid powersys	ensifier circuints- solenoid 9 aterial handlinns.	
Fail safe circuits, R Counter balance circuits, proximity se UNIT-V Travel step diagram and assembly application Outcome(s) TEXT BOOK: 1 Anthony	Cuit, Multi cylinder sequencing circuits, Elmsors, Programmable Logic Controllers, Lansors, Lansors, Programmable Logic Controllers, Lansors, Lansors, Programmable Logic Controllers, Lansors,	method, onitoring multi according to the multiple to the	agram, intenar Bottli g, troub student nts nid pow for vari tuation and accumational	cumulate & El Timers nce and ng and leshoot s will be er system ous pur circuits essorie edition	tor circuits, ectro hydra and Count I troublesh Packaging ing of fluid Tota e able to ems poses in income s used in fluid, 2013.	ulic components. poting Industry, Management of the powersystem I hours 45 ustry. uid powersys	ensifier circui ents- solenoids 9 aterial handlinas.	
Fail safe circuits, R Counter balance circuits, proximity se UNIT-V Travel step diagran and assembly application Outcome(s) TEXT BOOK: 1 Anthony 2 James R.I REFERENCES:	Cuit, Multi cylinder sequencing circuits, Elmsors, Programmable Logic Controllers, Lansors, Lansors, Programmable Logic Controllers, Lansors, Lansors, Programmable Logic Controllers, Lansors,	method, onitoring multi acronents a conents a conents a conents a conent on The	agram, intenal Bottli g, troub student aid pow for vari tuation and acc	cumula ic & El Timers nce and ng and leshoot s will b er syste ous pur circuits essorie edition	tor circuits, ectro hydra and Count I troublesh Packaging ing of fluid Tota e able to ems poses in ind s used in fluid in, 2013.	ulic componeers. poting Industry, M. powersyster I hours 45 ustry. uid powersys pany, Inc., 20	ensifier circuisnts- solenoids 9 aterial handlinns.	

3	Festo, Basic Pneumatic, Electro pneumatic, Hydraulic text and work books, 2015.
4	John Pippenger, Fluid Power Controls, Literary Licensing LLC, 2012.

CO'S	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	2	1	2	-	-	-	1	-	-	2	3	3	2
CO2	3	2	2	1	2	-	-	-	1	-	-	2	3	2	2
CO3	3	3	3	2	3	-	-	-	2	-	-	2	3	3	3
CO4	3	3	3	2	3	-	-	-	2	-	-	2	3	3	3
CO5	3	2	2	2	3	-	-	-	2	-	-	2	3	2	2

Course cod	e Course Name	Ho	ours/w	eek	Credit	Maximum marks
24ME1560	2 Canada and Instrumentation	L	T	P	С	100
24ME1560	3 Sensors and Instrumentation	3	0	0	3	100
Objective(s)	 To understand the concepts of measuremen To understand the various sensors used to n To study the fundamentals of signal condit in mechatronics system development To study the optical, pressure and temperate To understand the signal conditioning and I 	neasure vioning, d	various lata acc		•	
UNIT-I	Introduction					9
	surement – Classification of errors – Error analy leasures of sensors – Classification of sensors – Sen			•		
UNIT-II	Motion, Proximity and Ranging Sensors					9
Synchro - Mi	rs – Potentiometers, Resolver, Encoders – Optic crosyn, Accelerometer – GPS, Bluetooth, Range Range Sensor (LIDAR).					
UNIT-III	Force, Magnetic and Heading Sensors					9
	oad Cell, Magnetic Sensors –types, principle, requ Heading Sensors – Compass, Gyroscope, Inclinom		and adv	vantage	s: Magneto	resistive – Hall Effect –
Current sensor	Treating Sensors – Compass, Gyroscope, memori	ieters.				
UNIT-IV	Optical, Pressure and Temperature Sensor	:s				9
UNIT-IV Photo conduct Piezoelectric - measurement,	Optical, Pressure and Temperature Sensorive cell, photo voltaic, Photo resistive, LDR – Tactile sensors, Temperature – IC, Thermistor, Radiation Sensors - Smart Sensors - Film sensor, Management of the control of the	Fiber o	hermod	ouple.	Acoustic S	 Diaphragm, Bellows, bensors – flow and level ensors
Photo conductory Piezoelectric measurement, UNIT-V Amplification	Optical, Pressure and Temperature Sensorive cell, photo voltaic, Photo resistive, LDR – Tactile sensors, Temperature – IC, Thermistor,	Fiber of RTD, TIEMS & uisition:	hermoc Nano S	channacturin	Acoustic S s, LASER s el and mult g, Environr	Diaphragm, Bellows, bensors – flow and level ensors 9 ichannel data acquisition mental monitoring.
Photo conductory Piezoelectric measurement, UNIT-V Amplification	Optical, Pressure and Temperature Sensor ive cell, photo voltaic, Photo resistive, LDR – Tactile sensors, Temperature – IC, Thermistor, Radiation Sensors - Smart Sensors - Film sensor, M Signal Conditioning And DAQ Systems – Filtering – Sample and Hold circuits – Data Acq - applications - Automobile, Aerospace, Home app	Fiber of RTD, TIEMS & uisition: bliances,	Nano S Single Manuf	Sensors channacturin	Acoustic S s, LASER s	Diaphragm, Bellows, bensors – flow and level ensors 9 ichannel data acquisition mental monitoring.
Photo conductory Piezoelectric measurement, UNIT-V Amplification	Optical, Pressure and Temperature Sensor ive cell, photo voltaic, Photo resistive, LDR – Tactile sensors, Temperature – IC, Thermistor, Radiation Sensors - Smart Sensors - Film sensor, M Signal Conditioning And DAQ Systems - Filtering – Sample and Hold circuits – Data Acq	Fiber of RTD, Translation: bliances, will be a signal transduce in various application.	Single Manuf ble to: ypes for cics of ers. us apploons.	channa channa acturin or senso force,	Acoustic S s, LASER s el and mult g, Environi Total hou ors. magnetic,	- Diaphragm, Bellows, bensors – flow and level ensors 9 ichannel data acquisition mental monitoring. rs 45 heading, pressure and
Photo conductory Piezoelectric - measurement, UNIT-V Amplification - Data logging	Optical, Pressure and Temperature Sensor ive cell, photo voltaic, Photo resistive, LDR – Tactile sensors, Temperature – IC, Thermistor, Radiation Sensors - Smart Sensors - Film sensor, M Signal Conditioning And DAQ Systems - Filtering – Sample and Hold circuits – Data Acq - applications - Automobile, Aerospace, Home app Upon completion of this course, the Learners M • Explain various calibration techniques and • Describe the working principle and chatemperature, smart and other sensors and transducers • Apply the various sensors and transducers • Select the appropriate sensor for different and objects of the course, the Learners of the	Fiber of RTD, Translation: bliances, will be a signal transduce in various application.	Single Manuf ble to: ypes for cics of ers. us apploons.	channa channa acturin or senso force,	Acoustic S s, LASER s el and mult g, Environi Total hou ors. magnetic,	- Diaphragm, Bellows, bensors – flow and level ensors 9 ichannel data acquisition mental monitoring. rs 45 heading, pressure and
Photo conductory Piezoelectric - measurement, UNIT-V Amplification - Data logging Outcome(s) TEXT BOO	Optical, Pressure and Temperature Sensor ive cell, photo voltaic, Photo resistive, LDR – Tactile sensors, Temperature – IC, Thermistor, Radiation Sensors - Smart Sensors - Film sensor, M Signal Conditioning And DAQ Systems - Filtering – Sample and Hold circuits – Data Acq - applications - Automobile, Aerospace, Home app Upon completion of this course, the Learners M • Explain various calibration techniques and • Describe the working principle and chatemperature, smart and other sensors and transducers • Apply the various sensors and transducers • Select the appropriate sensor for different and objects of the course, the Learners of the	Fiber of RTD, To RTD,	Single Manuf ble to: ypes foics of ers. us appl ons. sors usi	channacturing r sensor force, ication	Acoustic S s, LASER s el and mult g, Environ Total hou ors. magnetic, s a acquisitio	- Diaphragm, Bellows, bensors - flow and level ensors 9 ichannel data acquisitionmental monitoring. rs 45 heading, pressure and on systems.
Photo conductive Piezoelectric - measurement, UNIT-V Amplification - Data logging Outcome(s) TEXT BOO 1 Erne 2 Saw	Optical, Pressure and Temperature Sensor ive cell, photo voltaic, Photo resistive, LDR – Tactile sensors, Temperature – IC, Thermistor, Radiation Sensors - Smart Sensors - Film sensor, M Signal Conditioning And DAQ Systems – Filtering – Sample and Hold circuits – Data Acq applications - Automobile, Aerospace, Home app Upon completion of this course, the Learners v Explain various calibration techniques and Describe the working principle and chatemperature, smart and other sensors and transducers Apply the various sensors and transducers Select the appropriate sensor for different and control of the signals from different sensors and transducers Discuss the Acquire the signals from different sensors and transducers	Fiber of RTD, Translation: Diances, will be a signal translation various application rent sensions and	Single Manuf ble to: ypes for ics of ers. us appl ons. fors usi	channa ch	Acoustic S s, LASER s el and mult g, Environ Total hou ors. magnetic, s a acquisitio	- Diaphragm, Bellows, bensors – flow and level ensors 9 ichannel data acquisition mental monitoring. rs 45 heading, pressure and on systems.
Photo conductive Piezoelectric - measurement, UNIT-V Amplification - Data logging Outcome(s) TEXT BOO 1 Erne 2 Saw Dha REFERENC	Optical, Pressure and Temperature Sensorive cell, photo voltaic, Photo resistive, LDR – Tactile sensors, Temperature – IC, Thermistor, Radiation Sensors - Smart Sensors - Film sensor, Madiation Sensors - Smart Sensors - Data Acquire - applications - Automobile, Aerospace, Home applications - Automobile, Aerospace, Home application of this course, the Learners of Explain various calibration techniques and the Describe the working principle and chartemperature, smart and other sensors and transducers of Select the appropriate sensor for different of Discuss the Acquire the signals from different sensor of Doebelin, "Measurement Systems – Application of Poebelin, "Accourse in Mediation New Delhi, 2013."	Fiber of RTD, Translation: Diances, will be a signal translation various application rent sensions and	Single Manuf ble to: ypes for ics of ers. us appl ons. fors usi	channa ch	Acoustic S s, LASER s el and mult g, Environ Total hou ors. magnetic, s a acquisitio	- Diaphragm, Bellows, bensors – flow and level ensors 9 ichannel data acquisition mental monitoring. rs 45 heading, pressure and on systems.
Photo conductive Piezoelectric - measurement,	Optical, Pressure and Temperature Sensorive cell, photo voltaic, Photo resistive, LDR – Tactile sensors, Temperature – IC, Thermistor, Radiation Sensors - Smart Sensors - Film sensor, Madiation Sensors - Smart Sensors - Data Acquire - applications - Automobile, Aerospace, Home applications - Automobile, Aerospace, Home application of this course, the Learners of Explain various calibration techniques and the Describe the working principle and chartemperature, smart and other sensors and transducers of Select the appropriate sensor for different of Discuss the Acquire the signals from different sensor of Doebelin, "Measurement Systems – Application of Poebelin, "Accourse in Mediation New Delhi, 2013."	Fiber of RTD, Translater in various applications and hanical lands.	Single Manuf ble to: ypes for cics of ers. us apploons. sors usi	channacturin or sensor force, ication ng Dat ", Tata ements	Acoustic S s, LASER s el and mult g, Environ Total hou ors. magnetic, s a acquisitio McGraw-H and Instru	- Diaphragm, Bellows, bensors – flow and level ensors 9 ichannel data acquisitionmental monitoring. rs 45 heading, pressure and on systems. fill, 2009. mentation and Control",
Photo conductive Piezoelectric - measurement, UNIT-V Amplification - Data logging Outcome(s) TEXT BOO 1 Erne 2 Saw Dha REFERENC 1 C. S	Optical, Pressure and Temperature Sensorive cell, photo voltaic, Photo resistive, LDR — Tactile sensors, Temperature — IC, Thermistor, Radiation Sensors - Smart Sensors - Film sensor, Madiation Sensors - Smart Sensors - Data Acquire - applications - Automobile, Aerospace, Home applications - Automobile, Aerospace, Home applications - Automobile, Aerospace, Home applications - Explain various calibration techniques and - Describe the working principle and chartemperature, smart and other sensors and transducers - Select the appropriate sensor for different - Discuss the Acquire the signals from different - Discuss the	Fiber of RTD, Translation: bliances, will be a signal translation application rent sensions and hanical differences.	Single Manuf ble to: ypes for sics of ers. us apploons. sors usi Design Measur rement,	channa ch	Acoustic S s, LASER s el and mult g, Environ Total hou ors. magnetic, s a acquisitio McGraw-H and Instru Viley & Son	- Diaphragm, Bellows, bensors – flow and level ensors 9 ichannel data acquisition mental monitoring. rs 45 heading, pressure and on systems. fill, 2009. mentation and Control",

CO'S	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	1	2	2	-	-	-	1	-	-	2	3	2	2
CO2	3	2	2	2	2	-	-	-	1	-	-	2	3	2	2
CO3	3	2	3	2	3	-	-	-	2	-	-	2	3	3	3
CO4	3	2	3	2	3	-	-	-	2	-	-	2	3	3	2
CO5	3	2	2	3	3	-	-	-	2	-	-	2	3	2	3

Course	e code	Course Name	Н	ours/w	eek	Credit	Maximum marks
24ME	15604	Embedded Systems and Programming	L	T	P	С	100
27 1V112	13004	Embedded Systems and Frogramming	3	0	0	3	100
Objectiv	ve(s)	 To study the architecture and fundamental un To study the microcontroller programming data exchange methods using various commu To design the interface circuit and programm To understand ARM processor architecture interface needs of growing mechatronic syste To understand real time embedded operating 	methonication ing of and ing and ing and ing ms.	dology on proto I/O dev ts func	and to ocols. vices, se tions to	ensors and a meet out	actuators. the computational and
UNI	IT-I	Introduction to Microcontroller	systen.	1101 44	rancea	system de	9
Fundame	ntals Fur	nctions of ALU - Microprocessor - Microcontrol ture - Features and Specifications - Memory Orga					
UNI	T-II	Programming and Communication					9
8051 Mid	crocontro	Assembly Language Programming – Instruction to bler – Basic Arithmetic and Logical Programming – Serial Communication, I ² C, SPI and CAN of 805 ller.	ng - T	Γimer a	ind Coi	inter - Inte	errupts - Interfacing and
UNI	Γ-III	Peripheral Interfacing					9
ADC and	DAC, S	 Interfacing of Memory, Key Board and Dispensors - Relays - Solenoid Valve and Heater - Stegramming of Servomotor - Traffic Light 	•	•			•
UNI	Γ-IV	ARM Processor					9
		7 Processor - Internal Architecture – Modes of State Registers – Pipelining – basic programming	•		_		Instruction Sets – ARM
UNI	T-V	Single Board Computers and Programming					9
•	ed Opera	Broadcom BCM2711 SoC – SBC architecture - Inting Systems - Real Time Programming Latterfacing			0 0		0
						Total hou	rs 45
Outcom	ne(s)	 Upon completion of this course, the Learners wie Explain the various functional units of microof features and specifications. Discuss the role of each functional units in mithe features and specifications. Discuss the Interface the sensors, actuators system on chip based interfacing Design the circuit and write the programming Develop the applications using Embedded systems. 	controlicroco and o	ller, pronter ther I/O	ocessor , proce D's wit	ssors and s	systemon- chip based on ntroller, processors and
TEXT E		Develop the applications using Embedded syst	em.				
1		Johid and Tany Civagia "Embadded Croter De-	~~" ^	011 W	ilov		
2		A hid and Tony Givagis, "Embedded System Desi				. , , ,,	2002
		n J. Aylala, "The 8051 Microcontroller, the Archit	ecture	and Pr	ogramn	ning Applic	cations", 2003
REFER	Muham	mad Ali Mazidi and Janice GillispicMazdi, "The on, 2006.	8051	Microco	ontrolle	r and Emb	edded Systems", Pearson

2	Simon Monk, Programming the Raspberry Pi, Second Edition: Getting Started with Python McGraw Hill TAB;
	2nd edition,2015
3	James W. Stewart, "The 8051 Microcontroller Hardware, Software and Interfacing", Regents Prentice Hall, 2003.
4	John B. Peatman, "Design with Microcontrollers", McGraw Hill International, USA, 2005.

co's	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	2	1	2	-	-	-	1	-	-	2	3	2	-
CO2	3	2	2	1	2	-	-	-	1	-	-	2	3	2	-
CO3	3	2	3	2	3	-	-	-	2	-	-	2	3	3	-
CO4	3	3	3	3	3	-	-	-	2	-	-	2	3	3	-
CO5	3	3	3	2	3	-	-	-	2	-	-	2	3	3	-

Course code	Course Name	k	Credit	Maximum marks		
243/15/05	Constant 1994 and 1 Total Process AVI 1914	C	100			
24ME15605	Smart Mobility and Intelligent Vehicles	3	0	0	3	100
Objective(s)	 To understand the various technologies and syste intelligent vehicles. To study the Radar Technology and Systems, Ul Technology and Systems and other sensors for au To study the Basic Control System Theory applie To study the various driving functions, connectin To understand the autonomous vehicle technolog 	trasonic itomobil ed to Au g the au	Sonar le vision tonomo	System n syster ous Auto	s, LIDAR S n. omobiles.	-
UNIT-I	Introduction to Automated, Connected, and Inte	•	Vehicle	06		9
	tomotive Electronics, Electronics Overview, History				inment Ro	
•	ctronics, Introduction to Automated, Connected, and					•
	Intelligent Vehicles		8			
UNIT-II	Sensor Technology for Smart Mobility					9
	r Technology and Systems, Ultrasonic Sonar Systems ight Vision Technology, Other Sensors, Use of Senso Systems					
UNIT-III	Connected Autonomous Vehicle					9
Laure Common D		Operai	10n of 1	ECUs, I	Basic Cybei	r-Physical Syster
Theory and Au Networks and A	ystem Theory applied to Automobiles, Overview of the atonomous Vehicles, Role of Surroundings Sensing autonomy Vehicle Wireless Technology & Networking					
Theory and Au Networks and A UNIT-IV Wireless System System Concep Computer Netw	attonomous Vehicles, Role of Surroundings Sensing autonomy	Systems mission nd Appl	Systen lication	Autono is – Mo s to V	my, Role of odulation/Enchicle Auto	9 ncoding, Received phonomy, Basics of
Theory and Au Networks and A UNIT-IV Wireless System System Concep Computer Netwand On-Board V	Autonomous Vehicles, Role of Surroundings Sensing Autonomy Vehicle Wireless Technology & Networking In Block Diagram and Overview of Components, Transports— Demodulation/Decoding, Wireless Networking and Vorking— the Internet of Things, Wireless Networking	mission nd Appl Fundam	Systen lication	Autono is – Mo s to V	my, Role of odulation/Enchicle Auto	9 ncoding, Received phonomy, Basics of
Theory and Au Networks and A UNIT-IV Wireless System Conceptor Network and On-Board VUNIT-V Connectivity F Vehicle-to-Road	Autonomous Vehicles, Role of Surroundings Sensing Autonomy Vehicle Wireless Technology & Networking In Block Diagram and Overview of Components, Transports—Demodulation/Decoding, Wireless Networking and Yorking—the Internet of Things, Wireless Networking Vehicle Networks Connected Car & Autonomous Vehicle Technology and Other Applications, Vehicle and Vehicle-to-Infrastructure Applications, Autonomous Autonomous Vehicles and Vehicle-to-Infrastructure Applications, Autonomous Vehicles and Vehicles	mission nd Appl Fundam ogy /ehicle-	Systen lication entals,	Autono as – Mo s to V Integra	odulation/Enterprise Autorion of Wir	9 ncoding, Received phonomy, Basics of reless Networkin 9 and Applications
Theory and Au Networks and A UNIT-IV Wireless System Conceptor Network and On-Board VUNIT-V Connectivity F Vehicle-to-Road	Autonomous Vehicles, Role of Surroundings Sensing Autonomy Vehicle Wireless Technology & Networking In Block Diagram and Overview of Components, Transports—Demodulation/Decoding, Wireless Networking are orking—the Internet of Things, Wireless Networking Vehicle Networks Connected Car & Autonomous Vehicle Technologundamentals, Navigation and Other Applications, Vehicles Navigation	mission nd Appl Fundam ogy /ehicle-	Systen lication entals,	Autono as – Mo s to V Integra	odulation/Enterprise Autorion of Wir	9 ncoding, Received onomy, Basics of reless Networkin 9 nd Applications Car Technology
Theory and Au Networks and A UNIT-IV Wireless System Conceptor Network and On-Board VUNIT-V Connectivity F Vehicle-to-Road	Autonomous Vehicles, Role of Surroundings Sensing Autonomy Vehicle Wireless Technology & Networking In Block Diagram and Overview of Components, Transports—Demodulation/Decoding, Wireless Networking and Yorking—the Internet of Things, Wireless Networking Of Pehicle Networks Connected Car & Autonomous Vehicle Technological and Vehicle-to-Infrastructure Applications, Autonomous Issues, Technical Issues, Security Issues Upon completion of this course, the Learners will be Explain the cyber-physical control systems and the autonomous vehicles Discuss the remote sensing and the types of sensor Discuss the fully autonomous vehicles Apply the basic concepts of wireless communication	mission nd Appl Fundam ogy Vehicle- conomou able to ir applic technolous	System lication nentals, to-Vehicles vehicles wireles	Autono ns – Mo s to Vo Integra cle Te icles - co collise eded to	odulation/Enchicle Autotion of Wirechnology a Driverless Total hour implement setworks	9 ncoding, Receive onomy, Basics of eless Networkin 9 and Applications Car Technology rs 45
Theory and Au Networks and A UNIT-IV Wireless System Conceptor Network and On-Board VUNIT-V Connectivity Founded to the Connectivity Foundard, Legal, R Outcome(s)	Autonomous Vehicles, Role of Surroundings Sensing Autonomy Vehicle Wireless Technology & Networking In Block Diagram and Overview of Components, Transports—Demodulation/Decoding, Wireless Networking and Orking—the Internet of Things, Wireless Networking of Pehicle Networks Connected Car & Autonomous Vehicle Technological and Vehicle-to-Infrastructure Applications, Autoadblock Issues, Technical Issues, Security Issues Upon completion of this course, the Learners will be Explain the cyber-physical control systems and the autonomous vehicles Discuss the remote sensing and the types of sensor Discuss the fully autonomous vehicles Apply the basic concepts of wireless communication Analyze the concept of the connected vehicle and in	mission nd Appl Fundam ogy Vehicle- conomou able to ir applic technolous	System lication nentals, to-Vehicles vehicles wireles	Autono ns – Mo s to Vo Integra cle Te icles - co collise eded to	odulation/Enchicle Autotion of Wirechnology a Driverless Total hour implement setworks	9 ncoding, Receive onomy, Basics of eless Networking 9 and Application Car Technology rs 45
Theory and Au Networks and A UNIT-IV Wireless System System Concep Computer Netw and On-Board V UNIT-V Connectivity F Vehicle-to-Road Moral, Legal, R Outcome(s)	Autonomous Vehicles, Role of Surroundings Sensing Autonomy Vehicle Wireless Technology & Networking In Block Diagram and Overview of Components, Transports—Demodulation/Decoding, Wireless Networking and Yorking—the Internet of Things, Wireless Networking of Connected Car & Autonomous Vehicle Technological Undamentals, Navigation and Other Applications, Autonomous Vehicle-to-Infrastructure Applications, Autonomous Issues, Technical Issues, Security Issues Upon completion of this course, the Learners will be Explain the cyber-physical control systems and the autonomous vehicles Discuss the remote sensing and the types of sensor Discuss the fully autonomous vehicles Apply the basic concepts of wireless communication Analyze the concept of the connected vehicle and in	mission nd Appl Fundam ogy Vehicle- conomou able to ir applic technolous ts role in	System lication nentals, to-Vehics Vehics vehicles auton to ogy need wireles in auton	Autono as – Mo s to Vo Integra cle Te icles - co collise eded to s data re nated ve	odulation/Enchicle Autotion of Wirchnology a Driverless Total hour implement setworks chicles	9 ncoding, Receive onomy, Basics of eless Networking 9 and Application Car Technology rs 45 ace and remote sensing
Theory and Au Networks and A UNIT-IV Wireless System System Concept Computer Netwand On-Board V UNIT-V Connectivity F Vehicle-to-Road Moral, Legal, R Outcome(s) TEXT BOOK I Intelligent	Vehicle Wireless Technology & Networking Block Diagram and Overview of Components, Transits—Demodulation/Decoding, Wireless Networking and orking—the Internet of Things, Wireless Networking orking—the Internet of Things, Wireless Networking of Connected Car & Autonomous Vehicle Technologundamentals, Navigation and Other Applications, Vehicle and Vehicle-to-Infrastructure Applications, Autoadblock Issues, Technical Issues, Security Issues Upon completion of this course, the Learners will be Explain the cyber-physical control systems and the autonomous vehicles Discuss the remote sensing and the types of sensor Discuss the fully autonomous vehicles Apply the basic concepts of wireless communication Analyze the concept of the connected vehicle and in the autonomous Systems and Connected and Automated	mission and Appl Fundam ogy /ehicle-tonomou able to ir applicate technologies and vita role in d Vehicle	System lication mentals, to-Vehics Vehics vehicles auton to wireles a auton es", 20	Autono as – Mo s to V Integra cle Te icles - cocollist eded to s data re nated ve	my, Role of odulation/Enehicle Autotion of Wirchnology a Driverless Total hour implement metworks whicles	9 ncoding, Receive onomy, Basics of eless Networking 9 and Application Car Technology rs 45 ace and remote sensing
Theory and Au Networks and A UNIT-IV Wireless System System Concep Computer Netw and On-Board V UNIT-V Connectivity F Vehicle-to-Road Moral, Legal, R Outcome(s) TEXT BOOK I Intelligent	Autonomous Vehicles, Role of Surroundings Sensing Autonomy Vehicle Wireless Technology & Networking In Block Diagram and Overview of Components, Transits—Demodulation/Decoding, Wireless Networking and Orking—the Internet of Things, Wireless Networking of Pehicle Networks Connected Car & Autonomous Vehicle Technological Connected Issues, Security Issues Upon completion of this course, the Learners will be Explain the cyber-physical control systems and the autonomous vehicles Discuss the remote sensing and the types of sensor Discuss the fully autonomous vehicles Apply the basic concepts of wireless communication Analyze the concept of the connected vehicle and in Transportation Systems and Connected and Automated Miucic, "Connected Vehicles: Intelligent Transportation Miucic, "Connected Vehicles: Intelligent Transportation	mission and Appl Fundam ogy /ehicle-tonomou able to ir applicate technologies and vita role in d Vehicle	System lication mentals, to-Vehics Vehics vehics wireless a auton es", 20	Autono as – Mo s to V Integra cle Te icles - cocollist eded to s data re nated ve	my, Role of odulation/Enehicle Autotion of Wirchnology a Driverless Total hour implement metworks whicles	9 ncoding, Receive onomy, Basics of eless Networking 9 and Application Car Technolog rs 45 ace and remote sensing

CO'S	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	2	2	2	-	-	-	-	-	-	2	3	2	2
CO2	2	2	2	2	2	-	-	-	-	-	-	2	2	2	2
CO3	3	2	2	1	2	-	-	-	-	-	-	2	3	2	2
CO4	2	2	2	3	3	-	-	-	-	-	-	2	2	2	2
CO5	3	3	3	3	3	-	-	-	-	-	-	2	3	2	2

Course co	ode	Course Name	Но	urs/w	eek	Credit	Maximum marks
24ME150	606	Electrical Drives and Actuators	L	T	P	С	100
241111131	000	Electrical Drives and Actuators	3	0	0	3	100
Objective(s	s)	 To study the relay and power semiconductor To understand the drive characteristics To understand the DC motors and drives. To understand the AC motors and drives. To understand the Stepper and Servo motors 		S			
UNIT-	I	Relay and Power Semi-Conductor Devices					9
		g Devices – Relay and Types, Switching chara FET and IGBT - Triggering and commutation					
UNIT-I	I	Drive Characteristics					9
	•	uations governing motor load dynamics – stea e, and Direction starting & stopping – Selection	•	•	y – mu	lti quadrant	Dynamics: acceleration
UNIT-I	II	DC Motors and Drives					9
		Types of PMDC & BLDC motors - principle o					ions - characteristics and
control – Dr	ives- H	I bridge - Single and Three Phases – 4 quadran	t operatio	л – л.		OHS	
UNIT-I	V	I bridge - Single and Three Phases – 4 quadran AC Motors and Drives luction motor drives – Speed control of 3-p					yoltage control – Stato
UNIT-I Introduction frequency copower recov UNIT-I Stepper Mo	V — Indontrol ery con V tor: Cl	AC Motors and Drives luction motor drives – Speed control of 3-p – Stator voltage and frequency control – State and Introl. Stepper And Servo Motor lassifications- Construction and Principle of	ohase inc	luction nt cont on – M	motorrol – S	- Stator tatic rotor	voltage control – Statos resistance control – Slip
UNIT-I Introduction frequency copower recov UNIT-I Stepper Mo	V — Indontrol ery con V tor: Cl	AC Motors and Drives luction motor drives – Speed control of 3-p – Stator voltage and frequency control – State of the s	ohase inc	luction nt cont on – M	motor rol – S Iodes – Appl	- Stator tatic rotor of Excitations.	voltage control – Statorresistance control – Slip 9 on- Drive System-Logic
UNIT-I Introduction frequency copower recov UNIT-I Stepper Mo	V — Indontrol ery control V tor: Cl Applic	AC Motors and Drives Juction motor drives – Speed control of 3-p – Stator voltage and frequency control – State Introl. Stepper And Servo Motor Justifications – Construction and Principle of Eations. Servo Mechanism – DC Servo motor-A Upon completion of this course, the Learners Explain the principles and working of rela Explain the working and characteristics of Apply the solid state switching circuits to Discuss the performance of Motors and Drives	Operation C Servo will be all ys, drive various operate vrives.	on – No motor ble to: s and r drives	motor rol – S fodes – Appl notors. and mo	- Stator tatic rotor of Excitations. Total house otors.	voltage control – Statorresistance control – Slip 9 on- Drive System-Logic rs 45
UNIT-I Introduction frequency co power recov UNIT-V Stepper Mo Sequencer -	V — Indontrol erry con V tor: Cl Applic	AC Motors and Drives luction motor drives – Speed control of 3-p – Stator voltage and frequency control – State introl. Stepper And Servo Motor lassifications- Construction and Principle of eations. Servo Mechanism – DC Servo motor-A Upon completion of this course, the Learners Explain the principles and working of rela Explain the working and characteristics of Apply the solid state switching circuits to Discuss the performance of Motors and Drives	Operation C Servo will be all ys, drive various operate vrives.	on – No motor ble to: s and r drives	motor rol – S fodes – Appl notors. and mo	- Stator tatic rotor of Excitations. Total house otors.	voltage control – Statoresistance control – Slip 9 on- Drive System-Logic rs 45
UNIT-I Introduction frequency co power recov UNIT-V Stepper Mo Sequencer - Outcome(s	V - Indontrol ery con V tor: Cl Applic	AC Motors and Drives Juction motor drives – Speed control of 3-p – Stator voltage and frequency control – State Introl. Stepper And Servo Motor Justifications – Construction and Principle of Eations. Servo Mechanism – DC Servo motor-A Upon completion of this course, the Learners Explain the principles and working of rela Explain the working and characteristics of Apply the solid state switching circuits to Discuss the performance of Motors and Drives	Operation Operation Operation Operation Operation Operation Operation Operate various Operation Operatio	on - Normation on the motor of the standard drives various ons.	motor rol – S fodes – Appl notors. and mo	of Excitation ications. Total houndary	voltage control – Stato resistance control – Slip 9 on- Drive System-Logic rs 45
UNIT-I Introduction frequency copower recove UNIT-V Stepper Mo Sequencer - Outcome(s TEXT BOO 1 Bi 2 M	V — Indontrol ery con V ttor: Cl Applic	AC Motors and Drives luction motor drives – Speed control of 3-p – Stator voltage and frequency control – State introl. Stepper And Servo Motor lassifications- Construction and Principle of eations. Servo Mechanism – DC Servo motor-A Upon completion of this course, the Learners • Explain the principles and working of rela • Explain the working and characteristics of • Apply the solid state switching circuits to • Discuss the performance of Motors and Drivers for given a	Operation C Servo will be all ys, drive various operate varives. application Published	on – Monotor ble to: s and r drives various ons.	motor rol – S flodes – Appl notors. and motypes types w Delh	of Excitation cations. Total house of Motors are it, 2012.	voltage control – Statoresistance control – Slip 9 on- Drive System-Logic rs 45 nd Drivers
UNIT-I Introduction frequency copower recove UNIT-V Stepper Mo Sequencer - Outcome(s TEXT BOO 1 Bi 2 M	V — Indontrol ery con V tor: Cl Applic OK: imbhra ehta V 016.	AC Motors and Drives luction motor drives – Speed control of 3-p – Stator voltage and frequency control – State introl. Stepper And Servo Motor lassifications- Construction and Principle of eations. Servo Mechanism – DC Servo motor-A Upon completion of this course, the Learners • Explain the principles and working of rela • Explain the working and characteristics of • Apply the solid state switching circuits to • Discuss the performance of Motors and Drivers for given a B.S., "Power Electronics", 5th Edition, Kanna K.K. & Rohit Mehta, "Principles of Electrical	Operation C Servo will be all ys, drive various operate varives. application Published	on – Monotor ble to: s and r drives various ons.	motor rol – S flodes – Appl notors. and motypes types w Delh	of Excitation cations. Total house of Motors are it, 2012.	voltage control – Stato resistance control – Slip 9 on- Drive System-Logic rs 45 nd Drivers
UNIT-I Introduction frequency copower recove UNIT-V Stepper Mo Sequencer - Outcome(s TEXT BO 1 Bi 2 M 20 REFEREN	V — Indontrol ery con V tor: Cl Applic OK: imbhra fehta V 016.	AC Motors and Drives luction motor drives – Speed control of 3-p – Stator voltage and frequency control – State introl. Stepper And Servo Motor lassifications- Construction and Principle of eations. Servo Mechanism – DC Servo motor-A Upon completion of this course, the Learners • Explain the principles and working of rela • Explain the working and characteristics of • Apply the solid state switching circuits to • Discuss the performance of Motors and Drivers for given a B.S., "Power Electronics", 5th Edition, Kanna K.K. & Rohit Mehta, "Principles of Electrical	Operation Concentration of Concentration	ble to: s and ridrives various ons. ers, Ne	motor rol – S flodes – Appl notors. and motypes types w Delh l Edition	of Excitation ications. Total house of Motors are it, 2012. on, S.Chande	voltage control – Statoresistance control – Slip 9 on- Drive System-Logic rs 45 add Drivers & Co. Ltd., New Delhi
UNIT-I Introduction frequency copower recove UNIT-V Stepper Mo Sequencer - Outcome(s TEXT BOO 1 Bi 2 M 20 REFEREN 1 Goo 2 Ti	V — Indontrol ery con V tor: Cl Applic OK: imbhra ehta V 16. VCES: obal K.	AC Motors and Drives Juction motor drives – Speed control of 3-p. Stator voltage and frequency control – Statementol. Stepper And Servo Motor Justina Servo Mechanism – DC Servo motor-Actions. Ser	Operation C Servo will be all ys, drive various operate various application Published Machine	on – No motor ble to: s and r drives various ons. ers, Ne s", 2nd	motor rol – S flodes (– Appl notors. and motypes (types (Belitical rosal P	of Excitation of Excitations. Total house of Motors and it, 2012. Total house of Motors and it, 2012. Total house of Motors and it, 2012. Total house of Motors and it, 2012.	voltage control – Stato resistance control – Slip 9 on- Drive System-Logic rs 45 Add Drivers & Co. Ltd., New Delhi Louse, New Delhi, 2001.

CO'S	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	2	1	2	-	-	-	1	-	-	2	3	2	2
CO2	3	2	2	1	2	-	-	-	1	-	-	2	3	2	2
CO3	3	2	3	2	2	-	-	-	1	-	-	2	3	3	2
CO4	3	3	2	2	2	-	-	-	2	-	-	2	3	3	2
CO5	3	3	2	2	2	-	-	-	2	-	-	2	3	3	2